

ELETTROTECNICA

[Fotocopie di Appunti]

A CURA DI ALESSANDRO PAGHI

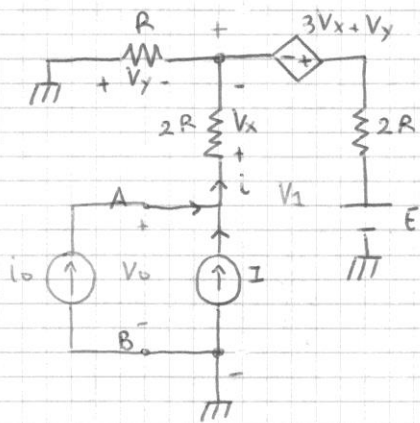
PROFESSORE: Mauro Forti (<http://www3.diism.unisi.it/people/person.php?id=7>)

LINK AL CORSO:

<http://www3.diism.unisi.it/FAC/index.php?bodyinc=didattica/inc.insegnamento.php&id=55109&aa=2015>

FREQUENTAZIONE: Consigliata.

PARTE 1



? TR metodo rapido

$$i = i_0 + I$$

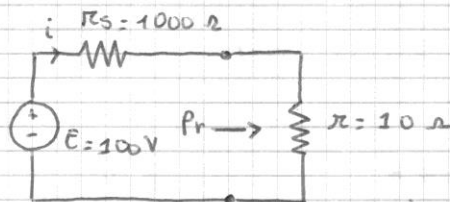
$$V_x = 2R \cdot i$$

$$V_y = V_x - V_0 = 2Ri - V_0$$

$$\text{MILLMANN: } V_1 = \frac{i_0 + I + \frac{E - 3V_x - V_y}{2R}}{\frac{1}{R} + \frac{1}{2R}} = \frac{2Ri_0 + 2RI + E - 3V_x - V_y}{3}$$

$$V_0 = 2R(i_0 + I) + V_1 \quad \leftarrow \quad V_1 = V_0 - V_x$$

Trasformatore Adattatore di Resistenza



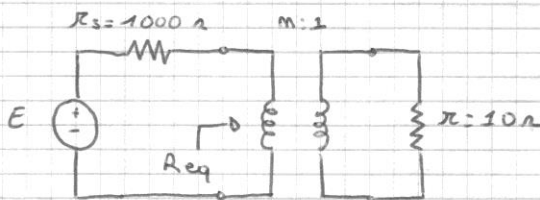
$$r = r_s = 1000 \Omega$$

$$P_{MAX} = \frac{1}{4} \frac{E^2}{r_s} = 2,5 \text{ Watt}$$

$$i = \frac{100}{1010} \approx 0,1 \text{ A}$$

$$P_r = 10 \cdot i^2 = 10 \cdot 0,1^2 = 0,1 \text{ Watt}$$

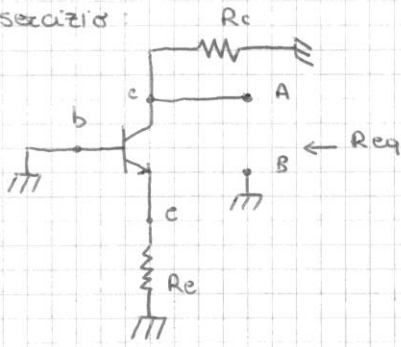
Butto fuori troppa poca potenza!



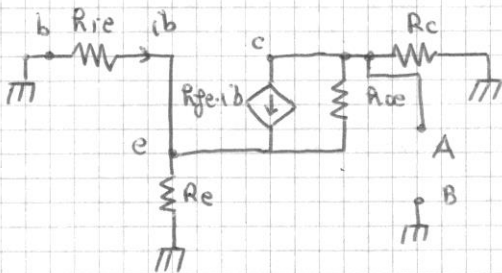
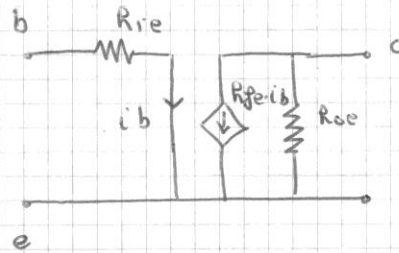
$$r_s = R_{eq} = m^2 r \quad \rightarrow \quad m = \sqrt{\frac{r_s}{r}} = 10$$

$$P_r = 2,5 \text{ Watt} = P_{MAX}$$

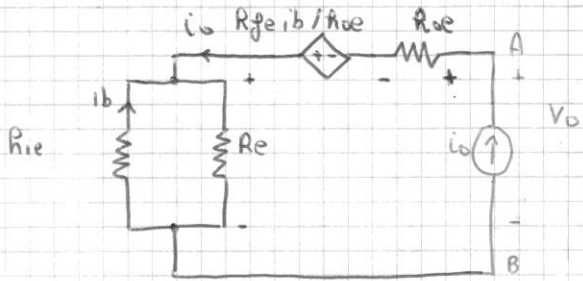
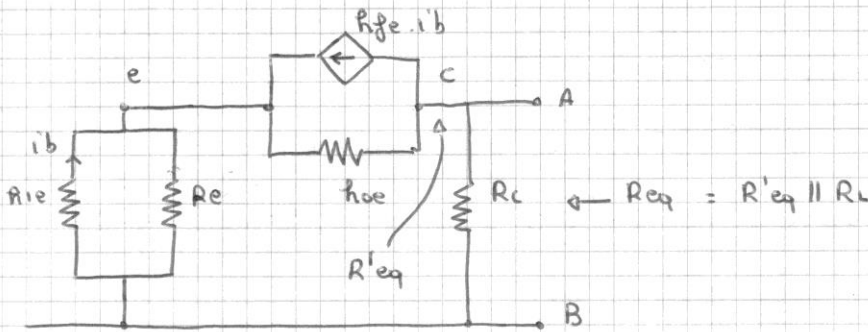
Esercizio:



? Req utilizzando per il BJT le modello a parametri h con $R_{ce} = \beta$



R_{ce} conduttanza



$$i_b = -i_o \cdot \frac{\frac{1}{R_{ie}}}{\frac{1}{R_{ie}} + \frac{1}{R_e}} = -i_o \cdot \frac{R_e}{R_{ie} + R_e}$$

$$V_o = i_o \cdot \frac{1}{R_{ce}} - \frac{R_{fe}}{R_{ce}} \cdot i_b + (R_{ce} \parallel R_L) \cdot i_o = \frac{i_o}{R_{ce}} \rightarrow \frac{R_{fe}}{R_{ce}} \cdot i_o \cdot \frac{R_e}{R_{ie} + R_e} \rightarrow \frac{R_{fe} R_e i_o}{R_{ie} + R_e}$$

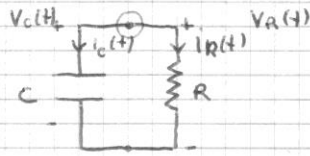
$$R'_{eq} = \frac{V_o}{i_o} = \frac{1}{R_{ce}} + \frac{R_{fe}}{R_{ce}} \cdot \frac{R_e}{R_{ie} + R_e} + \frac{R_e \cdot R_{ie}}{R_{ie} + R_e}$$

$$R_{eq} = R'_{eq} \parallel R_L$$

24/04/2015

Circuiti del Primo Ordine, analizzati nel Dominio del Tempo.

Scarica di C su R



C inizialmente carico

$$V_c(\phi) = V_0$$

$V_c(t)$ variabile di Stato

$$i_c(t) + i_r(t) = 0$$

$$C \cdot \frac{dV_c(t)}{dt} + \frac{V_R(t)}{R} = 0, \quad t \geq \phi$$

$$V_R(t) = V_c(t)$$

$$\begin{cases} \tau \cdot \frac{dV_c(t)}{dt} + V_c(t) = 0 \\ V_c(\phi) = V_0 \end{cases}$$

$$\tau = \tau_{RC} = RC$$

Costante di tempo circuito

RC 1° ordine

$$[\tau] = \text{sec}$$

↑
Eq. differenziale 1° ordine omogenea.

Problema di Cauchy → Unica Soluzione

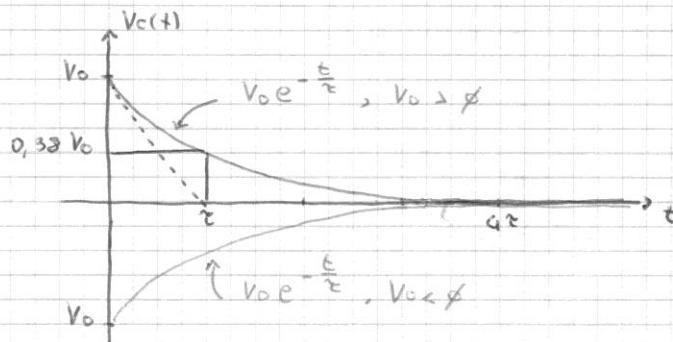
$$\tau p + 1 = 0, \quad p = -\frac{1}{\tau} = -\frac{1}{RC} \quad \text{Radice Caratteristica}$$

$$V_c(t) = K e^{pt} = K e^{-\frac{t}{\tau}} = K e^{-\frac{t}{RC}}, \quad t \geq \phi$$

$K \in \mathbb{R}$

$$V_c(\phi) = K = V_0$$

$$V_c(t) = V_0 \cdot e^{-\frac{t}{\tau}} = V_c(\phi) \cdot e^{-\frac{t}{\tau}}, \quad t \geq \phi \quad \leftarrow \text{Scarica di C su R.}$$



Risposta LIBERA,
NATURALE, a
INGRESSO NULLO

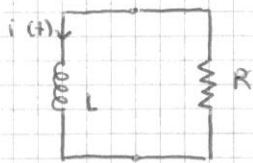
$$p = -\frac{1}{RC} = -\frac{1}{\tau}$$

↑
Frequenza naturale

$$\text{Dopo } 4 \div 5 \tau \rightarrow V_c(t) = 0,02 V_0$$

Durata Transitoria di Scarica, $4 \div 5 \tau$

Scarica di L su R



Voci serie di stato $i(t)$

$$? i(t), t \geq 0$$

$$i(0) = I_0$$

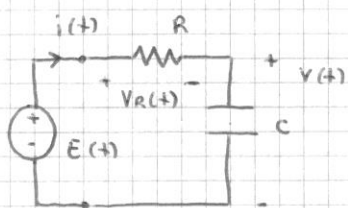
$$\tau = \frac{L}{R}$$

$$\tau \frac{d}{dt} i(t) + i(t) = 0$$

$$i(0) = I_0$$

Fimixe per casa!

Risposta Forzata ($v(t)$, qualsiasi $v(0) = \neq$)



Risposta allo stato nuovo

$$v_R(t) + v_C(t) = E(t), t \geq 0$$

$$R \cdot i(t) + v(t) = E(t)$$

$$R \cdot C \frac{d}{dt} v(t) + v(t) = E(t)$$

$$\tau \frac{d}{dt} v(t) + v(t) = E(t), t \geq 0$$

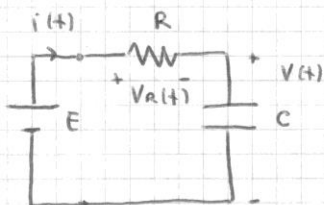
$$v(0) = \neq$$

$$v(t) = V_{\text{omog}}(t) + V_{\text{part. affime}}(t) = K e^{-\frac{t}{\tau}} + V_{\text{part. affime}}(t)$$

$$V_{\text{part. affime}} = \int_{\neq}^t e^{-\frac{t-\sigma}{\tau}} \cdot E(\sigma) d\sigma$$

$V_{\text{part. affime}}$ \rightarrow Eccitazioni Costanti

\rightarrow Eccitazioni Sinusoidali



$$\tau \frac{d}{dt} v + v = E = \text{cost.}, t \geq 0$$

$$v(0) = \neq$$

Eccitazione costante \rightarrow integrale Particolare Costante

(deve 'stessa forma' dell'eccitazione)

$$V_{\text{part}}(t) = H$$

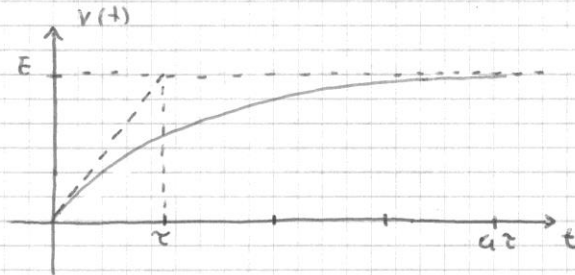
$$H = E, \quad t \geq \phi$$

$$v(t) = K \cdot e^{-\frac{t}{\tau}} + E, \quad t \geq \phi$$

$$v(\phi) = \phi = K + E \quad \rightarrow \quad K = -E$$

$$v(t) = -E \cdot e^{-\frac{t}{\tau}} + E = E(1 - e^{-\frac{t}{\tau}}), \quad t \geq \phi$$

↑ Carica di C inizialmente scarica con Batteria



$$\text{dopo } 4\tau \rightarrow v(t) = E - 0,02 E \approx E$$

Interpretazione Risposta Forzata

$$v(t) = -E e^{-\frac{t}{\tau}} + E, \quad t \geq \phi$$

↙ Parte Transitoria

↘ Risposta in Regime Stazionario

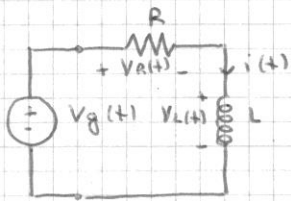
$$\text{Dopo } 4\tau \rightarrow \phi$$

$$F = T + \text{Regime Stazionario}$$

Risposta in Regime Stazionario:

- Int. part. oppure;
- Cui che resta per $t \rightarrow +\infty$
- Deco stessa Forma dell' Eccitazione;

Circuito RL con Eccitazione Sinusoidale



$i(t)$, Risposta Forzata

$i(\phi) = \phi$: Stato Misto

$$V_M \cos(\omega t) = V_R(t) + V_L(t), \quad t \geq \phi$$

$$L \cdot \frac{d}{dt} i(t) + R i(t) = V_M \cos(\omega t), \quad t \geq \phi$$

$$V_g(t) = V_M \cos(\omega t)$$

$$i(t) = i_{\text{trans}}(t) + i_{\text{regime}}(t) = K \cdot e^{-\frac{t}{\tau}} + I_M \cos(\omega t + \phi_i)$$

F = T + Regime Sinusoidale

$$i(t) = i_{\text{trans}}(t) + i_{\text{regime}}(t)$$

$$i_{\text{regime}}(t) = \frac{V_M}{\sqrt{R^2 + \omega^2 L^2}} \cos(\omega t - \arctan \frac{\omega L}{R})$$

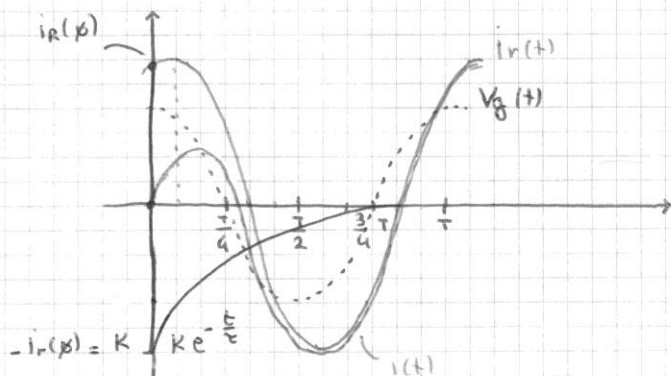
$$\uparrow$$

$$\frac{V_M}{Z} \cos(\omega t + \phi_v - \phi_z)$$

$$i(t) = K e^{-\frac{t}{\tau}} + \frac{V_M}{\sqrt{R^2 + \omega^2 L^2}} \cos(\omega t - \arctan \frac{\omega L}{R})$$

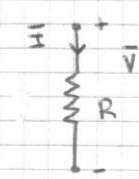
$$i(\phi) = \phi = K + \frac{V_M}{\sqrt{R^2 + \omega^2 L^2}} \cos(\arctan \frac{\omega L}{R})$$

$$i(t) = \underbrace{-\frac{V_M}{\sqrt{R^2 + \omega^2 L^2}} \cos(\arctan \frac{\omega L}{R}) e^{-\frac{t}{\tau}}}_{i_T(t)} + \underbrace{\frac{V_M}{\sqrt{R^2 + \omega^2 L^2}} \cos(\omega t - \arctan \frac{\omega L}{R})}_{i_R(t)}$$

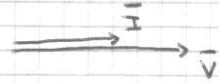


Con $t \rightarrow +\infty$: $i(t) = i_R(t)$, inizialmente $i(t) \neq i_R(t)$.

Espressione di P, Q per i tipi ideali R, L, C .

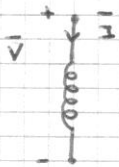


$$\bar{V} = R \bar{I}$$



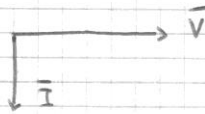
$$\bar{P} = \frac{1}{2} \bar{V} \bar{I}^* = \frac{1}{2} R \bar{I} \cdot \bar{I}^* = \frac{1}{2} R I_H^2 + j\phi$$

$$\left\{ \begin{array}{l} P_R = \frac{1}{2} R I_H^2 = \frac{1}{2} \frac{V_H^2}{R} \\ \quad = R I^2 = \frac{V^2}{R} \text{ Watt} \geq \phi \\ Q_R = \phi \text{ VAR} \end{array} \right.$$

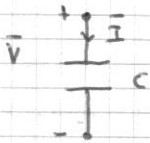


$$\begin{aligned} \bar{V} &= j\omega L \cdot \bar{I} \\ &= jX_L \cdot \bar{I} \end{aligned}$$

$$\bar{P} = \frac{1}{2} \bar{V} \bar{I}^* = \frac{1}{2} j\omega L \cdot \bar{I} \cdot \bar{I}^* = j \frac{1}{2} \omega L I_H^2$$



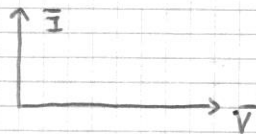
$$\left\{ \begin{array}{l} P_L = \phi \text{ Watt} \\ Q_L = \frac{1}{2} X_L I_H^2 = \frac{1}{2} \frac{V_H^2}{X_L} \\ \quad = X_L I^2 = \frac{V^2}{X_L} \text{ VAR} \end{array} \right.$$



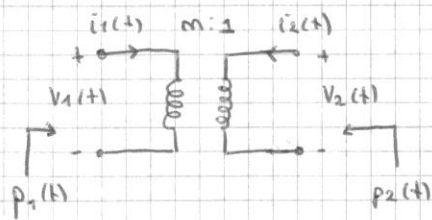
$$\begin{aligned} \bar{I} &= j\omega C \bar{V} \\ &= j \frac{\bar{V}}{X_C} \end{aligned}$$

$$\begin{aligned} \bar{P} &= \frac{1}{2} \bar{V} \cdot \bar{I}^* = \frac{1}{2} \bar{V} (j\omega C \bar{V})^* = \frac{1}{2} \bar{V} \omega C (-j) \bar{V}^* \\ &= \phi - j \frac{1}{2} \omega C V_H^2 \end{aligned}$$

$$\left\{ \begin{array}{l} P_C = \phi \text{ Watt} \\ Q_C = -\frac{1}{2} \omega C V_H^2 = -\frac{1}{2} \frac{V_H^2}{X_C} = -\frac{1}{2} X_C I_H^2 \\ \quad = -\frac{V^2}{X_C} = -X_C I^2 \text{ VAR} \end{array} \right.$$

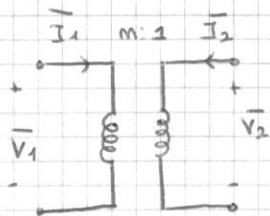


Trasformatore Ideale



$$\begin{cases} v_1(t) = m v_2(t) \\ i_1(t) = -\frac{1}{m} i_2(t) \end{cases}$$

$$\begin{aligned} p_1(t) + p_2(t) &= \\ &= v_1(t) i_1(t) + v_2(t) i_2(t) \\ &= 0 \end{aligned}$$



$$\begin{cases} \bar{V}_1 = m \bar{V}_2 \\ \bar{I}_1 = -\frac{1}{m} \bar{I}_2 \end{cases}$$

$$\bar{P} = \bar{P}_1 + \bar{P}_2 = \frac{1}{2} \bar{V}_1 \bar{I}_1^* + \frac{1}{2} \bar{V}_2 \bar{I}_2^* = \frac{1}{2} m \bar{V}_2 \left(-\frac{1}{m}\right) \bar{I}_2^* + \frac{1}{2} \bar{V}_2 \bar{I}_2^* = 0$$

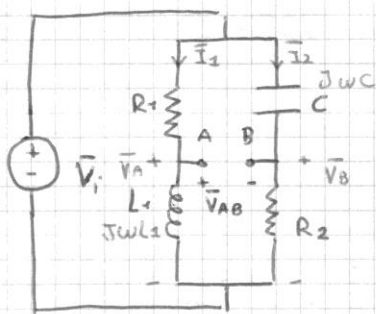
$$\bar{P} = (P_1 + P_2) + j(Q_1 + Q_2) = 0$$

$$\begin{cases} P_1 + P_2 = 0 & \text{è Trasparente a Potenza attiva} \\ Q_1 + Q_2 = 0 & \text{e Reattiva.} \end{cases}$$

Giratore Ideale (Per Caso)

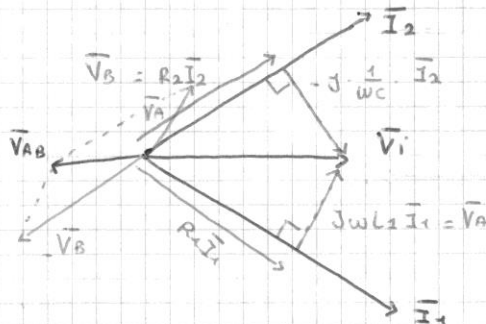
Trasparente a P ma non a Q.

Esercizio



Verificare con metodo grafico del Fasore che se il ponte è bilanciato ($V_{AB} = 0$) se e solo se: i rami in parallelo hanno stessa costante di tempo:

$$\tau_{LR} = \frac{L_1}{R_1} = R_2 C = \tau_{RC}$$

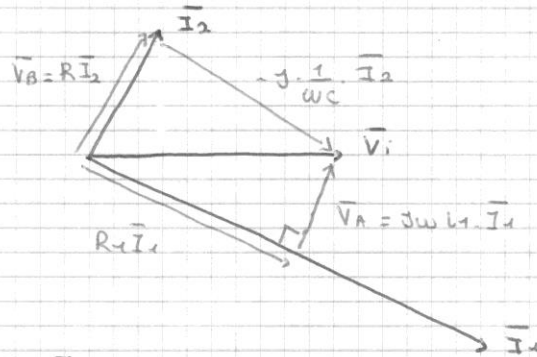


$$\begin{aligned} \bar{V}_{AB} &= \bar{V}_A - \bar{V}_B \\ &= j\omega L_1 \bar{I}_1 - R_2 \bar{I}_2 \end{aligned}$$

R_1, L_1, C fissi. Variò R_2

Bisogna che $\bar{V}_A \parallel \bar{V}_B$.

Alorsò il valore di R_2



$$\bar{V}_A = \bar{V}_B$$

$$\bar{V}_A - \bar{V}_B = \bar{V}_{AB} = \phi$$

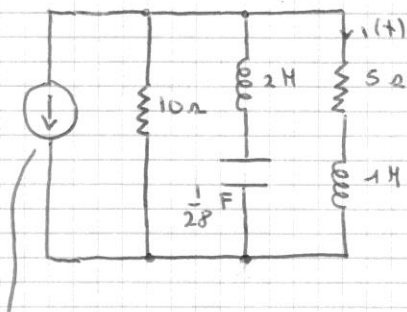
Fonte di corrente

$$\begin{cases} R_2 I_{2H} = \omega L_1 I_{1H} \\ \frac{1}{\omega C} I_{2H} = R_1 I_{1H} \end{cases}$$

$$\frac{I_{2H}}{I_{1H}} = \frac{\omega L_1}{R_2} = R_1 \omega C \rightarrow \frac{L_1}{R_1} = C R_2 \leftarrow \text{Le costanti di Tempo sono uguali}$$

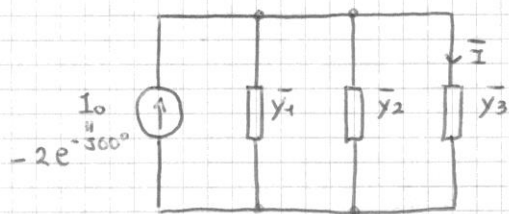
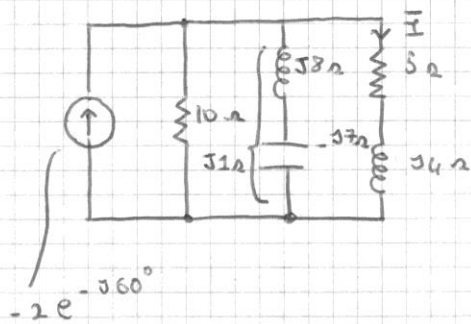
Ho dimostrato!

Esercizio



$$2 \cos(4t - 60^\circ) \text{ Amp.}$$

? $i(t)$ in regime sinusoidale
 \rightarrow metodo Fasori.



$$\bar{y}_1 = \frac{1}{10} \Omega^{-1}$$

$$\bar{y}_2 = -j \Omega^{-1}$$

$$\bar{y}_3 = \frac{1}{5+j4} \Omega^{-1}$$

$$\bar{I} = \bar{I}_0 \cdot \frac{\bar{y}_3}{\bar{y}_1 + \bar{y}_2 + \bar{y}_3} = -2e^{-j60^\circ} \cdot \frac{\frac{1}{5+j4}}{\frac{1}{10} - j + \frac{1}{5+j4}}$$

$$= -2e^{-j60^\circ} \cdot \frac{1}{1 + \frac{5+j4}{10} - j(5+j4)} = -20e^{-j60^\circ} \cdot \frac{1}{55 - j46}$$

$$= \frac{20}{\sqrt{55^2 + 46^2}} e^{j180^\circ} e^{-j60^\circ} e^{j \arctan\left(\frac{46}{55}\right) \approx 40^\circ}$$

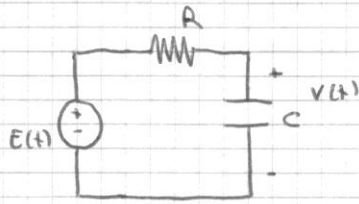
$$= 0,279 \cdot e^{+160^\circ} \text{ Amp.}$$

↓
 I_H

$$i(t) = 0,279 \cos(4t + 160^\circ) \text{ Amp.}$$

29/04/2015

Risposta Completa



$$v(\phi) = V_0 \neq \phi$$

$$\frac{1}{2} C V_0^2 \text{ Joule}$$

$C = L + F$ ← (Principio di Sovrapposizione degli Effetti).
 ↑ Libera ↑ Forzata
 Completa

↓
 DIMOSTRAZIONE:

$$\begin{cases} \tau \frac{d}{dt} V_{COM} + V_{COM} = E(t) \\ V_{COM}(\phi) = \phi \end{cases}$$

$$\begin{cases} \tau \frac{d}{dt} V_{LIB} + V_{LIB} = \phi \\ V_{LIB}(\phi) = V_0 \end{cases}$$

$$\begin{cases} \tau \frac{d}{dt} (V_{LIB} + V_{FOR}) + (V_{LIB} + V_{FOR}) = E(t) \\ (V_{LIB} + V_{FOR})(\phi) = V_0 \end{cases}$$

$$\begin{cases} \tau \frac{d}{dt} V_{FOR} + V_{FOR} = E(t) \\ V_{FOR}(\phi) = \phi \end{cases}$$

$$E(t) = E = \text{costante}$$

$$C = L + F =$$

$$V_{COM}(t) = V_0 \cdot e^{-\frac{t}{\tau}} + E(1 - e^{-\frac{t}{\tau}})$$

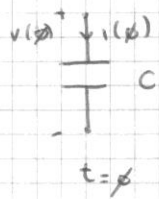
Scomposizione in Parti Significative

$$C = L + F = L + T + \text{Regime}$$

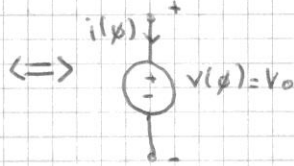
$$L + T = \text{Transitorio Completo}$$

$$C = TC + \text{Regime}$$

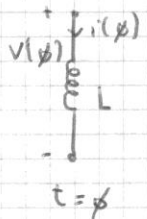
Comportamento a $t = \phi$ degli elementi reattivi L e C .



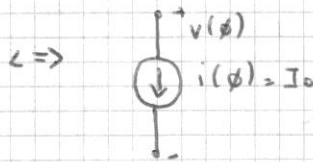
$v(\phi) = V_0$ $\forall i(\phi)$ conosciuto da variabile di stato.



$v(\phi) = \phi$
 $\forall i(\phi)$ \Leftrightarrow c.c.



$i(\phi) = I_0$ $\forall v(\phi)$ conosciuto da variabile di stato



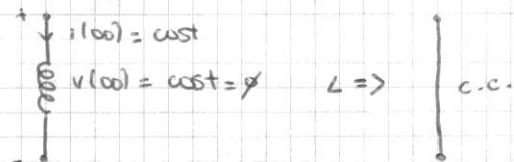
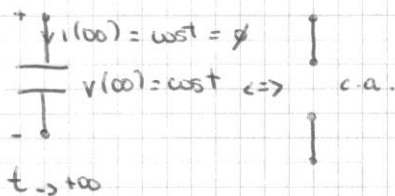
$i(\phi) = \phi$
 $\forall v(\phi)$ \Leftrightarrow c.a.

Comportamento per $t \rightarrow +\infty$

1) Circuito in Regime stazionario per $t \rightarrow +\infty$.

Generatori di v e i costanti

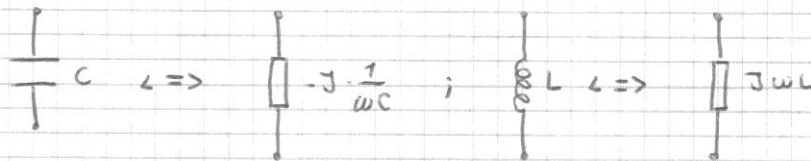
Tutte le v e le i del circuito sono costanti per $t \rightarrow +\infty$.



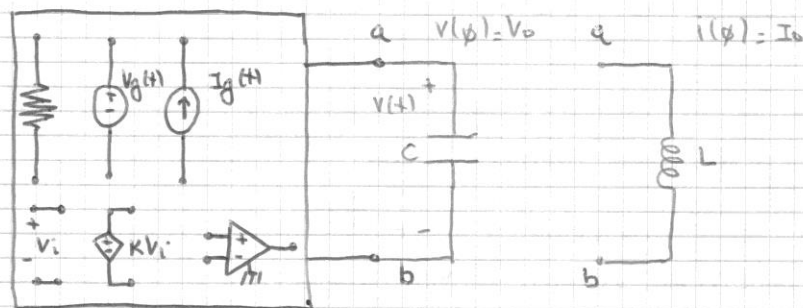
2) Esempio in Regime Sinusoidale per $t \rightarrow \infty$

Generatori di v e i sinusoidali

Tutte le v e i sono sinusoidali per $t \rightarrow +\infty$.

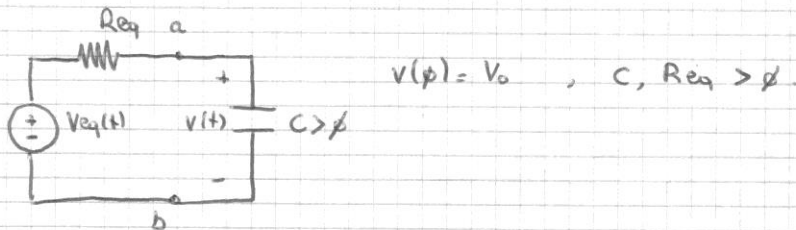


Circuiti del 1° Ordine



Rete senza memoria non omog.

Bipolo ab conbr. in corrente



$$\begin{cases} R_{eq} \frac{d}{dt} v + v = V_{eq}(t) & , t \geq \phi \\ v(\phi) = V_0 \end{cases}$$

$$\tau_{eq} = C \cdot R_{eq}$$

$$C: V_0 \neq \phi, V_{eq}(t) \neq \phi$$

$$F: V_0 = \phi, V_{eq}(t) \neq \phi$$

$$L: V_0 \neq \phi; V_{eq}(t) = \phi$$

Eccitazioni unipolari ad esplosi Costanti
 $V_g(t)$, $I_g(t)$ costanti (in continua)

$$V_{eq}(t) = V_{c.a.}(t) = V_{eq} = \text{Costante}$$

$$\begin{cases} \tau_{eq} \cdot \frac{d}{dt} v + v = V_{eq} = \text{costante} \\ v(\phi) = V_0 \end{cases}$$

$$C: v(t) = V_0 e^{-\frac{t}{\tau_{eq}}} + V_{eq} \cdot (1 - e^{-\frac{t}{\tau_{eq}}}), t \geq \phi$$

$$F: v(t) = V_{eq} (1 - e^{-\frac{t}{\tau_{eq}}}), t \geq \phi$$

$$L: v(t) = V_0 \cdot e^{-\frac{t}{\tau_{eq}}}, t \geq \phi$$

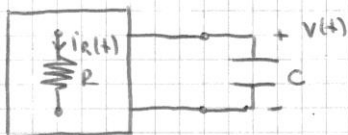
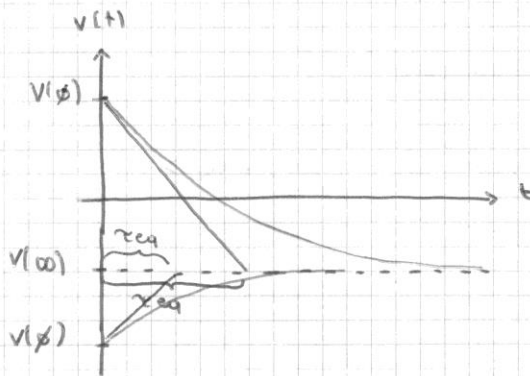
$$V_0 = v(\phi)$$

$$V_{eq} = V(\infty) \text{ Regime Stazionario}$$

$$v(t) = v(\phi) \cdot e^{-\frac{t}{\tau_{eq}}} + V(\infty) \cdot (1 - e^{-\frac{t}{\tau_{eq}}}), t \geq \phi$$

$$= V(\infty) + [v(\phi) - V(\infty)] \cdot e^{-\frac{t}{\tau_{eq}}}, t \geq \phi$$

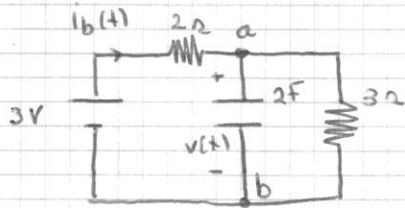
Per circuiti del primo ordine con eccitazioni costanti.



$$i_R(t) = i_R(\phi) e^{-\frac{t}{\tau_{eq}}} + i_R(\infty) (1 - e^{-\frac{t}{\tau_{eq}}})$$

τ_{eq} è sempre la stessa!

Esercizio:



$$v(\phi) = 4V$$

? $i_b(t)$, $t \geq \phi$, Resp. Completa.

$i_b(t)$ ma var. di Stato

1. Trovo $v(t)$ (var. di stato) e poi $i_b(t)$:

$$i_b(t) = \frac{3 - v(t)}{2}$$



$$\tau_{eq} = C \cdot R_{eq} = \frac{12}{5} \text{ sec}$$

$$v_{WH}(t) = 4 \cdot e^{-\frac{5}{12}t} + \frac{9}{5} (1 - e^{-\frac{5}{12}t}), \quad t \geq \phi$$

$$i_b(t) = \frac{3 - v(t)}{2} = \dots = \frac{2}{5} - \frac{11}{10} \cdot e^{-\frac{5}{12}t}$$

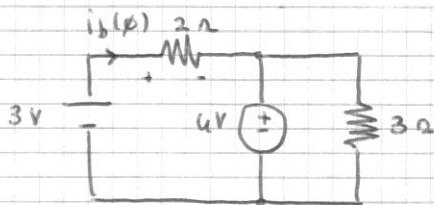
2. Trovo dualmente $i_b(t)$.

$$i_b(t) = i_b(\phi) \cdot e^{-\frac{t}{\tau_{eq}}} + i_b(\infty) (1 - e^{-\frac{t}{\tau_{eq}}})$$

Istantanea a $t = \phi$

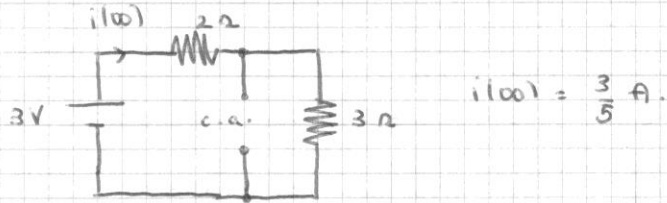
Regime stazionario $t \rightarrow \infty$

$t = \phi$



$$i_b(\phi) = -\frac{1}{2} A$$

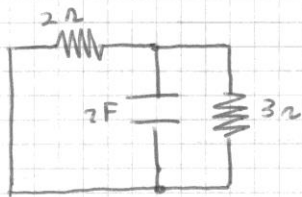
$t \rightarrow \infty$



Determinazione di τ_{eq} .

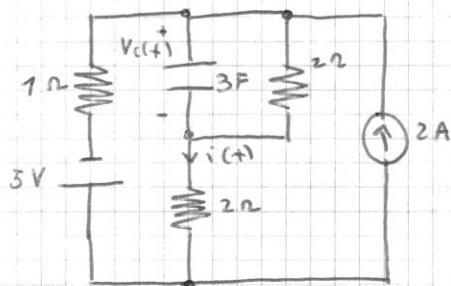
$K \cdot e^{-\frac{t}{\tau_{eq}}} \rightarrow$ sol. omogenea

Evoluzione libera \rightarrow Generatori Spenti



$$\tau = C \cdot R_{eq} = 2 \cdot \frac{6}{5} = \frac{12}{5} \text{ sec.}$$

Esercizio Per casa :



$$V_c(\phi) = 2 \text{ V}$$

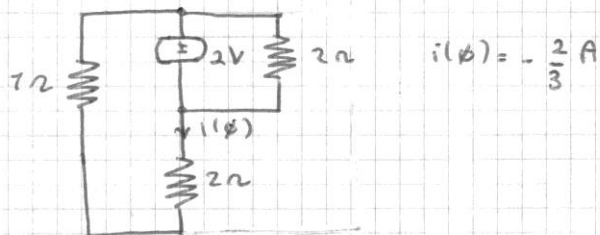
$$i(\phi), t \geq \phi$$

L, F, T, Regime Stazionario

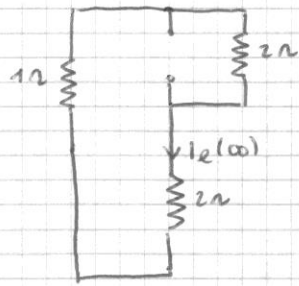
Circuito 1° Ordine con eccitazioni costanti

L:

$$i_2(t) = i_2(\phi) \cdot e^{-\frac{t}{\tau_{eq}}} + i_2(\infty) (1 - e^{-\frac{t}{\tau_{eq}}})$$



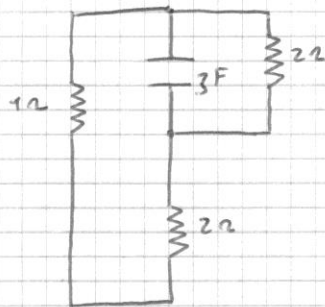
$t = \phi$



$$i_e(\infty) = \phi \text{ A.}$$

$t \rightarrow \infty$

τ_{eq} :



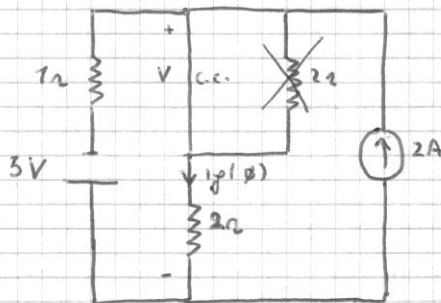
$$\tau_{eq} = C \cdot R_{eq} = \frac{18}{5} \text{ Sec.}$$

$$i_e(t) = -\frac{2}{3} \cdot e^{-\frac{5}{18}t}, \quad t \geq \phi.$$

F:

$$i_f(t) = i_f(\phi) \cdot e^{-\frac{t}{\tau_{eq}}} + i_f(\infty) \left(1 - e^{-\frac{t}{\tau_{eq}}}\right).$$

$t = \phi$

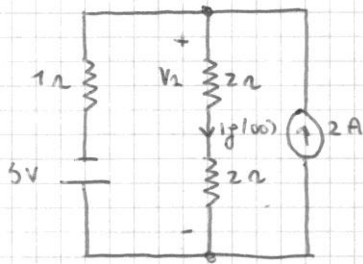


HILLMANN

$$V = \frac{-5 + 2}{1 + \frac{1}{2}} = -2 \text{ V}$$

$$i_f(\phi) = \frac{V}{2} = -1 \text{ A.}$$

$t \rightarrow \infty$



MILLMANN :

$$V_2 = \frac{-5 + 2}{1 + \frac{1}{4}} = -\frac{12}{5} \text{ V}$$

$$i_g(\infty) = \frac{V_2}{4} = -\frac{3}{5} \text{ A}$$

$$i_g(t) = -e^{-5/18 t} - \frac{3}{5} (1 - e^{-5/18 t})$$

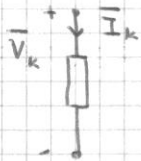
$$F = T + R$$

$$i_g(t) = -\frac{3}{5} - \frac{1}{5} e^{-5/18 t}$$

$$R = -\frac{3}{5}, \quad T = -\frac{2}{5} e^{-5/18 t}$$

Teorema di Boucherot

Rete di ℓ bipoli in regime sinusoidale a pulsazione ω .



Per una rete di ℓ bipoli in regime sinusoidale a pulsazione ω , è nulla la somma (vettoriale) delle potenze complesse assorbite dai bipoli:

$$\sum_{k=1}^{\ell} \frac{1}{2} \bar{V}_k \bar{I}_k^* = \sum_{k=1}^{\ell} \bar{P}_k = \emptyset$$

$$\sum_{k=1}^{\ell} (P_k + jQ_k) = \sum_{k=1}^{\ell} P_k + j \sum_{k=1}^{\ell} Q_k = \emptyset$$

$$\left\{ \begin{array}{l} \sum_{k=1}^{\ell} P_k = \emptyset \text{ Watt} \\ \sum_{k=1}^{\ell} Q_k = \emptyset \text{ VAR} \end{array} \right.$$

Valere il principio di conservazione per potenza complessa attiva e reattiva.

Rete R, L, C e generatori indipendenti di tensione e corrente

$$\sum_{\text{generatori}} P_{gi} = \sum_{\text{resistori}} P_{Ri} = \sum_{\text{resistori}} R_i I_i^2 \text{ Watt.}$$

↑
Potenza attiva erogata dai gen. e l-esimo.

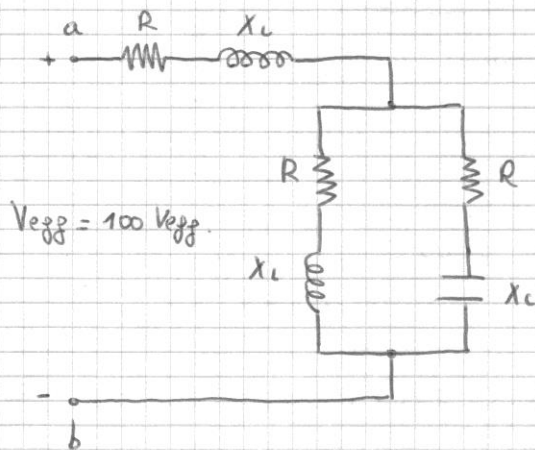
$$\sum_{\text{generatori}} Q_{gi} = \sum_{\text{induttori}} Q_{Li} + \sum_{\text{condensatori}} Q_{Ci}$$

↑
Potenza reattiva erogata dai gen. e l-esimo.

$$= \sum_{\text{induttori}} \omega L_i I_i^2 + \sum_{\text{condensatori}} (-\omega C_i V_i^2)$$

$$= 2 \omega \left[\sum_{\text{induttori}} E_{Li}^{\text{medio}} - \sum_{\text{condensatori}} E_{Ci}^{\text{medio}} \right] \text{ VAR}$$

Applicazione Teorema di Boucherot



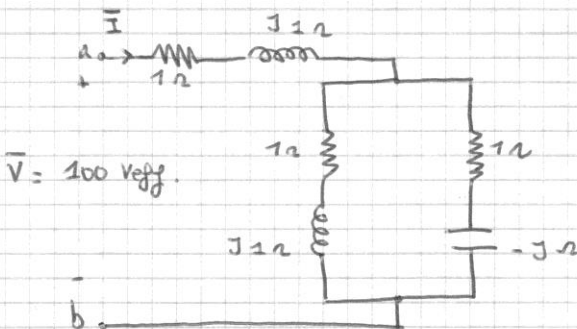
$$R = X_L = X_C = 1 \Omega$$

? P, Q assorbita da ab e verificata T. di Boucherot.

$$\bar{V} = V_{eff} e^{j4r} \text{ Volt}$$

$$\bar{V} = V_{eff} e^{j4r} V_{eff}$$

$$\bar{I} = I_{eff} e^{j4i} A_{eff}$$



da potenza assorbita e indipendente dalla Fase di \bar{V} .

$$\bar{P} = \bar{V} \bar{I}^*$$

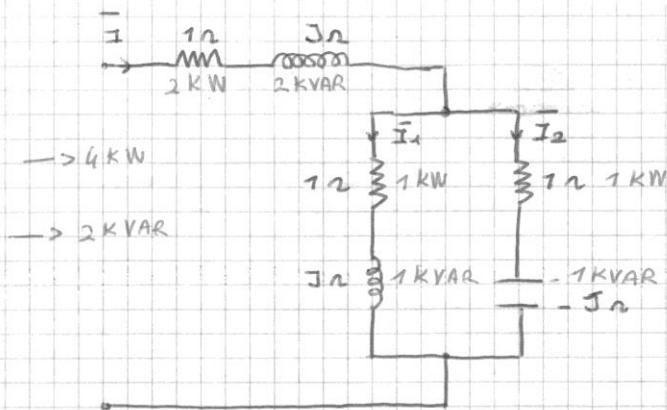
$$\bar{Z} = 1 + j + \frac{1}{\frac{1}{1+j} + \frac{1}{1-j}} = 1 + j + \frac{(1+j)(1-j)}{1+j+1-j} = 1 + j + \frac{2}{2} = 2 + j \Omega$$

$$\bar{I} = \frac{\bar{V}}{\bar{Z}} = \frac{100}{2+j} = \frac{100(2-j)}{5} = 40 - j20 \text{ Aeff.} \quad I^2 = 2000 \text{ Aeff}^2$$

$$\bar{P} = 100 \cdot (40 + j20) = 4000 + j2000 \text{ VA.}$$

$$P = 4 \text{ kW.}$$

$$Q = 2 \text{ kVAR.}$$



$$P_R = R \cdot I_{\text{eff}}^2$$

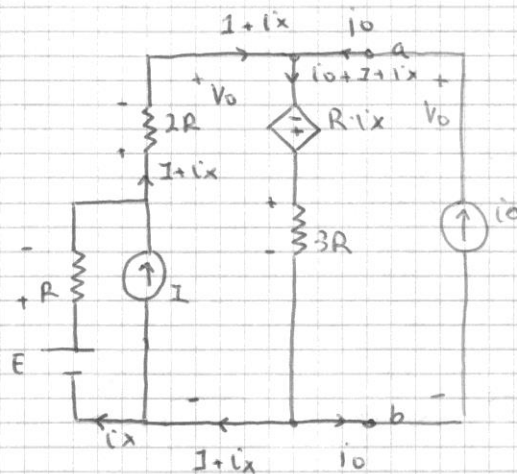
$$\bar{I}_1 = \bar{I} \cdot \frac{\frac{1}{1+j}}{\frac{1}{1+j} + \frac{1}{1-j}} = (40 - j20) \cdot \frac{1-j}{1+j+1-j}$$

$$= (40 - j20) \cdot \frac{1-j}{2} = (20 - j10)(1-j) = 10 - j30 \text{ Aeff}$$

$$\bar{I}_2 = \bar{I} - \bar{I}_1 = 30 + j10 \text{ Aeff.}$$

$$I_1^2 = I_2^2 = 1000 \text{ Aeff}^2$$

Esercizi Parte 1.



? TR con metodo rapido

$$V_0 = -2R(i_x + I) - R \cdot i_x + E = -3R i_x - 2RI + E$$

$$i_x = \frac{E - 2RI - V_0}{3R}$$

$$V_0 = 3R(i_0 + I + i_x) - R \cdot i_x$$

$$= 3R(i_0 + I + \frac{E - 2RI - V_0}{3R}) - R \cdot \frac{E - 2RI - V_0}{3R}$$

$$= 3R i_0 + 3RI + E - 2RI - V_0 - \frac{E}{3} + \frac{2}{3}RI + \frac{V_0}{3}$$

$$= 3R i_0 + \frac{5}{3}RI + \frac{2}{3}E - \frac{2}{3}V_0$$

$$\frac{5}{3}V_0 = 3R i_0 + \frac{5}{3}RI + \frac{2}{3}E$$

$$V_0 = \frac{9}{5}R i_0 + RI + \frac{2}{5}E$$

$$R_{eq} = \frac{9}{5}R \quad ; \quad V_{eq} = RI + \frac{2}{5}E$$

06/05/2015

C ideale oppure L ideale

$i_c(t)$ limitata in $[t_a, t_b]$

$\rightarrow v_c(t)$ è continua in (t_a, t_b)

$v_c(t)$ limitata in $[t_a, t_b]$

$\rightarrow i_c(t)$ è continua in (t_a, t_b)

Ditt:

$t_0 \in (t_a, t_b)$

$v_c(t_0^+) \neq v_c(t_0^-)$

$$|v_c(t_0 + \varepsilon) - v_c(t_0 - \varepsilon)| = \left| \frac{1}{C} \int_{t_0 - \varepsilon}^{t_0 + \varepsilon} i_c(t) dt \right| \leq \frac{1}{C} \int_{t_0 - \varepsilon}^{t_0 + \varepsilon} |i_c(t)| dt \leq M \cdot 2\varepsilon + \infty$$

$$\frac{1}{C} \int_{t_0 - \varepsilon}^{t_0 + \varepsilon} |i_c(t)| dt \leq \frac{1}{C} \cdot M \cdot 2\varepsilon$$

$$\lim_{\varepsilon \rightarrow 0} \frac{1}{C} \cdot M \cdot 2\varepsilon = 0 \quad \text{ovvero } v_c(t_0^+) = v_c(t_0^-)$$

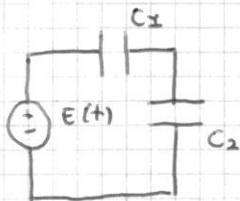
Assurdo!

Quindi se $i_c(t)$ è limitata $\rightarrow v_c(t)$ è continua!

Evento critico: (Chiusura o Apertura di un interruttore oppure discontinuità della V o I impressa da un generatore indipendente.

Istante critico: Istante in cui avviene l'evento critico.
($t = t_c$)

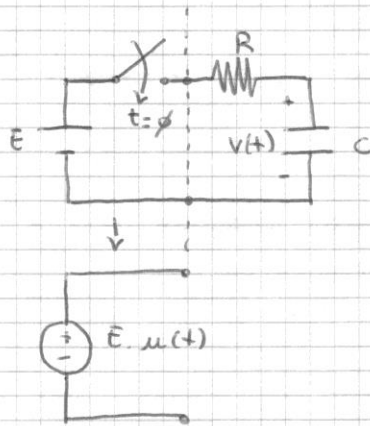
Rete Degenera RLC: Rete che contiene una maglia di soli C e/o generatori indipendenti di V , oppure, per dualità, un taglio di soli L e/o generatori indipendenti di I .



Continuità delle Variabili di Stato:

in una rete RLC non degenerata le variabili di stato (i_c , v_c) sono continue in presenza di eventi critici.

... Deriva dal fatto che i_c e v_c sono limitate in corrispondenza degli istanti critici.



C scarico per $t < \phi$.
 $v(t), t > \phi$

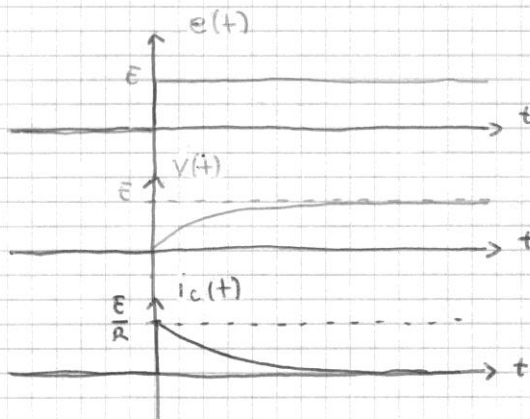
$$\begin{cases} R \cdot C \cdot \frac{dv}{dt} + v = E, & t > \phi \\ v(\phi^+) = v(\phi^-) = \phi \end{cases}$$

↑ continuità var. di stato

Conosco lo stato per $t < \phi$
 $v(\phi^-) = \phi$

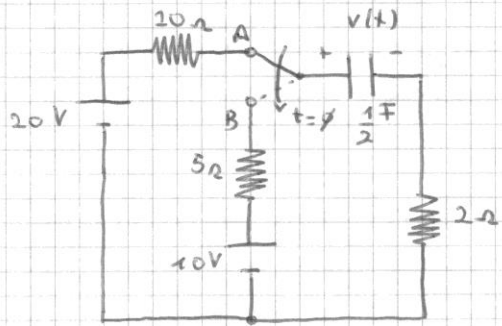
Per risolvere equazione differenziale ho bisogno dello stato a $t = \phi^+$.

$$v(t) = E \left(1 - e^{-\frac{t}{\tau}} \right), \quad t \geq \phi$$



$$i_c(t) = \frac{E}{R} e^{-\frac{t}{\tau}}, \quad t > \phi$$

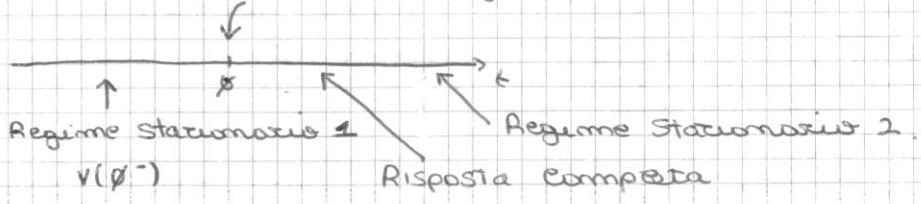
$i_c(t)$ non è var. di stato
 \rightarrow è discontinua



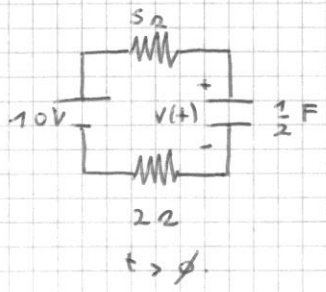
? $v(t)$, $t > 0$

il commutatore, da lungo tempo nella posizione A, viene scattato a $t=0$, nella posizione B.

Rete non danneggiata : $v(0^+) = v(0^-)$.



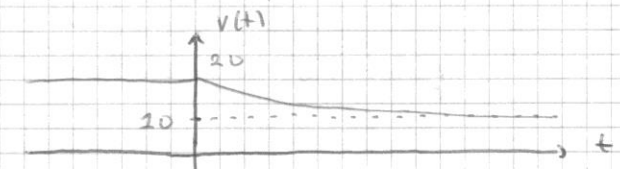
Reg. Staz. 1, $v(0^-) = 20V = v(0^+)$



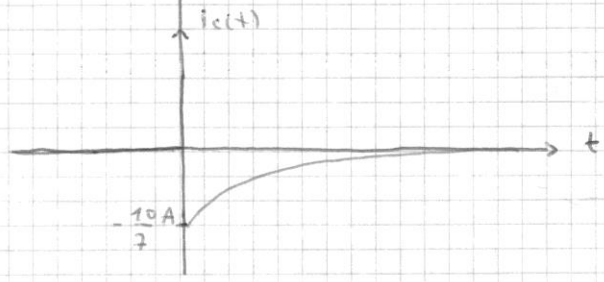
$V_{\text{con}}(t) = V_{\text{lib}}(t) + V_{\text{for}}(t)$

$\tau = RC = \frac{7}{2} \text{ sec}$

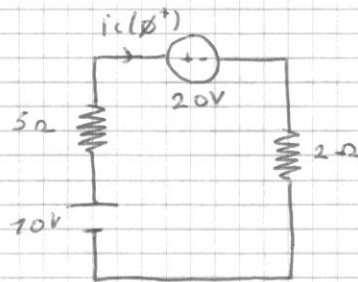
$V_{\text{con}}(t) = v(0^+) e^{-\frac{t}{\tau}} + 10(1 - e^{-\frac{t}{\tau}})$
 $= 20 e^{-\frac{2}{7}t} + 10(1 - e^{-\frac{2}{7}t}), t \geq 0$



C è un c.a. C è un gem. di V

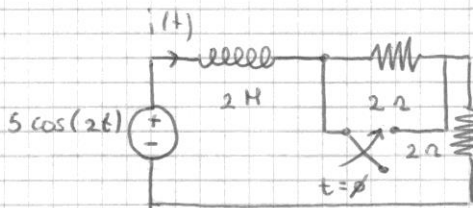


$t = \phi$



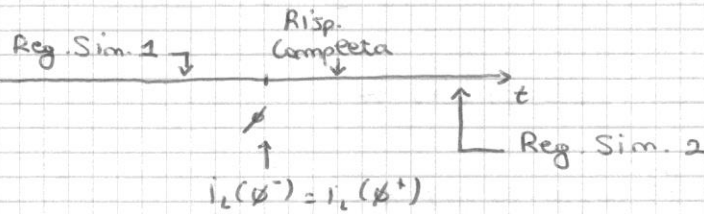
$$i_L(\phi^+) = -\frac{10}{7} \text{ A}$$

17/02/1997

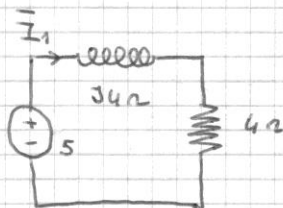


l'interuttore apre da lungo tempo si chiude a $t = \phi$

? $i(t)$, $t > \phi$



Reg. Sim. 1, $t = \phi^-$

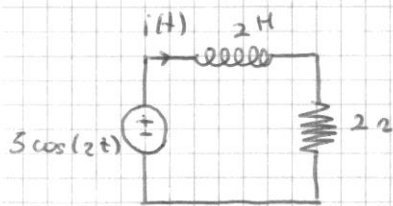


$$\begin{aligned} \bar{I}_1 &= \frac{5}{4 + j4} = \frac{5}{4} \cdot \frac{1}{1 + j} = \frac{5}{4} \cdot \frac{1 - j}{2} \\ &= \frac{5}{8} - j \frac{5}{8} \end{aligned}$$

$$i(t) = \text{Re} \left[\bar{I}_1 e^{j2t} \right] \rightarrow i_L(\phi) = \text{Re} \left[\bar{I}_1 \right]$$

$$i_L(\phi^-) = \frac{5}{8} \text{ A} = i_L(\phi^+)$$

$t > \neq$, evoluzione continua per $t > \neq$.



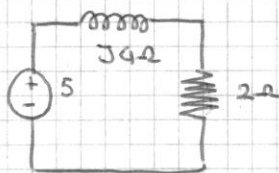
$$\begin{aligned}
 C &= L + F \\
 &= L + T + \text{Regime Sim. 2} \\
 &= TC + \text{Regime Sim. 2}
 \end{aligned}$$

$$i(t) = K \cdot e^{-\frac{t}{\tau}} + I_{M2} \cos(2t + \varphi_{32})$$

$$\tau = \frac{L}{R} = 1 \text{ sec}$$

K si calcola come ultima cosa!

Reg. Sim. 2



$$\begin{aligned}
 \bar{i}_2 &= \frac{5}{2 + j3} = \frac{5}{2} \frac{1}{1 + j1.5} = \frac{5}{2} \frac{e^{-j \arctan 1.5}}{\sqrt{5}} \\
 &= e^{-j63.4^\circ} \frac{\sqrt{5}}{2}
 \end{aligned}$$

$$i(t) = K \cdot e^{-t} + \frac{\sqrt{5}}{2} \cos(2t - 63.4^\circ) \text{ A}$$

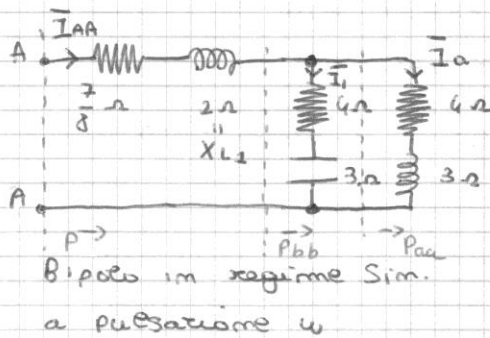
$$i(\neq^+) = \frac{5}{8} \text{ A} = K + \frac{\sqrt{5}}{2} \cos(-63.4^\circ) \text{ A}$$

$$\rightarrow K = 0.124$$

$$i(t) = 0.124 \cdot e^{-t} + \frac{\sqrt{5}}{2} \cos(2t - 63.4^\circ) \text{ A}, \quad t \geq \neq$$

Il transitorio permette di Raccattare le Variabili di Stato!

Esercizio



$I_a = 20 \text{ Aeff}$

? P_{AA} , Q_{AA} , V_{AA} , I_{AA}
 usando T. di Boucherot.

$P_{aa} = 4 I_a^2 = 1600 \text{ W}$

$Q_{aa} = 3 I_a^2 = 1200 \text{ VAR}$

$A_{aa} = \sqrt{P_{aa}^2 + Q_{aa}^2} = 2000 \text{ VA} = V_a I_a \rightarrow V_a = 100 \text{ Veff}$

$I' = \frac{V_{aa}}{Z} = \frac{100}{\sqrt{3^2 + 4^2}} = \frac{100}{5} = 20 \text{ Aeff}$

$P_{bb} = 1600 + 4 \cdot 20^2 = 3200 \text{ W}$

$Q_{bb} = 1200 - (3 \cdot 20^2) = \emptyset \text{ VAR}$

$A_{bb} = 3200 \text{ VA} = V_{aa} \cdot I_{AA} \rightarrow I_{AA} = 32 \text{ Aeff}$

$\bar{I}_{AA} = \bar{I}' + \bar{I}_a \leftarrow \text{N.B.}$

$I_{AA} \neq I' + I_a$

Non si sommano i valori Efficaci!

$P_{AA} = 3200 + \frac{7}{8} \cdot I_{AA}^2 = 4096 \text{ W} \approx 4100 \text{ W}$

$Q_{AA} = \emptyset + 2 \cdot I_{AA}^2 = 2050 \text{ VAR}$

$A_{AA} = \sqrt{P_{AA}^2 + Q_{AA}^2} = 4580 \text{ VA} = V_{AA} \cdot I_{AA} \rightarrow V_{AA} = 143 \text{ Veff}$

$$P = V \cdot I \cos \varphi_z = V \cdot I \cdot \cos(\varphi_v - \varphi_z) \text{ Watt}$$

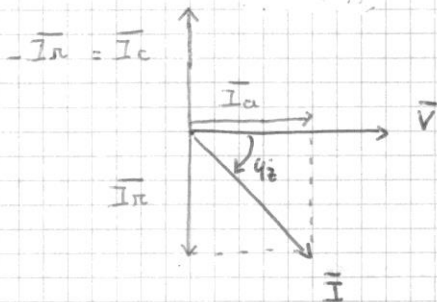
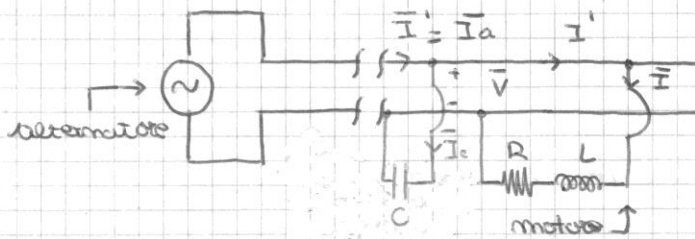
$$Q = V \cdot I \sin \varphi_z = V \cdot I \cdot \sin(\varphi_v - \varphi_z) \text{ VAR}$$

$\cos \varphi_z = \cos(\varphi_v - \varphi_z)$: Fattore di Potenza (Attiva)

$\cos \varphi_z = 1 \rightarrow P_{\text{MAX}}, Q_{\text{MIN}}$

$\cos \varphi_z = \phi \rightarrow P_{\text{MIN}}, Q_{\text{MAX}}$

RIFASAMENTO:



Solo I_a trasporta
energia!

$\rightarrow I_a = I'$ dopo il rifasamento

la linea ora trasporta solo Potenza Attiva

La Potenza Scommessa fa passare la corrente di
linea la quale non trasporta energia!

La elimina col rifasamento.

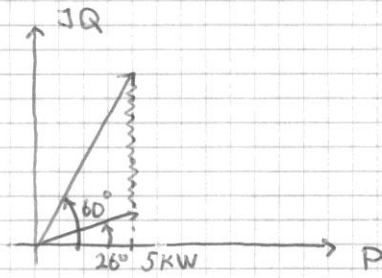
Motore assorbe 5 kWatt con fattore di potenza 0,5 induttivo.

Effettuare un rifasamento a $\cos \varphi_{\text{rif}} = 0,9$ (induttivo);

$\omega = 314 \text{ rad/sec}$; $V = 160 \text{ Veff}$.

$$\cos \varphi_m = 0,5 \rightarrow \varphi_m = 60^\circ$$

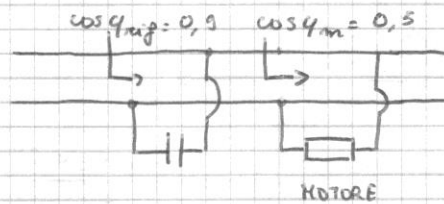
$$\cos \varphi_{\text{rif}} = 0,9 \rightarrow \varphi_{\text{rif}} \approx 26^\circ$$



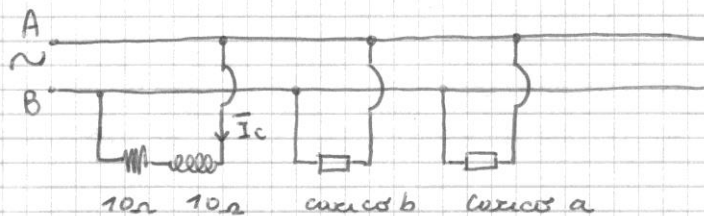
$$|Q_c| = P \operatorname{tg} \varphi_m - P \operatorname{tg} \varphi_{ref}$$

$$\omega C V^2 = P (\operatorname{tg} \varphi_m - \operatorname{tg} \varphi_{ref})$$

$$C = \frac{P}{\omega V^2} (\operatorname{tg} \varphi_m - \operatorname{tg} \varphi_{ref}) = \frac{5000 (\operatorname{tg} 60^\circ - \operatorname{tg} 26^\circ)}{314 \cdot 160^2} = 773 \mu\text{F}$$



Esercizio:



$$V : 100 \text{ Veff}$$

$$f = 50 \text{ Hz}$$

$$\text{carico a : } A_a = 1000 \text{ VA}$$

$$\cos \varphi_a = 0,8 \text{ (induttivo)}$$

$$\text{carico b : } \begin{cases} \text{corrente attiva : } 5 \text{ Aeff} \\ \text{corrente reattiva induttiva : } 5 \text{ Aeff} \end{cases}$$

Riparamentis a $\cos \varphi_{ref} = 0,9$ (induttivo)

$$a) P_a = A_a \cos \varphi_a = 800 \text{ W}$$

$$Q_a = A_a \sin \varphi_a = 600 \text{ VAR}$$

$$b) P_b = V_{eff} \cdot I_{act} = 500 \text{ W}$$

$$Q_b = V_{eff} \cdot I_{reatt} = 500 \text{ VAR}$$

esercizio RL:

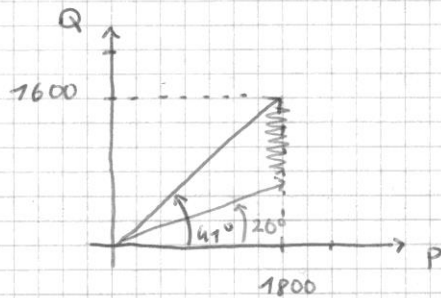
$$\bar{I}_c = \frac{100}{\sqrt{10^2 + 10^2}} = 7,07 \text{ A}_{eff}$$

$$P_c = 10 \cdot 7,07^2 = 500 \text{ W}$$

$$Q_c = 10 \cdot 7,07^2 = 500 \text{ VAR}$$

$$P_{AB} = 1800 \text{ W}$$

$$Q_{AB} = 1600 \text{ VAR}$$



$$WCV^2 = Q_{AB} - P_{AB} \tan 26^\circ = \frac{1600 - 1800 \tan 26^\circ}{314 \cdot 100^2} = 232 \mu\text{F}$$

$$W = 2\pi f$$

? Valutare la diminuzione di corrente assorbita dal bipolo AB in Valore efficace, ottenuta col superamento.

I_{AB} prima:

$$A_{AB} \text{ prima} = \sqrt{P_{AB}^2 + Q_{AB}^2} = 2400 \text{ VA} = V I_{AB} \text{ prima}$$

$$I_{AB} \text{ prima} = 24 \text{ A}_{eff}$$

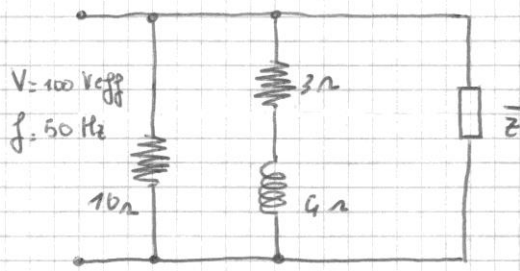
I_{AB} dopo:

$$A_{AB} \text{ dopo} = \sqrt{P_{AB}^2 + (P_{AB} \tan 26^\circ)^2} = 2000 \text{ VA}$$

$$I_{AB} \text{ dopo} = 20 \text{ A}_{eff}$$

$$\text{Diminuzione: } 24 - 20 = 4 \text{ A}_{eff}$$

Esercizio per casa:



\bar{z} : 5 A_{eff} attiva
 $10 \text{ A}_{\text{eff}}$ reattiva induttiva

1. Rispazamento a $\cos(\varphi_{\text{eff}}) = 0,9$ (induttivo)

[$C = 555 \mu\text{F}$]

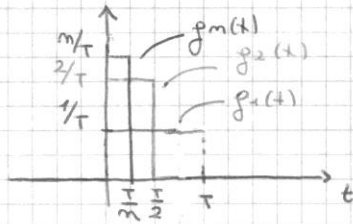
2. Corrente Fase assoluta del bipolo.

$$\begin{cases} I_{\text{prima}} = 37,354 \\ I_{\text{seconda}} = 37,354, 2 \end{cases}$$

PARTE 3

08/05/2015

Richiami su Funzioni Impulsive

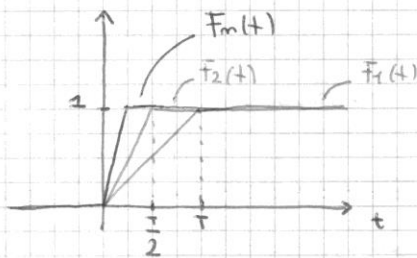


$$\delta(t) = \lim_{m \rightarrow \infty} f_m(t) = \begin{cases} \phi, & t \neq \phi \\ \infty, & t = \phi \end{cases}$$

con area sottoa unitaria

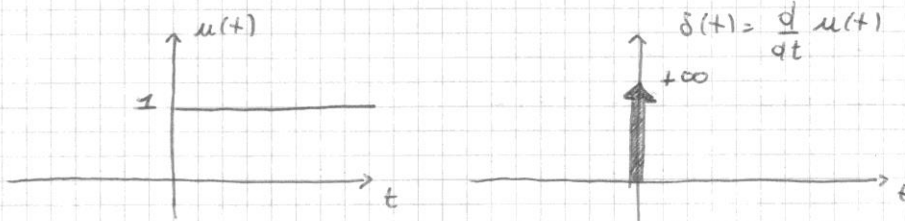
$$\int_{-\infty}^{+\infty} \delta(t) dt = \int_{-\epsilon}^{+\epsilon} \delta(t) dt = 1, \quad \forall \epsilon > \phi$$

Da non confondersi con la $\delta(x)$ in tempo discreto che $\delta(\phi) = 1$!



$$f_m(t) = \frac{d}{dt} F_m(t)$$

$$\lim_{m \rightarrow \infty} f_m(t) = \delta(t) = \frac{d}{dt} \left(\lim_{m \rightarrow \infty} F_m(t) \right) = \frac{d}{dt} u(t)$$



$\delta(t) = \frac{d}{dt} u(t)$, derivata nel senso delle funzioni impulsive.

Sia $f(t)$ derivabile nel senso delle funzioni ordinarie, eccetto che in un numero finito di istanti $t_i, (i=1, \dots, n)$ dove esistono discontinuita di Prima Specie (\exists finite $f(t_i^+), f(t_i^-)$).

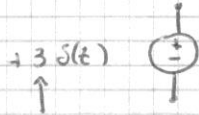
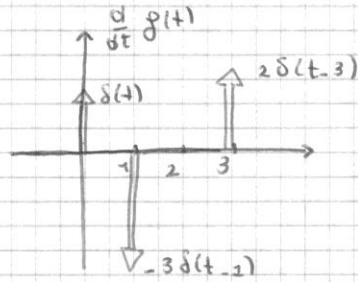
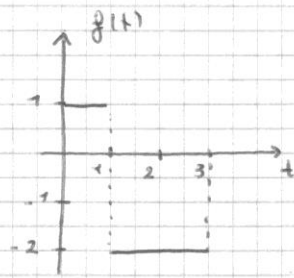
allora:

$$\frac{d}{dt} f(t) = f'(t) + \sum_{i=1}^n [f(t_i^+) - f(t_i^-)] \delta(t - t_i)$$

↑
derivata nel senso
delle funzioni
impulsive

↑
derivata nel senso
delle funzioni
ordinarie

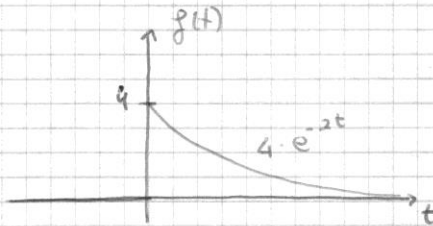
δ_i : salto di f in t_i



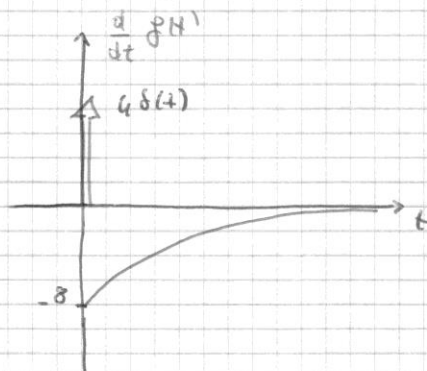
unità di misura di 3 : V·sec oppure A·sec , [3] = V·sec

$$f(t) = 4 e^{-2t} \cdot u(t)$$

$$? \frac{d}{dt} f(t)$$



$$\frac{d}{dt} f(t) = \underbrace{-8 e^{-2t} \cdot u(t)}_{f'(x)} + 4 \delta(t - 0)$$



Ricordi della Teoria di Laplace

$$f(t) : \mathbb{R} \rightarrow \mathbb{C}$$

$$L[f] = F(s), \quad s = \sigma + j\omega$$

$$L[f] = F(s) = \int_{\gamma}^{+\infty} f(t) e^{-st} dt$$

$$F(s) : \mathbb{C} \rightarrow \mathbb{C}$$

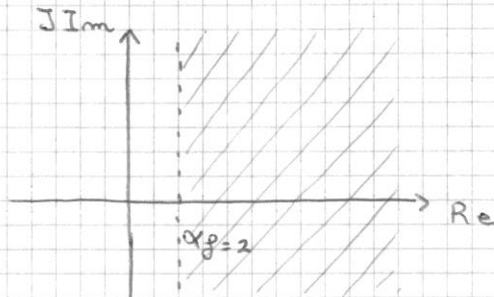
Funzioni Ordinarie Trasformabili secondo Laplace

-) f continua a tratti; \mathbb{R}_+ ha più discontinuità di prima specie (\exists finite $f(t^+)$, $f(t^-)$)
-) f di ordine esponenziale

$$|f(t)| \leq M \cdot e^{\beta t}, \quad t \geq 0 \quad M, \beta > 0$$

$\rightarrow \alpha_f \geq 0$ ascissa di convergenza

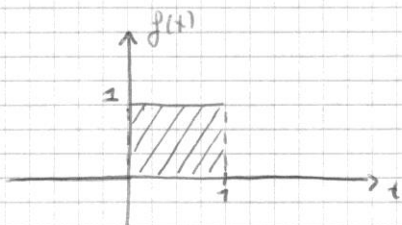
$F(s)$ è ben definita per $\text{Re}[s] = \sigma > \alpha_f$.



$$e^{2t} \cdot u(t) \rightarrow \frac{1}{s-2}, \quad \alpha_f = 2$$

Trasformate di Laplace di Funzioni Elementari

$f(t)$	$F(s)$
$u(t)$	$\frac{1}{s}$ ($\alpha = \beta$)
$e^{s_0 t} \cdot u(t), s_0 \in \mathbb{C}$	$\frac{1}{s - s_0}$
$\sin(\omega_0 t) \cdot u(t), \omega_0 \in \mathbb{R}$	$\frac{\omega_0}{s^2 + \omega_0^2}$ ($\alpha \neq \beta$)
$\cos(\omega_0 t) \cdot u(t), \omega_0 \in \mathbb{R}$	$\frac{s}{s^2 + \omega_0^2}$ ($\alpha = \beta$)
$e^{-\alpha t} \sin(\beta t) \cdot u(t)$	$\frac{\beta}{(s + \alpha)^2 + \beta^2}$
$e^{-\alpha t} \cos(\beta t) \cdot u(t)$	$\frac{s + \alpha}{(s + \alpha)^2 + \beta^2}$
$t^m \cdot u(t)$	$\frac{m!}{s^{m+1}}$
$t \cdot u(t)$	$\frac{1}{s^2}$
$e^{-\alpha t} \cdot t^m \cdot u(t)$	$\frac{m!}{(s + \alpha)^{m+1}}$



$$F(s) = \int_{-\infty}^{+\infty} f(t) e^{-st} dt$$

$$f(t) = u(t) - u(t-1)$$

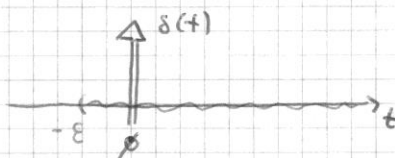
$$F(s) = \frac{1}{s} - \frac{1}{s} e^{-s}$$

$$= \frac{1 - e^{-s}}{s} \xrightarrow{s \neq 0} 1 \text{ area sottesa dalla funzione}$$

Trasformata di Laplace di Funzioni Impulsive

$$\delta(t) = \begin{cases} 0 & t \neq \phi \\ \infty & t = \phi \end{cases}$$

area unitaria



$$L[\delta(t)] = \int_{\phi}^{+\infty} \delta(t) e^{-st} dt$$

$$L_{\phi}[\delta(t)] = \lim_{\epsilon \rightarrow 0^+} \int_{-\epsilon}^{+\infty} \delta(t) e^{-st} dt = \left[e^{-st} \right]_{t=\phi} = 1$$

Teorema di derivazione (area ϕ^-).

$$L_{\phi} \left[\frac{d}{dt} f(t) \right] = s \cdot L_{\phi} [f(t)] - f(\phi^-)$$

Trasformata
allo zero meno

Trasformata nel
senso della ϕ^-
impulsive

Limite sinistro di f
in $t = \phi$.

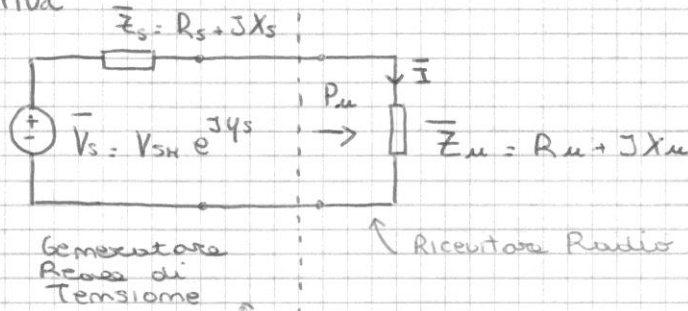
$$\delta(t) = \frac{d}{dt} u(t)$$

$$L_{\phi}[\delta(t)] = s \cdot L_{\phi}[u(t)] - u(\phi^-) = s \cdot \frac{1}{s} - \phi = 1$$

PARTE 2

Teorema del massimo Trasferimento di Potenza

ATTIVA

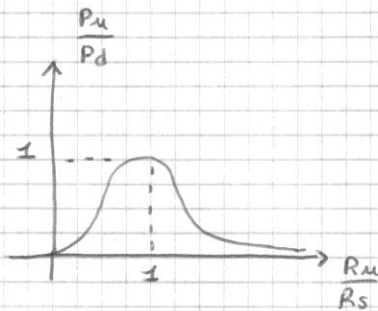


Il caso che ~~avverte~~ la massima potenza utata \bar{i} :

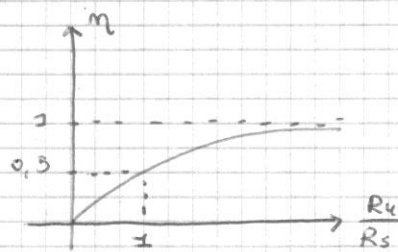
$$\bar{Z}_u = \bar{Z}_s^* \rightarrow \begin{cases} R_u = R_s \\ X_u = -X_s \end{cases} \rightarrow \begin{array}{l} \text{Impedenza adattata} \\ \text{per massima} \\ \text{assorbimento di} \\ \text{Potenza.} \end{array}$$

Potenza massima base:

$$P_{u, \text{MAX}} = \frac{1}{8} \cdot \frac{V_{SH}^2}{R_s} = \frac{1}{4} \cdot \frac{V_{s, \text{eff}}^2}{R_s} = P_d \quad \text{Potenza disponibile dal generatore.}$$



$$X_u = -X_s$$



$$\eta = \frac{P_u}{P_u + P_s} = \frac{R_u}{R_u + R_s}$$

nel caso di una rete elettrica: $\eta_{\text{MAX}} \rightarrow R_u \gg R_s$
 $P_{\text{RICEVUTA}} \text{ MIN.}$

nel caso di una ricezione di segnali: $P_{\text{RICEVUTA}} \text{ MAX}, \eta = 0,5.$

$$P_u = \frac{1}{2} \operatorname{Re} [\bar{Z}_u] I_u^2 = \frac{1}{2} R_u I_u^2 = \frac{1}{2} R_u \frac{V_{SH}^2}{(R_u + R_s)^2 + (X_u + X_s)^2}$$

$$F_u(R_u, X_u) = \frac{(R_u + R_s)^2 + (X_u + X_s)^2}{R_u}$$

$$\frac{\partial F}{\partial X_u} = \frac{2(X_u + X_s)}{R_u} = 0 \rightarrow X_u = -X_s$$

$$\frac{\partial F}{\partial R_u} = \frac{2(R_u + R_s)R_u - (R_u + R_s)^2 - (X_u + X_s)^2}{R_u^2} \Big|_{X_u = -X_s}$$

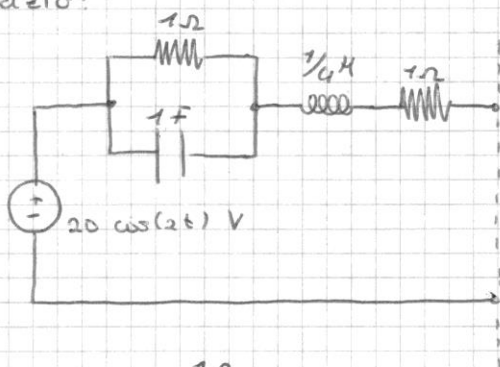
$$= \frac{2R_u^2 + 2R_s R_u - R_u^2 - R_s^2 - 2R_u R_s}{R_u^2} = \frac{R_u^2 - R_s^2}{R_u^2} = \frac{(R_u + R_s)(R_u - R_s)}{R_u^2} = 0$$

$$\begin{cases} X_u = -X_s \\ R_u = R_s \end{cases}$$

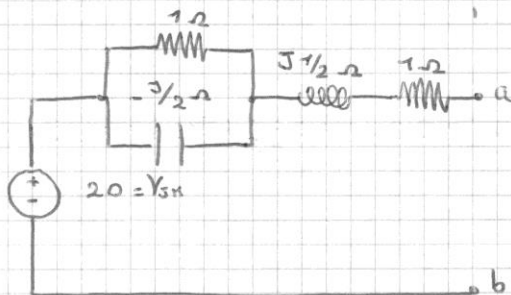
$$P_u = \frac{1}{2} R_u \frac{V_{SH}^2}{(R_u + R_s)^2 + (X_u + X_s)^2}$$

$$P_{u, \max} = \frac{1}{2} R_s \frac{V_{SH}^2}{(2R_s)^2} = \frac{1}{8} \frac{V_{SH}^2}{R_s}$$

Esercizio:



? Potenza disponibile generatore Reale.



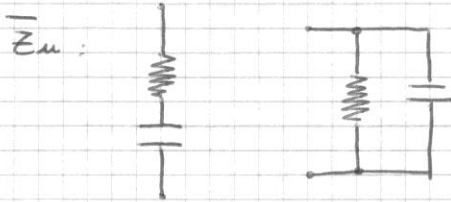
$$\bar{Z}_s = \frac{-j \frac{1}{2}}{1 - \frac{j}{2}} + \frac{1}{2} + 1 = \frac{-j}{2-j} + \frac{1}{2} + 1 = -j \cdot \frac{2+j}{5} + \frac{3}{2} + 1$$

$$= \frac{1}{5} + 1 - j \cdot \frac{2}{5} + \frac{j}{2} \Omega$$

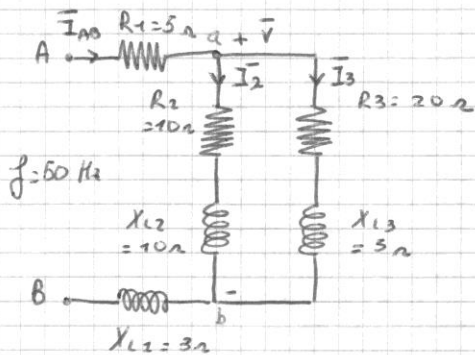
$$\bar{Z}_s = \frac{6}{5} + j \cdot \frac{1}{10} \Omega$$

$$P_d = \frac{1}{8} \cdot \frac{V_{SH}^2}{R_s} = \frac{1}{8} \cdot \frac{20^2}{\frac{6}{5}} = 41,7 \text{ W}$$

$$\bar{Z}_u = \bar{Z}_s^* = \frac{6}{5} - j \cdot \frac{1}{10} \Omega \quad (\text{ORmica Capacitiva})$$



24/06/2014



0,9 induttivo dopo il
riferimento

Diminuzione I_{eff}

$$P_{R2} = 10 \text{ kW}$$

$$\begin{cases} P_{AB} = 32635 \text{ W} \\ Q_{AB} = 20290 \text{ VAR} \end{cases}$$

$$P_{R2} = I_{2eff}^2 \cdot R_2 \Rightarrow I_{2eff} = 31,62 \text{ A}_{eff}$$

$$A_{AB} = 38428 \text{ VA}$$

$$V_{eff} = 31,62 \cdot \sqrt{200} = 447 \text{ V}_{eff}$$

$$= V_{AB} \cdot I_{AB}$$

$$\rightarrow V_{AB} = 746 \text{ V}_{eff}$$

$$I_{3eff} = \frac{V_{eff}}{\sqrt{425}} = 21,68 \text{ A}_{eff}$$

$$C = \frac{20290 - P_{AB} \cdot \tan \phi_{AB}}{V_{AB}^2}$$

$$P_{R3} = I_{3eff}^2 \cdot R_3 = (21,68)^2 \cdot 20 = 9400 \text{ W}$$

$$= 25 \mu\text{F}$$

$$Q_{L3} = I_{3eff}^2 \cdot X_{L3} = 2350 \text{ VAR}$$

$$\Rightarrow I_{Aeff} = 48,5 \text{ A}_{eff}$$

$$P_{AB} = P_{R2} + P_{R3} = 19,4 \text{ kW}$$

$$Q_{AB} = Q_{L2} + Q_{L3} = 12350 \text{ VAR}$$

$$A_{AB} = \sqrt{P_{AB}^2 + Q_{AB}^2} = 23 \text{ kVA} = I_{AB} \cdot V_{AB}, \quad I_{AB} = \frac{A_{AB}}{V_{AB}} = 51,45 \text{ A}_{eff}$$

$$P_{R1} = I_{Aeff}^2 \cdot 5 = 13235 \text{ W}, \quad Q_{L1} = I_{Aeff}^2 \cdot 3 = 7041 \text{ VAR}$$

? Energia magnetica media su un periodo T per i 3 induttori.

$$E_{L1} = 12,6 \text{ J}$$

$$E_{L2} = 15,9 \text{ J}$$

$$E_{L3} = 3,74 \text{ J}$$

PARTE 3

13/05/2015

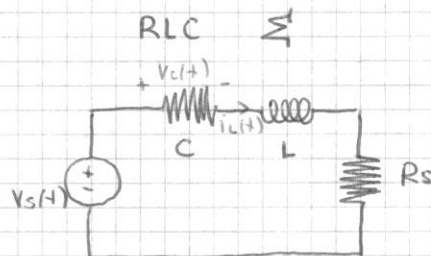
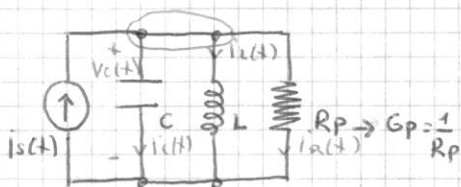
Circuiti del Secondo Ordine

1) Evoluzione continua per $t > \phi$

- Lineare;
- Forzata ad eccitazione costante e sinusoidale;
- Completa

2) Transitori CRL conseguono ad un evento critico

RLC //



Var. di stato: $i_L(t)$, $v_C(t)$

$$\frac{d^2}{dt^2} v_C + \frac{R_s}{L} \frac{d}{dt} v_C + \frac{1}{LC} v_C = \frac{1}{LC} v_s(t), t > \phi$$

$$i_s(t) = i_c(t) + i_L(t) + i_R(t), t > \phi$$

$$\text{Perdite} = R_s \cdot i^2(t)$$

$$v_C(t) = v(t) = L \frac{d}{dt} i_L(t)$$

$$L \cdot C \cdot \frac{d^2}{dt^2} i_L + \frac{L}{R_p} \frac{d}{dt} i_L + i_L = i_s(t), t > \phi$$

$$\frac{d^2}{dt^2} i_L + \frac{G_p}{C} \frac{d}{dt} i_L + \frac{1}{LC} i_L = \frac{1}{LC} i_s(t)$$

$$\text{Perdite} = v^2(t) \cdot G_p$$

$$\frac{d^2}{dt^2} x + 2\alpha \frac{d}{dt} x + \omega_0^2 x = f(t), t > 0$$

//

$$\alpha = \alpha_p = \frac{GP}{2C} \text{ rad/sec}$$

↑

Coefficiente di smorzamento

$$\alpha = \alpha_s = \frac{R_s}{2L}$$

Σ

$$\omega_0 = \frac{1}{\sqrt{LC}} \text{ rad/sec}$$

↑ Pulsazione di Risonanza

$$\omega_0 = \frac{1}{\sqrt{LC}}$$

$$f(t) = \omega_0^2 i_s(t)$$

$$x(t) = i_L(t)$$

$$f(t) = \omega_0^2 v_s(t)$$

$$x(t) = v_C(t)$$

Risposta Libera

$$\frac{d^2}{dt^2} x + 2\alpha \frac{d}{dt} x + \omega_0^2 x = 0, t > 0$$

integrale generale omogenea

$$s^2 + 2\alpha s + \omega_0^2 = 0$$

$$s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2}$$

radici caratteristiche

$$\Delta = \alpha^2 - \omega_0^2$$

$$\Delta \stackrel{!}{=} 0; \alpha \stackrel{!}{=} \omega_0$$

//

$$\alpha = \alpha_p = \frac{GP}{2C} \stackrel{!}{=} \omega_0 = \frac{1}{\sqrt{LC}}$$

$$\alpha = \alpha_s = \frac{R_s}{2L} \stackrel{!}{=} \omega_0 = \frac{1}{\sqrt{LC}}$$

$$\alpha \stackrel{!}{=} \omega_0 \Leftrightarrow GP \stackrel{!}{=} 2\sqrt{\frac{C}{L}} = G_c \quad \alpha \stackrel{!}{=} \omega_0 \Leftrightarrow R_s \stackrel{!}{=} 2\sqrt{\frac{L}{C}} = R_c$$

G_c : Conduttanza critica RLC // R_c : Resistenza critica RLC Σ

1) $\alpha > \omega_0$

Sommasmorzatur (Positive Werte)

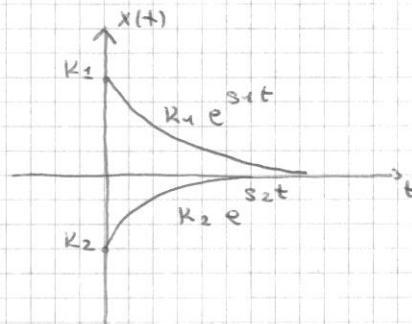
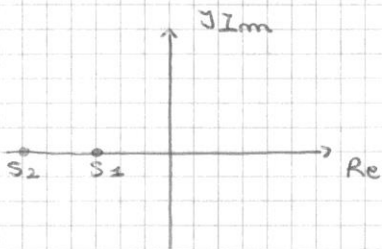
$$G_p > G_c = 2 \sqrt{\frac{C}{L}} \quad (//)$$

$$R_s > R_c = 2 \sqrt{\frac{L}{C}} \quad (\Sigma)$$

$$s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2} \quad (\text{Reale negative constanten})$$

$$x(t) = K_1 e^{s_1 t} + K_2 e^{s_2 t}, \quad t > 0$$

Composamente Aperiodisch



2) $\alpha = \omega_0$

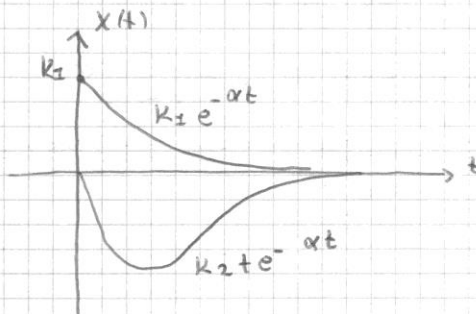
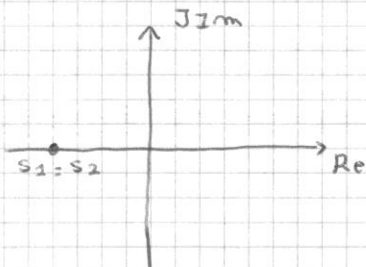
$$G_p = G_c = 2 \sqrt{\frac{C}{L}}, \quad \Delta = 0 \quad (//)$$

$$R_s = R_c = 2 \sqrt{\frac{L}{C}}, \quad \Delta = 0 \quad (\Sigma')$$

$$s_1 = s_2 = -\alpha = -\omega_0 \quad \text{Smorzamenteur Critisch}$$

$$x(t) = K_1 e^{-\alpha t} + K_2 t \cdot e^{-\alpha t}$$

Composamente Aperiodisch



3) $\alpha < \omega_0$, $\Delta < \phi$

Sottosmorcato

$G_p < G_c = 2\sqrt{\frac{C}{L}}$ (//)

$R_s < R_c = 2\sqrt{\frac{L}{C}}$ (Σ)

$S_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2} \rightarrow \angle \phi$

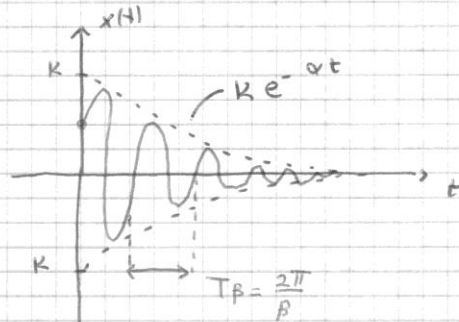
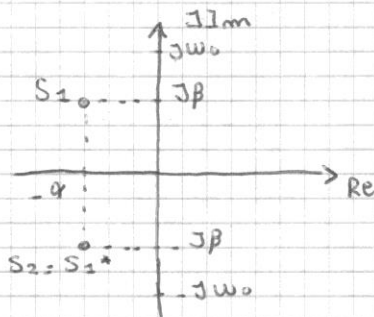
$S_{1,2} = -\alpha \pm j\sqrt{\omega_0^2 - \alpha^2}$

$\beta = \sqrt{\omega_0^2 - \alpha^2}$ rad/sec : Pulsazione naturale di oscillazione

$\phi < \beta < \omega_0$

$S_{1,2} = -\alpha \pm j\beta$

$x(t) = K_1 e^{-\alpha t} \cos(\beta t) + K_2 e^{-\alpha t} \sin(\beta t)$
 $= K e^{-\alpha t} \cos(\beta t - \theta)$, $t > \phi$



Pulsazione delle oscillazioni effettive

Interno delle impulso $\beta < \omega_0$

4) Senza Perdite

$G_p = \phi$ (//)

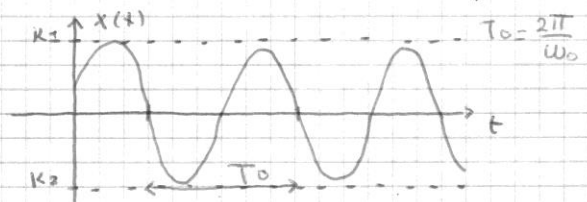
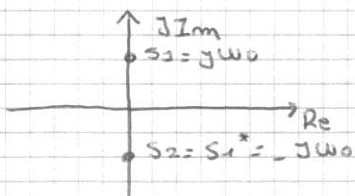
$R_s = \phi$ (Σ)

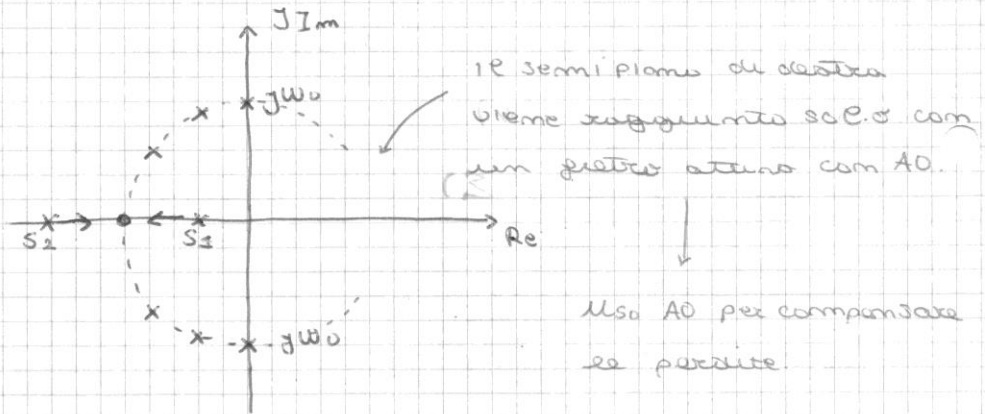
$\alpha = \phi$

$S_{1,2} = \pm j\omega_0 = \pm j\frac{1}{\sqrt{LC}}$

Oscilla alla frequenza ω_0

$x(t) = K_1 \cos(\omega_0 t) + K_2 \sin(\omega_0 t) = K \cos(\omega_0 t - \theta)$





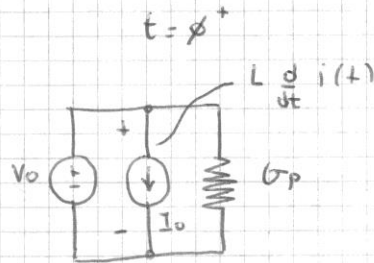
L, C fissi, variare G_p .

Determinazione di K_1, K_2 (costanti arbitrarie)

Condizioni iniziali: $i_L(\phi^+)$, $V_C(\phi^+)$
 I_0 , V_0

RLC //, sottosmorzato

$$\begin{cases} x(t) = i_L(t) = K_1 e^{s_1 t} + K_2 e^{s_2 t} \\ i_L(\phi^+) = I_0 \\ \frac{d}{dt} i_L(\phi^+) = \frac{V_0}{L} \end{cases}$$



$$i_L(\phi) = K_1 + K_2 = I_0$$

$$\frac{d}{dt} i_L(\phi^+) = s_1 K_1 + s_2 K_2 = \frac{V_0}{L}$$

$$K_1 = \frac{1}{s_1 - s_2} \left(\frac{V_0}{L} - s_2 I_0 \right)$$

$$K_2 = \frac{1}{s_2 - s_1} \left(\frac{V_0}{L} - s_1 I_0 \right)$$

fare gli altri casi per casa.

Esercizio:

Circuito RLC // in excitazione libera

$$R_p = 1 \Omega, L = 1 \text{ mH}, C = 1 \text{ F}$$

$$I_{00} = 1 \text{ A}, V_0 = 1 \text{ V}$$

$$? i_L(t), t > 0$$

$$G_C = 2 \sqrt{\frac{C}{L}} = 2 \Omega^{-1}, G_P = \frac{1}{R_p} = 1 \Omega^{-1} \ll 2 \Omega^{-1}$$

→ Caso sottosmorzato!

$$s_{1,2} = -\alpha_p \pm j\beta$$

$$\alpha_p = \frac{G_P}{2C} = \frac{1}{2} \text{ rad/sec}$$

$$\omega_0 = \frac{1}{\sqrt{LC}} = 1 \text{ rad/sec}$$

$$\beta = \sqrt{\omega_0^2 - \alpha_p^2} = \sqrt{1 - 1/4} = \frac{\sqrt{3}}{2} \text{ rad/sec}$$

$$s_{1,2} = -\frac{1}{2} \pm j \frac{\sqrt{3}}{2}$$

$$\begin{cases} i_L(t) = k_1 e^{-\frac{1}{2}t} \cos\left(\frac{\sqrt{3}}{2}t\right) + k_2 e^{-\frac{1}{2}t} \sin\left(\frac{\sqrt{3}}{2}t\right), t > 0 \\ i_L(0^+) = 1 \text{ A} \\ \frac{d}{dt} i_L(0^+) = \frac{V_0}{L} = 1 \text{ A/sec} \end{cases}$$

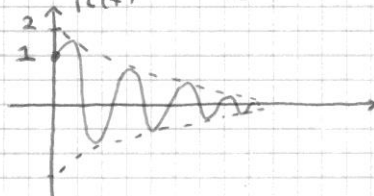
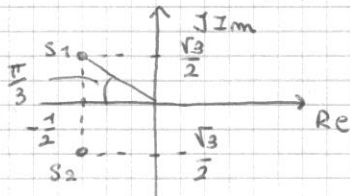
$$i_L(0^+) = k_1 = 1$$

$$i_L(t) = e^{-\frac{1}{2}t} \cos\left(\frac{\sqrt{3}}{2}t\right) + k_2 e^{-\frac{1}{2}t} \sin\left(\frac{\sqrt{3}}{2}t\right), t > 0$$

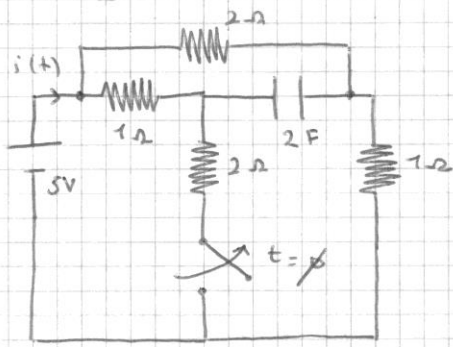
$$\frac{d}{dt} i_L(0^+) = -\frac{1}{2} + k_2 \cdot \frac{\sqrt{3}}{2} = 1 \text{ A/sec}$$

$$k_2 = \frac{3}{\sqrt{3}} = \sqrt{3}$$

$$i_L(t) = e^{-1/2t} \cos\left(\frac{\sqrt{3}}{2}t\right) + \sqrt{3} e^{-1/2t} \sin\left(\frac{\sqrt{3}}{2}t\right)$$

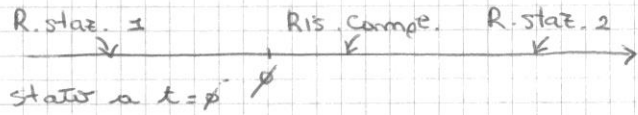


PARTE 2



l'interruttore, chiuso da lungo tempo, si apre a $t = \phi$.

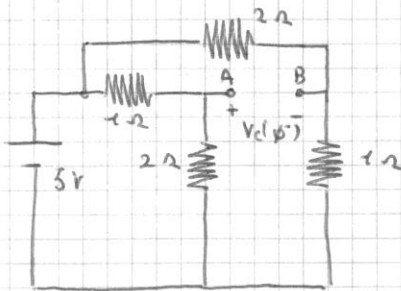
? $i(t), t > \phi$.



$$V_C(\phi^-) = V_C(\phi^+)$$

↑
Circuito non degenerato

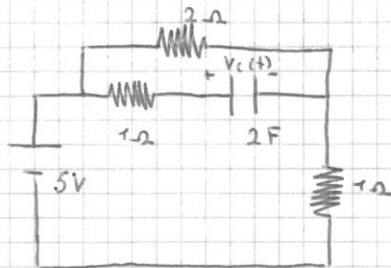
$t = \phi^-$ R. staz. 1



$$V_C(\phi^-) = V_A - V_B = \frac{10}{3} - \frac{5}{3} = \frac{5}{3} V.$$

$$V_C(\phi^+) = V_C(\phi^-) = \frac{5}{3} V.$$

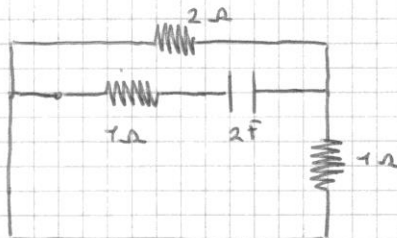
$t > \phi$



esercizio I° ordine con eccitazione costante.

$$i(t) = i(\phi^+) e^{-\frac{t}{\tau_{eq}}} + i(\infty) (1 - e^{-\frac{t}{\tau_{eq}}})$$

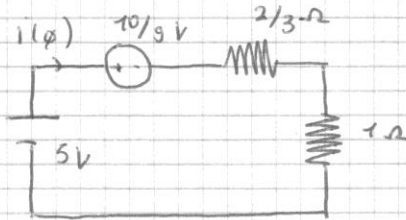
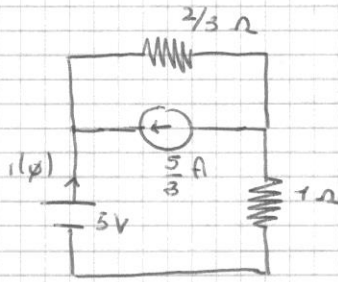
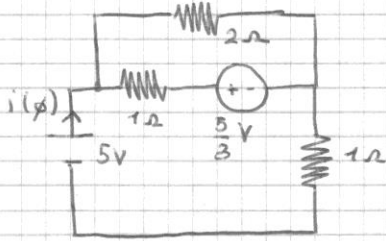
$t > \phi$



$$\tau_{eq} = C \cdot R_{eq} = \frac{10}{3} \text{ sec.}$$

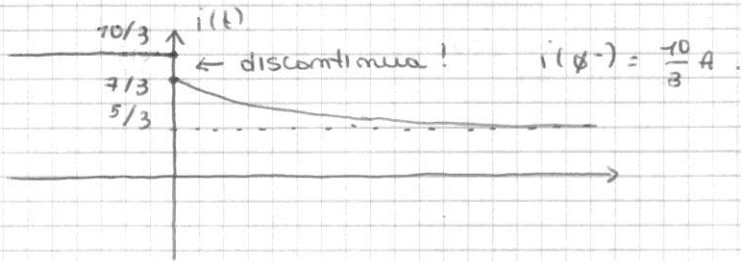
$$i(\infty) = \frac{5}{3} A.$$

$t = \phi^+$ istantanea

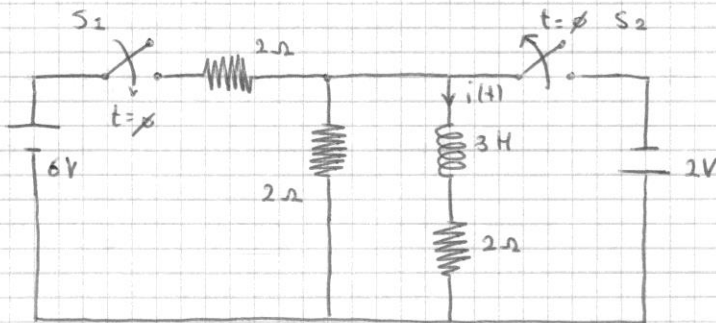


$$i(\phi) = \frac{5 - 10/9}{\frac{5}{3}} = \frac{7}{3} \text{ A}$$

$$\rightarrow i(t) = \frac{7}{3} e^{-\frac{3}{10}t} + \frac{5}{3} (1 - e^{-\frac{3}{10}t}), \quad t > \phi$$



Esercizio:



S_1 aperto da lungo tempo si chiude a $t = \phi$.

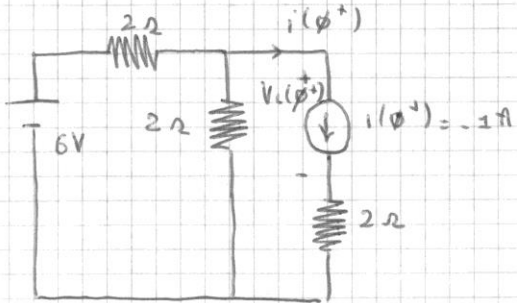
S_2 chiuso " " " " apre a $t = \phi$.

? $i(\phi^+)$, $\frac{d}{dt} i(\phi^+)$

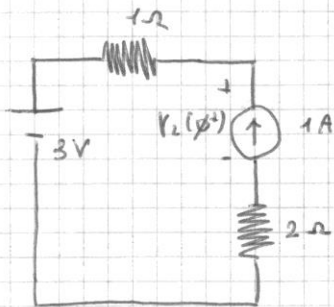
$$i(\phi^-) = -\frac{2}{2} = -1 \text{ A}$$

Rece non degenera : $i(\phi^+) = i(\phi^-) = -1 A$.

Istantanea a $t = \phi^+$.



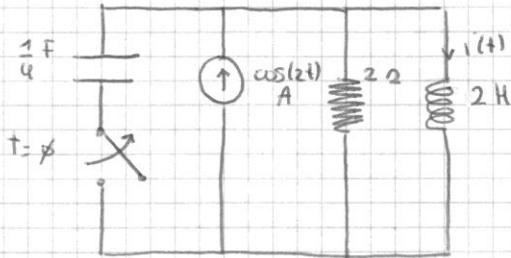
$$L \cdot \frac{d}{dt} i(\phi^+) = V_L(\phi^+)$$



$$V_L(\phi^+) = 3 + 3 = L \cdot \frac{d}{dt} i(\phi^+) = 3 \cdot \frac{d}{dt} i(\phi^+)$$

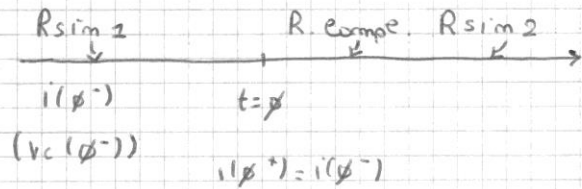
$$\frac{d}{dt} i(\phi^+) = 2 A/sec$$

Esercizio :

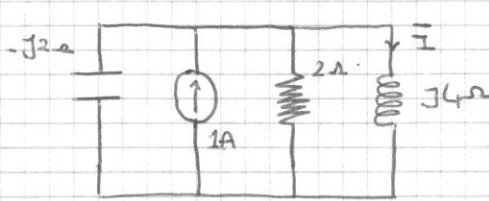


interrottata e chiuso da
lungo tempo si apre a $t = \phi$.

? $i(t)$, $t > \phi$, risp. completa.



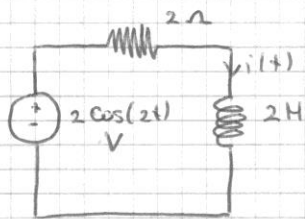
$$i = \phi \quad \text{RSim 1}$$



$$\bar{I} = \frac{\frac{1}{j4}}{\frac{1}{-j2} + \frac{1}{2} + \frac{1}{j4}} = \dots = -\frac{1}{2} - \frac{j}{2} \text{ A}$$

$$i(\phi^-) = i(\phi^+) = \text{Re} \{ \bar{I} \} = -\frac{1}{2} \text{ A}$$

Risp. completa $t > \phi$



$$i(t) = i_{\text{lec}}(t) + i_{\text{part}}(t) = i(\phi^+) \cdot e^{-t} + \text{Forzata}$$

↑
Per cosa!

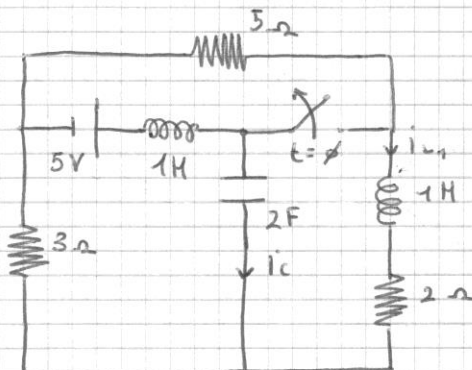
$$\tau_{\text{eq}} = \frac{L}{R} = 2 \text{ sec}$$

$$i(t) = \tau c + \text{Regime Sim. 2} = K e^{-t} + \frac{2}{\sqrt{4+4}} \cos(2t - 45^\circ)$$

$$i(\phi^+) = -\frac{1}{2} = K + \frac{2}{\sqrt{8}} \cos(-45^\circ)$$

$$\rightarrow -\frac{1}{2} = K + \frac{\sqrt{2}}{2} \cdot \frac{\sqrt{2}}{2} \Rightarrow K = -1$$

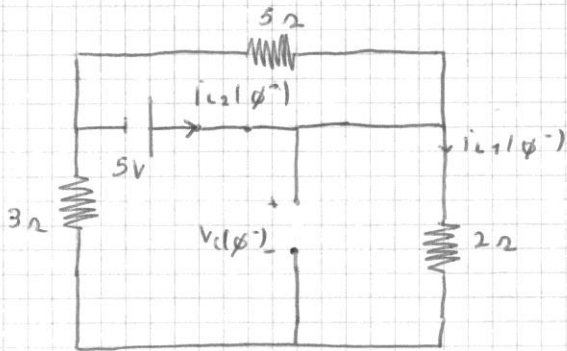
Esercizio:



$t = \phi$ si apre interruttore

$$? i_c(\phi^+), \frac{d}{dt} i_L(\phi^+)$$

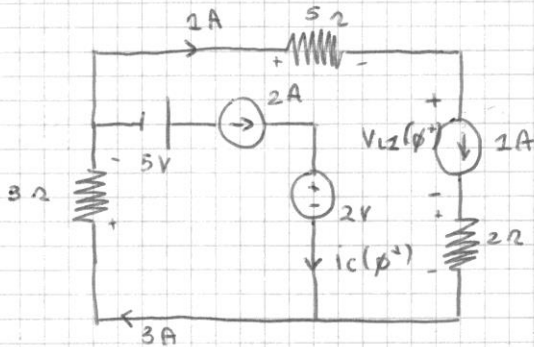
$t = \varphi^-$ Regime Stazionario



? $V_C(\varphi^-)$
 ? $i_{L1}(\varphi^-)$
 ? $i_{L2}(\varphi^-)$

$$\begin{aligned} i_{L2}(\varphi^-) &= 1 \text{ A} &= i_{L2}(\varphi^+) \\ V_C(\varphi^-) &= 2 \text{ V} &= V_C(\varphi^+) \\ i_{L1}(\varphi^-) &= 2 \text{ A} &= i_{L1}(\varphi^+) \end{aligned}$$

$t = \varphi^+$



$$i_C(\varphi^+) = 2 \text{ A}$$

$$\begin{aligned} 0 + 5 + V_{L2}(\varphi^+) + 2 &= \varphi \\ V_{L2}(\varphi^+) &= -7 \text{ V} \end{aligned}$$

$$\rightarrow \frac{d}{dt} i_L(t) = -7 \text{ A/sec}$$

Piccola Parentesi:

$$\sqrt[m]{1} \rightarrow s^m = 1, \quad s = |s| e^{j\theta}$$

$$s^m = |s|^m e^{jm\theta} = 1 \cdot e^{j(\theta + 2k\pi)}$$

$$|s|^m = 1 \rightarrow |s| = 1 = \sqrt[m]{1}$$

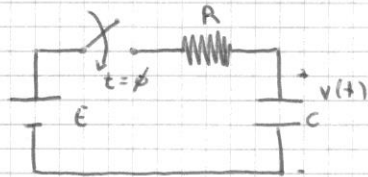
$$m\theta = 2k\pi, \quad k = 0, 1, 2, \dots, m-1, \dots$$

$$\theta = \frac{2k\pi}{m}, \quad k = 0, 1, \dots, m-1$$

$$m = 6, \quad \theta = \frac{2k\pi}{6}$$

$$\begin{aligned} \rightarrow k=0 &\rightarrow \theta = 0 \\ k=1 &\rightarrow \theta = \pi/3 \\ k=2 &\rightarrow \theta = 2/3\pi \\ k=3 &\rightarrow \vdots \\ k=4 &\rightarrow \vdots \\ k=5 &\rightarrow \vdots \end{aligned}$$

Analisi in II mee DT e mee DL di transistori in
 esercizi del I° ordine.



? $v(t), t > \phi$ DT e poi con TL.
 $v(\phi^-) = V_0$

DT:

1) Analisi per istante critico (ϕ^-, ϕ^+)

$$v(\phi^+) = v(\phi^-) = V(\phi)$$

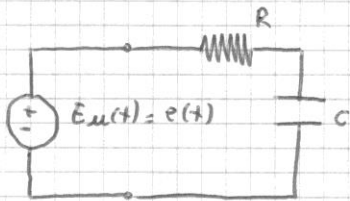
continuità var. di stato circuito non degenero

2) Analisi in evoluzione continua per $t > \phi$

$$\begin{cases} RC \cdot \frac{dv}{dt} + v = E & , t > \phi \\ v(\phi^+) = v(\phi^-) = V_0 \end{cases}$$

$$v(t) = V_{lib}(t) + V_{for}(t) = V_0 e^{-\frac{t}{RC}} + E(1 - e^{-\frac{t}{RC}}), t > \phi$$

DL: Verifica con TL



$t > \phi^-$

$t > -E$

$$\begin{cases} RC \cdot \frac{dv}{dt} + v = e(t) = E \cdot u(t) \\ v(\phi^-) = V_0 \end{cases}$$

$$\int_{\phi^-}^{+\infty} (RC \frac{dv}{dt} + v) e^{-st} dt = \int_{\phi^-}^{+\infty} e(t) e^{-st} dt$$

$$= RC [sV(s) \cdot v(\phi^-)] + V(s) = E(s) = \frac{E}{s}$$

$$(sRC + 1) V(s) = RC V(\phi^-) + \frac{E}{s} \rightarrow V(s) = \frac{RC}{sRC + 1} V_0 + \frac{E}{s(sRC + 1)}$$

$$= V_{lib}(s) + V_{for}(s)$$

$$V_{lib}(s) = \frac{V_0}{s + \frac{1}{RC}} \xrightarrow{\mathcal{L}^{-1}} V_{lib}(t) = V_0 e^{-\frac{t}{RC}} u(t)$$

$$V_{FOR}(s) = \frac{E}{\tau} \cdot \frac{1}{s + \frac{1}{\tau}} \cdot \frac{1}{s}$$

$$F(s) = \frac{1}{s + \frac{1}{\tau}} \cdot \frac{1}{s} = \frac{A}{s} + \frac{B}{s + \frac{1}{\tau}}$$

$$A = \lim_{s \rightarrow 0} s F(s) = \tau$$

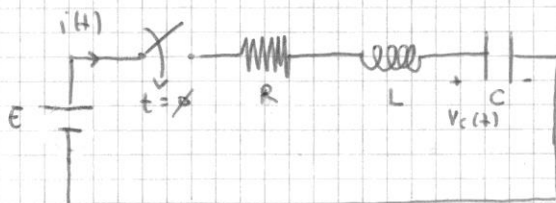
$$B = \lim_{s \rightarrow -\frac{1}{\tau}} (s + \frac{1}{\tau}) F(s) = -\tau$$

$$V_{FOR}(s) = \frac{E}{s} - \frac{E}{s + \frac{1}{\tau}} \xrightarrow{\mathcal{L}^{-1}} V_{FOR}(t) = E u(t) - E e^{-\frac{t}{\tau}} u(t)$$

OK! Il risultato è lo stesso.

Se $F(s) = \frac{N(s)}{D(s)}$, s_0 polo 1° ordine $\rightarrow A = \frac{N(s_0)}{D'(s_0)}$.

Esercizio Teorico (esercizio II° Ordine)



? $i(t)$, $t \geq 0$
Risposta Forzata

$$i(\phi^-) = 0, V_c(\phi^-) = 0$$

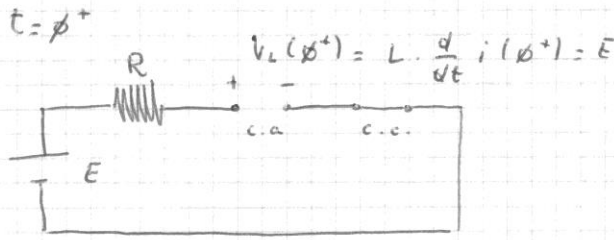
- 1) Analisi (ϕ^-, ϕ^+) , continuità loc. di stato
Circuito non degenerato $\rightarrow i(\phi^+) = 0$
 $V_c(\phi^+) = 0$

- 2) Evoluzione continua per $t > \phi$.

$$L \frac{d}{dt} i + R i + V_c(\phi^+) + \frac{1}{C} \int_{\phi^+}^t i(t') dt' = E, t > \phi$$

Posso derivare:

$$\begin{cases} L \frac{d^2}{dt^2} i + R \frac{d}{dt} i + \frac{1}{C} i = 0, t > \phi \\ i(\phi^+) = 0 \\ \frac{d}{dt} i(\phi^+) = ? = \frac{E}{L} \end{cases}$$



Caso Sottosmorcato :

$$R < R_c = 2 \sqrt{\frac{L}{C}} \quad s_{1,2} = -\alpha \pm j\beta$$

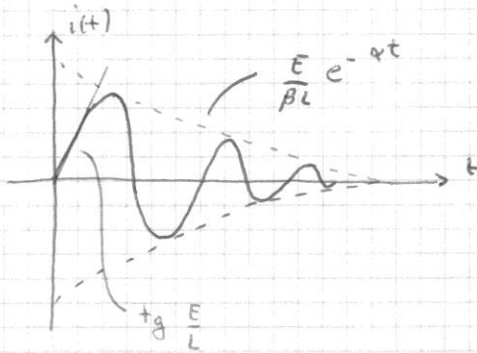
$$i(t) = K_1 \cdot e^{-\alpha t} \cos(\beta t) + K_2 \cdot e^{-\alpha t} \sin(\beta t), \quad t > \phi$$

$$i(\phi^+) = \phi = K_1$$

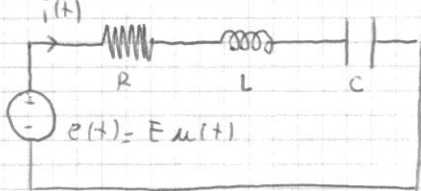
$$\rightarrow i(t) = K_2 \cdot e^{-\alpha t} \cdot \sin(\beta t), \quad t > \phi$$

$$\frac{d}{dt} i(\phi^+) = \beta \cdot K_2 = \frac{E}{L} \quad \rightarrow K_2 = \frac{E}{\beta \cdot L}$$

$$i(t) = \frac{E}{\beta \cdot L} e^{-\alpha t} \sin(\beta t) \cdot u(t)$$



TL:



$$L \frac{d}{dt} i(t) + R i(t) + v_C(\phi^+) \stackrel{1}{=} \int_{\phi^-}^t i(t') dt' = E u(t), \quad t > \phi^-$$

$t > -\epsilon$

$$L [s I(s) - i(\phi^-)] + R I(s) + \frac{v_C(\phi^-)}{s} + \frac{1}{sC} \cdot I(s) = \frac{E}{s}$$

$$(sL + R + \frac{1}{sC}) I(s) = L i(\phi^-) + \frac{v_C(\phi^-)}{s} + \frac{E}{s}$$

$$I(s) = \frac{E}{s} \cdot \frac{1}{sL + R + \frac{1}{sC}} + \frac{Li(\varphi^*) - \frac{v_c(\varphi^*)}{s}}{sL + R + \frac{1}{sC}}$$

$$= I_{\text{FOR}}(s) + I_{\text{LIB}}(s)$$

Denkweise $I_{\text{FOR}}(s)$

$$I_{\text{FOR}}(s) = \frac{E}{L} \cdot \frac{1}{s^2 + \frac{R}{L}s + \frac{1}{LC}} = \frac{E}{L} \cdot \frac{1}{s^2 + 2\alpha s + \omega_0^2}$$

Pole + i. komplexen mit reellen charakteristische

Case unterdamped:

$$R < R_c = 2\sqrt{\frac{L}{C}}$$

$$\text{Pole: } s_{1,2} = \alpha \pm j\beta$$

$$F(s) = \frac{1}{s^2 + 2\alpha s + \omega_0^2} = \frac{1}{(s-s_1)(s-s_2)} = \frac{1}{[s - (-\alpha + j\beta)][s - (-\alpha - j\beta)]}$$

$$= \frac{A}{s - (-\alpha + j\beta)} + \frac{B}{s - (-\alpha - j\beta)}$$

$$\Rightarrow \text{Residue: } B = A^*$$

$$i(t) = \frac{E}{L} \left[\underbrace{A e^{(-\alpha + j\beta)t}}_{f(t)} + \underbrace{A^* e^{(-\alpha - j\beta)t}}_{f^*(t)} \right] u(t)$$

$$i(t) = \frac{E}{L} 2 \operatorname{Re} \left[A \cdot e^{(-\alpha + j\beta)t} \right] u(t)$$

$$= 2 \frac{E}{L} e^{-\alpha t} \operatorname{Re} \left[A \cdot e^{j\beta t} \right] u(t)$$

$$A = \lim_{s \rightarrow -\alpha + j\beta} (s - (-\alpha + j\beta)) F(s) = \frac{1}{s - (-\alpha - j\beta)} \Big|_{s = -\alpha + j\beta}$$

$$= \frac{1}{-\alpha + j\beta + \alpha + j\beta} = \frac{1}{j2\beta} = -j \cdot \frac{1}{2\beta}$$

$$i(t) = \frac{2E}{L} e^{-\alpha t} \operatorname{Re} \left[-\frac{j}{2\beta} (\cos \beta t + j \sin \beta t) \right] u(t)$$

$$= \frac{E}{\beta L} e^{-\alpha t} \sin(\beta t) u(t)$$

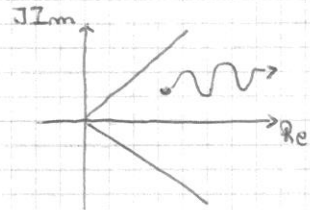
$$I(s) = \frac{E}{L} \cdot \frac{1}{s^2 + s \frac{R}{L} + \frac{1}{LC}}$$

$$i(\infty) = \lim_{s \rightarrow \infty} s I(s) = 0$$

$$\frac{d}{dt} i(\infty) = \lim_{s \rightarrow \infty} s^2 I(s) = \frac{E}{L}$$

Se $I(s)$ contiene e^{-s}

$$i(\infty) = \lim_{s \rightarrow \infty} s I(s) \quad (\operatorname{Re} s \rightarrow +\infty)$$



$$s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2} \quad \text{rad/sec}$$

radici caratteristiche \Leftrightarrow frequenze naturali

Luogo Frequenze Naturali:

$$s^2 + 2\alpha s + \omega_0^2 = 0$$

$$s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2}$$

L, C fissi, Varia $G_p \parallel$
Varia $R_s \Sigma$

Fattore di qualità di un circuito RLC:

$$Q = \frac{\omega_0}{2\alpha}$$

$$\parallel: Q_p = \frac{\omega_0}{2\alpha_p} = \frac{\omega_0}{2 \frac{G_p}{2C}} = \frac{\omega_0 C}{G_p} \propto \frac{1}{G_p}$$

$$\Sigma: Q_s = \frac{\omega_0}{2\alpha_s} = \frac{\omega_0}{2 \frac{R_s}{2L}} = \frac{\omega_0 L}{R_s} \propto \frac{1}{R_s}$$

Sovertammamento: $\alpha > \omega_0$, $Q < 1/2$

Smorzamento critico: $\alpha = \omega_0$, $Q = 1/2$

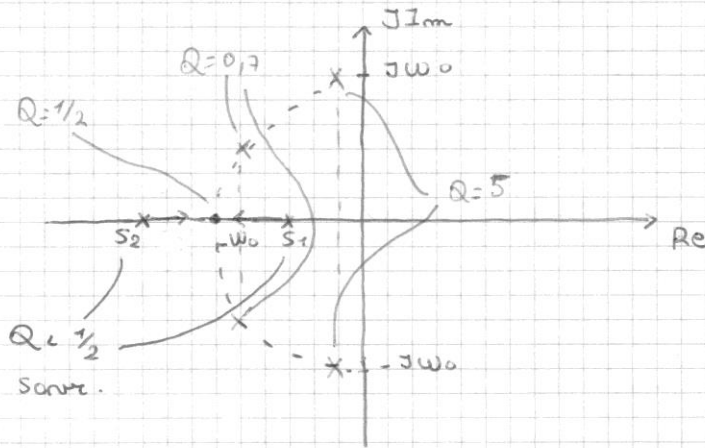
Sottosmorzamento: $\alpha < \omega_0$, $Q > 1/2$

No Perdite: $\alpha = 0$, $Q \rightarrow \infty$

$$S_1 \cdot S_2 = \omega_0^2 = \text{cost}$$

$$S_1 + S_2 = 2\alpha$$

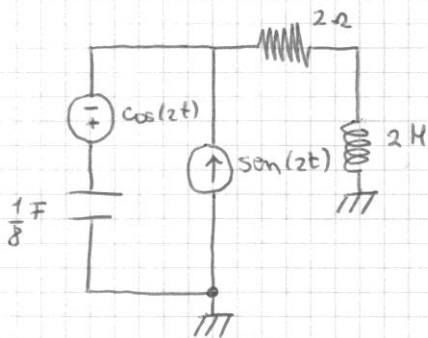
$$\downarrow \sigma_p \quad \downarrow \alpha_p \quad \uparrow Q$$



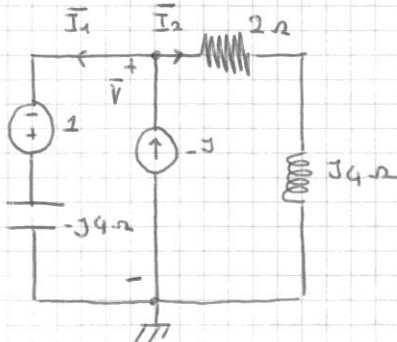
$$Q > 3, \quad S_{1/2} \approx -\frac{\omega_0}{Q} \pm j\omega_0$$

PARTE 2

3/03/2010



Verificare T. Bancarevat per
esercizio in figura.



$$\bar{V} = \frac{-1 \cdot \frac{j}{4} - j}{\frac{j}{4} + \frac{1}{2 + j4}} = \dots = -5.510 \text{ V}$$

$$\bar{V} = -1 + \bar{I}_1 (-j4)$$

$$\bar{I}_1 = \frac{\bar{V} + 1}{-j4} = \dots = \frac{5}{2} - 0 \text{ A}$$

$$-j = \bar{I}_1 + \bar{I}_2 \rightarrow \bar{I}_2 = -j - \bar{I}_1 = -\frac{5}{2} \text{ A}$$

$$\overline{P}_{\text{gem. cor. exogato}} = \frac{1}{2} \overline{V} \overline{I} = \frac{1}{2} (-5 - j10) j = 5 \cdot j \cdot \frac{5}{2} \text{ VA}$$

$$\overline{P}_{\text{gem. tem. exogato}} = \frac{1}{2} \cdot \overline{I} \cdot \overline{I}^* = \frac{1}{2} \cdot \left(\frac{5}{2} + j\right) \cdot \left(\frac{5}{2} - j\right) = \frac{5}{4} \cdot \frac{29}{2} \text{ VA}$$

$$\overline{P}_{\text{gem. xi exogato}} = \frac{25}{4} - j2$$

$$P_R = \frac{1}{2} \cdot 2 \cdot I_{2H}^2 = \frac{25}{4} \text{ Watt}$$

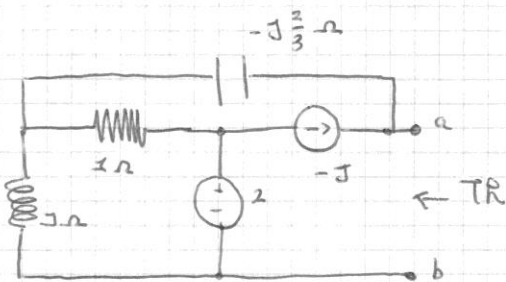
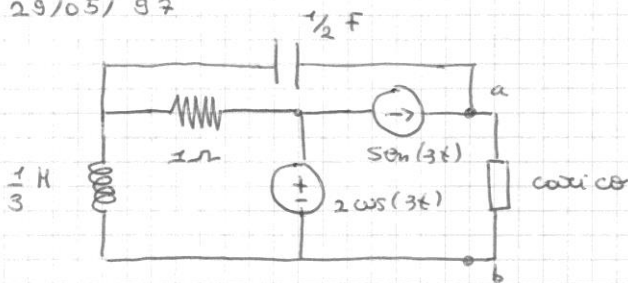
$$Q_L = \frac{1}{2} X_L I_{2H}^2 = \frac{1}{2} \cdot 4 \cdot \frac{25}{4} = \frac{25}{2} \text{ VAR}$$

$$Q_C = -\frac{1}{2} X_C I_{2H}^2 = -\frac{1}{2} \cdot 4 \cdot \frac{29}{4} = -\frac{29}{2} \text{ VAR}$$

$$Q_L + Q_C = -2 \text{ VAR}$$

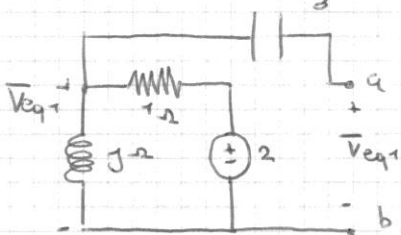
OK! Verificator.

29/05/97

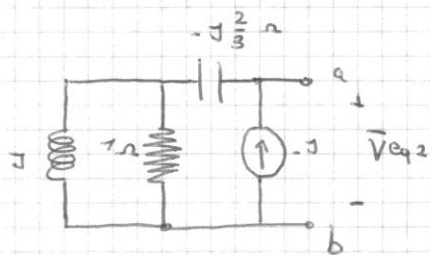


$$\overline{Z}_{eq} = -j \frac{2}{3} + 1 \parallel j = -j \frac{2}{3} + \frac{j}{1+j} = \dots = \frac{1}{2} - j \frac{1}{6}$$

P.s.e. $-j \frac{2}{3} \Omega$

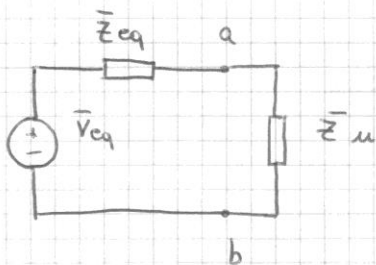


$$\overline{V}_{eq1} = \frac{2j}{1+j} = \frac{2j(1-j)}{2} = 1 + j \text{ V}$$



$$\begin{aligned}\bar{V}_{eq2} &= -j \cdot \bar{Z}_{eq1} = -j \left(\frac{1}{2} - j\frac{1}{6} \right) \\ &= -\frac{1}{6} - j \cdot \frac{1}{2} \text{ V}\end{aligned}$$

$$\bar{V}_{eq} = \bar{V}_{eq1} + \bar{V}_{eq2} = \frac{5}{6} + j\frac{1}{2} \text{ V.}$$



$$\bar{Z}_L = \bar{Z}_{eq}^* = \frac{1}{2} + j\frac{1}{6} \Omega.$$

$$\begin{aligned}P_d = P_{L, \text{MAX}} &= \frac{1}{8} \cdot \frac{V_{eq, \text{eff}}^2}{R_{eq}} \\ &= \frac{1}{8} \cdot \frac{\frac{25}{36} + \frac{1}{4}}{\frac{1}{2}} = 0,236 \text{ W.}\end{aligned}$$

$$I_f(s) = \frac{E}{L} \frac{1}{s^2 + \frac{R}{L}s + \frac{1}{LC}} \xrightarrow{\mathcal{L}^{-1}} i(t) = \frac{E}{L} \frac{1}{s_1 - s_2} [e^{s_1 t} - e^{s_2 t}] u(t)$$

Scorcio: $R > R_c = 2\sqrt{\frac{L}{C}}$ $s_{1,2}$, reali neg. distinte

Smorz. Critico: $R = R_c$ $s_1 = s_2 = -\alpha = -\omega_0$

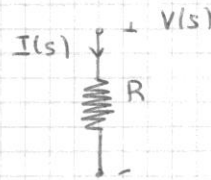
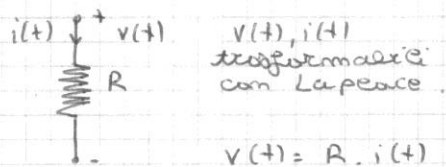
$$I_f(s) = \frac{E}{L} \frac{1}{(s+\alpha)^2} \xrightarrow{\mathcal{L}^{-1}} i_f(t) = \frac{E}{L} t e^{-\alpha t} u(t)$$

Metodo Simmetrico di Laplace per circuiti LTI.

- 1) Relazioni costitutive di R, L, C nel dominio di s;
- 2) Leggi di Kirchhoff, nel dominio di s;

→ circuito simmetrico nel dominio di s.

R ideale



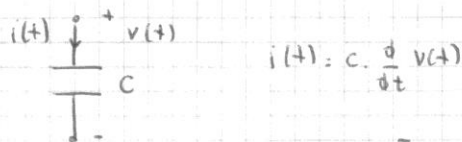
$$V(s) = R \cdot I(s)$$

$$[V(s)] = \text{Volt} \cdot \text{sec}$$

$$[I(s)] = \text{Ampere} \cdot \text{sec}$$

DT.

C ideale



$$I(s) = C [sV(s) - v(\phi^-)]$$

DT.

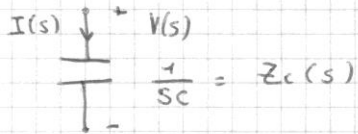
- 1) C scarica a $t = \phi^-$, $v(\phi^-) = \phi$

$$I(s) = \frac{V(s)}{\frac{1}{sC}} \quad Z_c(s) = \frac{1}{sC} : \text{impedenza di C in Dominio di s.}$$

$$\left[\frac{1}{sC} \right] = \Omega \rightarrow I(s) = \frac{V(s)}{Z_c(s)} : \text{Legge di Ohm simmetrica di C.}$$

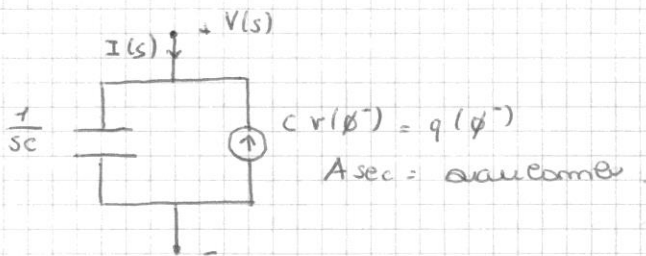
$$y_c(s) = sC = \frac{1}{z_c(s)} : \text{Admittenza di } C.$$

C scarico a $t = \phi^-$ è un'impedenza di valore $\frac{1}{sC}$.

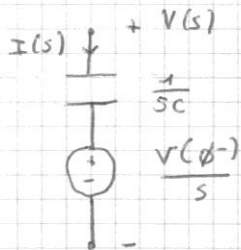


2) C carico a $t = \phi^-$

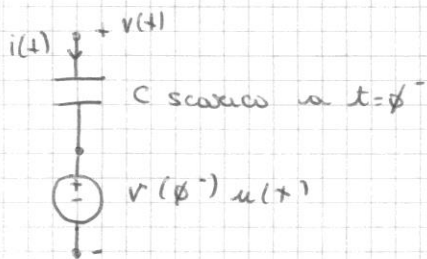
$$I(s) = sC V(s) - C v(\phi^-)$$



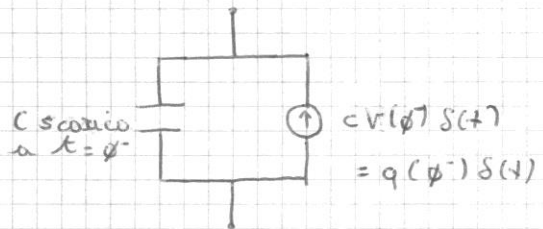
$$V(s) = \frac{1}{sC} \cdot I(s) + \frac{v(\phi^-)}{s}$$



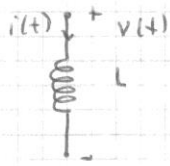
C carico a $t = \phi^-$



C carico a $t = \phi^-$



L ideale



$$v(t) = L \cdot \frac{d}{dt} i(t)$$

$$V(s) = L [s \cdot I(s) - i(\phi^-)]$$

1) L scarico a $t = \phi^-$, $i(\phi^-) = \phi$.

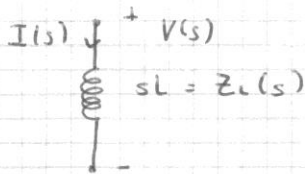
$$V(s) = sL \cdot I(s), \quad Z_L(s) = sL \quad \text{: impedenza di L in dominio di } s.$$

$$[Z_L(s)] = sL$$

$$I(s) = \frac{V(s)}{Z_L(s)} = \frac{V(s)}{sL}$$

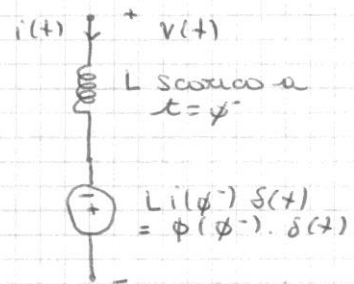
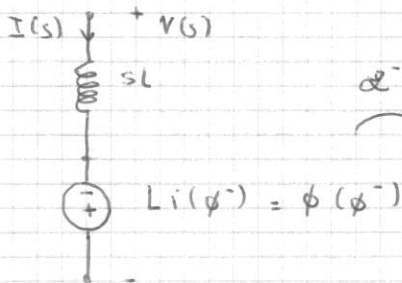
$$Y_L(s) = \frac{1}{sL} \quad \text{ammettanza di L}$$

L scarico a $t = \phi^-$ è un'impedenza di valore sL .

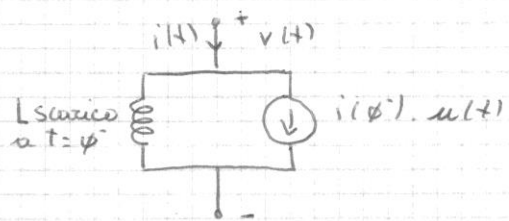
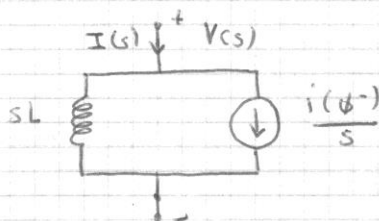


2) L carico a $t = \phi^-$

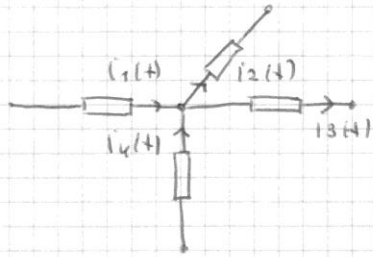
$$V(s) = sL I(s) - L i(\phi^-)$$



$$I(s) = \frac{V(s)}{sL} + \frac{i(\phi^-)}{s}$$



Leggi di Kirchhoff nel dominio di s .



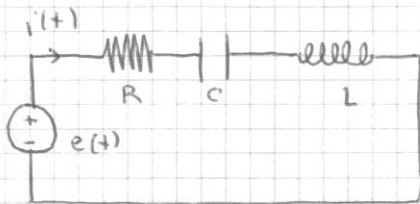
$$i_1(t) - i_2(t) - i_3(t) + i_4(t) = 0$$

$$I_1(s) - I_2(s) - I_3(s) + I_4(s) = 0$$

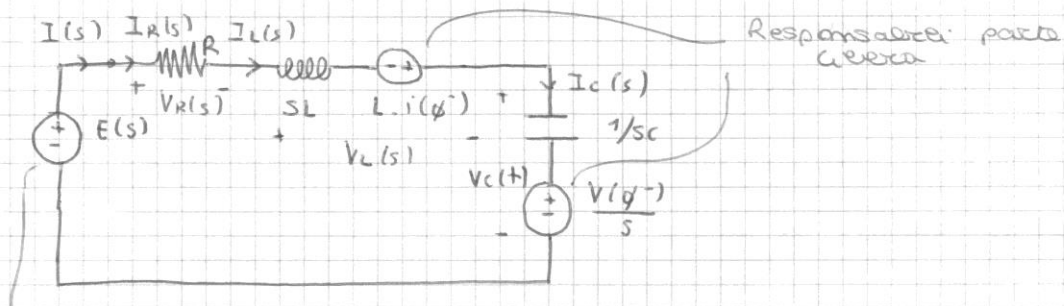
T.L. di Correnti Saldatura KI.

T.L. di Tensioni Saldatura KV.

Esercizio Testico



? $I(s)$



Responsabile parte generata

$$KV: E(s) = V_R(s) + V_L(s) + V_C(s)$$

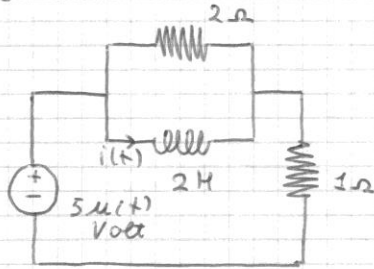
$$= R \cdot I_R(s) + sL \cdot I_L(s) - Li(\phi^-) + \frac{1}{sC} \cdot I_C(s) + \frac{V(\phi^-)}{s}$$

$$KI: I(s) = I_R(s) = I_L(s) = I_C(s)$$

$$\rightarrow \left(R + sL + \frac{1}{sC} \right) I(s) = E(s) + Li(\phi^-) - \frac{V(\phi^-)}{s}$$

Da cui ricavare $I(s)$

Esercizio:



$$i(\phi^-) = 2 \text{ Amp.}$$

$$? i(t), t > \phi$$

1) DT

2) TL

$$i(\phi^+) = i(\phi^-) = 2 \text{ Amp.}$$

$t > \phi$

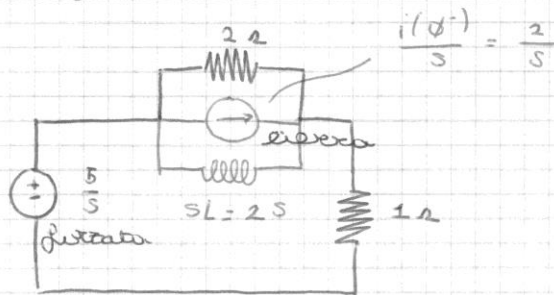
$$i(t) = \underbrace{i(\phi^-)}_2 e^{-t/\tau_{eq}} + \underbrace{i(\infty)}_5 (1 - e^{-t/\tau_{eq}})$$

$$\frac{L}{R_{eq}} = 3 \text{ sec}$$

$$i(t) = \underbrace{2 e^{-t/3}}_{i_e(t)} + \underbrace{5(1 - e^{-t/3})}_{i_f(t)}, t > \phi$$

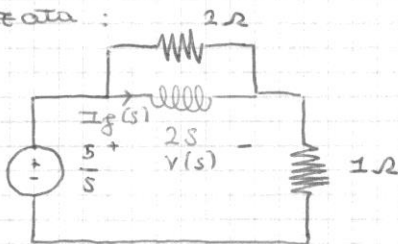
N.B. nel caso non si analizza var di stato e due parti non sono rispettivamente parte forzata e parte libera

Circuito Simbolico



$$i(\phi^-) = \frac{2}{5}$$

Forzata:



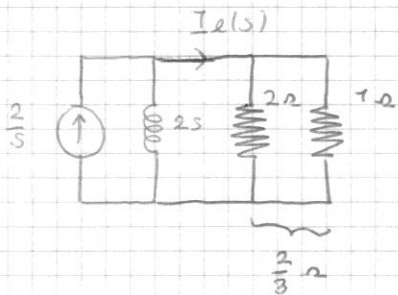
$$Z_{||}(s) = \frac{1s}{2+2s} = \frac{2s}{s+1}$$

$$V(s) = \frac{5}{s} \cdot \frac{Z_{||}(s)}{Z_{||}(s) + 1} = \frac{5}{s} \cdot \frac{\frac{2s}{s+1}}{\frac{2s}{s+1} + 1}$$

$$= \frac{5}{s} \cdot \frac{2s}{3s+1} = \frac{10}{3} \cdot \frac{1}{s + \frac{1}{3}}$$

$$I_f(s) = \frac{V(s)}{2s} = \frac{5}{2s} \cdot \frac{1}{3} \cdot \frac{1}{s + \frac{1}{3}} = \frac{5}{8} \left(\frac{3}{s} - \frac{3}{s + \frac{1}{3}} \right) = \frac{5}{s} - \frac{5}{s + \frac{1}{3}}$$

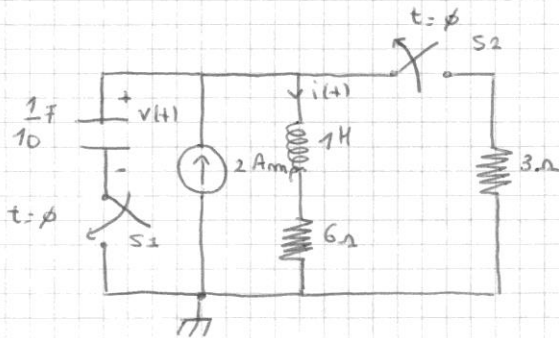
$$i_g(t) = 5u(t) - 5e^{-\frac{t}{3}}u(t)$$



$$I_2(s) = \frac{2}{s} \cdot \frac{\frac{3}{2}}{\frac{3}{2} + \frac{1}{2s}} = 2 \cdot \frac{1}{s + \frac{1}{3}}$$

$$i_2(t) = 2e^{-t/3}u(t)$$

04/07/2011



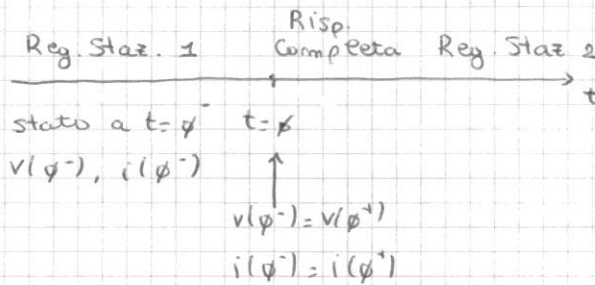
S_2 aperto da lungo tempo
 si chiude a $t = \phi$
 S_2 chiuso da lungo tempo
 si apre a $t = \phi$.

$$v(\phi^-) = 2V$$

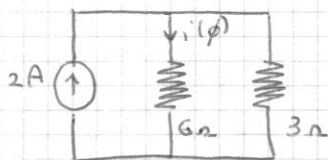
$$v(\phi^-) = 2V$$

? $i(t)$, $t > \phi$

- 1) me e D.T.
- 2) con T.L.

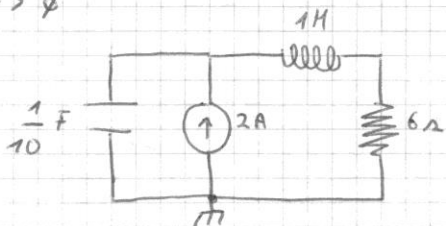


$$v(\phi^-) = 2V = v(\phi^+)$$



$$i(\phi^-) = \frac{2}{3}A = i(\phi^+)$$

$t > \phi$



? che tipo di circuito è per $t > \phi$

In soluzione libera RLC serie I° ordine

↑
Spenti i gen. xi

Completa:

$$C = TC + \text{Regime Stat. 2}$$

$$i(t) = \dots + i(\infty), t > \phi$$

? In che caso siamo

$$R_c = 2\sqrt{\frac{L}{C}} = 2\sqrt{10}$$

$$R = 6 \Omega < R_c = 2\sqrt{10}$$

→ Caso sottosmorzato

$s_{1,2}$ complessi, parte reale neg., coniugati

$$s_{1,2} = -\alpha_s \pm j\beta$$

$$\alpha_s = \frac{R_s}{2L} = 3 \text{ rad/sec}, \quad \beta = \sqrt{\omega_0^2 - \alpha_s^2} = 1 \text{ rad/sec}$$

$$\omega_0 = \frac{1}{\sqrt{LC}} = \sqrt{10} \text{ rad/sec}$$

$s_{1,2} = -3 \pm j$: radici caratteristiche

$$i(t) = K_1 e^{-3t} \cos(t) + K_2 e^{-3t} \sin(t) + i(\infty), t > \phi$$

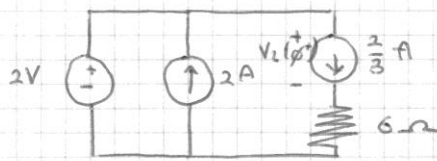
$$i(\infty) = 2A \rightarrow \text{cc. al posto di } L \\ \text{cc. al posto di } C$$

$$\begin{cases} i(t) = K_1 e^{-3t} \cos(t) + K_2 e^{-3t} \sin(t) + 2, t > \phi. \\ i(\phi^+) = \frac{2}{3} A \\ \frac{d}{dt} i(\phi^+) = ? = -2A/\text{sec} \end{cases}$$

$$\rightarrow K_1 + 2 = \frac{2}{3} \rightarrow K_1 = -\frac{4}{3}$$

$$-3K_1 + K_2 = -2 \rightarrow K_2 = -6$$

$$t = \varphi^+$$



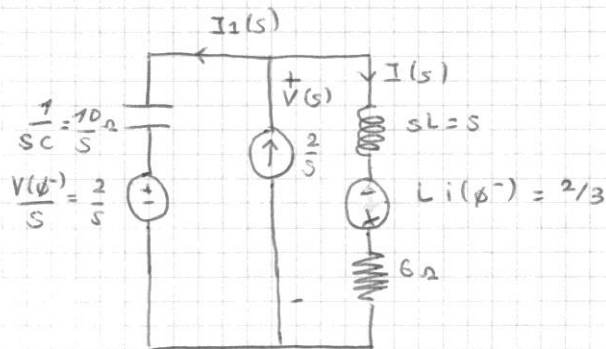
$$V_L(\varphi^+) = L \cdot \frac{d}{dt} i(\varphi^+), \quad L = 1$$

$$= \frac{d}{dt} i(\varphi^+)$$

$$V_L(\varphi^+) + 6 \cdot \frac{2}{3} - 2 = \varphi \quad \rightarrow \quad V_L = \varphi^+ = -2V = \frac{d}{dt} i(\varphi^+)$$

Verifica con Trasformata di Laplace

$$t > \varphi$$



$$V(s) = \frac{\frac{2}{s} \cdot \frac{3}{10} + \frac{2}{s} - \frac{2}{3} \cdot \frac{1}{s+6}}{\frac{s}{10} + \frac{1}{s+6}}$$

$$= \dots$$

$$\frac{2}{s} = I_1(s) + I(s)$$

$$s I(s) - \frac{2}{3} + 6 \cdot I(s) - \frac{2}{s} - \frac{10}{s} I_1(s) = \varphi$$

$$s I(s) - \frac{2}{3} + 6 \cdot I(s) - \frac{2}{s} - \frac{10}{s} \left(\frac{2}{s} - I(s) \right) = \varphi$$

$$I(s) \left(s + 6 + \frac{10}{s} \right) - \frac{2}{3} - \frac{2}{s} - \frac{20}{s^2} = \varphi$$

$$I(s) = \frac{\frac{2}{3} + \frac{2}{s} + \frac{20}{s^2}}{\frac{s^2 + 6s + 10}{s}} = \frac{\frac{2s^2 + 6s + 60}{3s^2}}{\frac{s^2 + 6s + 10}{s}} = \frac{2s^2 + 6s + 60}{3s(s^2 + 6s + 10)}$$

$$I(s) = \frac{2}{3} \cdot \frac{s^2 + 3s + 30}{s(s^2 + 6s + 10)} \quad \leftarrow F(s)$$

$$s_{1,2} = -3 \pm \sqrt{-1} = -3 \pm j$$

$$F(s) = \frac{A}{s} + \frac{B}{s - (-3+j)} + \frac{B^*}{s - (-3-j)}$$

OK sono le radici caratteristiche

$$A = \lim_{s \rightarrow 0} s F(s) = 3$$

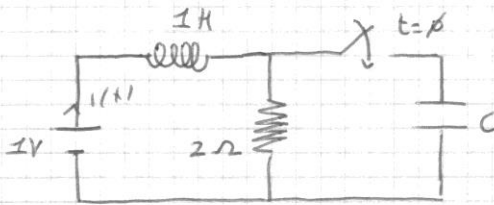
$$B = \lim_{s \rightarrow -3+j} (s - (-3+j)) F(s) = \dots = -1 + j \frac{9}{2}$$

$$i(t) = 2 \cdot u(t) + \frac{1}{3} \cdot 2 \operatorname{Re} [B e^{(-3+j)t}] u(t)$$

$$= 2u(t) + \frac{4}{3} \operatorname{Re} \left[(-1 + j\frac{9}{2}) e^{jt} \right] e^{-3t} \cdot u(t)$$

$$= 2u(t) + \frac{4}{3} e^{-3t} \left(-\cos(t) - \frac{9}{2} \sin(t) \right) u(t)$$

Esercizio



$$t > t_0, \omega_0 = 2 \alpha$$

C inizialmente scarica

? $i(t)$, $t > t_0$ me e DT.

$t > t_0$: RLC Parallelo

$$\omega_0 = \frac{1}{\sqrt{LC}} = 2 \alpha_{||}, \text{ dove } \alpha_{||} = \frac{G^2}{2C} = \frac{1/2}{2C} = \frac{1}{4C}$$

$$\cancel{2} \cdot \frac{1}{\cancel{2} C} = \frac{1}{\sqrt{C}} \rightarrow C = \frac{1}{4} \text{ F}$$

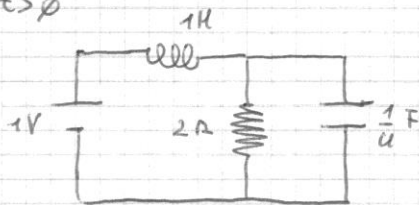
$t = t_0^-$

$$V(t_0^-) = 0 = V(t_0^+)$$

$$i(t_0^-) = \frac{1}{2} \text{ A} = i(t_0^+)$$

$$i(t) = TC + R. \text{ staz.}, \quad R. \text{ staz.} = \frac{1}{2} \text{ A.}$$

$t > t_0$



$$G_L G_C = 2 \sqrt{\frac{C}{L}}$$

$$\frac{1}{2} \leq 2 \sqrt{\frac{1/4}{1}} \rightarrow \frac{1}{2} \leq 1.$$

Caso sottosmorzato

$$s_{1,2} = -\alpha_{||} \pm j\beta$$

$$\alpha_{||} = \frac{G^2}{2C} = \frac{1/2}{1/2} = 1 \text{ rad/sec}$$

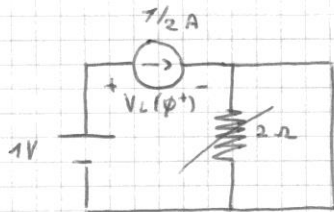
$$\omega_0 = \frac{1}{\sqrt{LC}} = 2 \text{ rad/sec}$$

$$\rightarrow s_{1,2} = -1 \pm \sqrt{3} j$$

$$\beta = \sqrt{\omega_0^2 - \alpha_{||}^2} = \sqrt{3} \text{ rad/sec}$$

$$\begin{cases} i(t) = K_1 e^{-t} \cos(\sqrt{3}t) + K_2 e^{-t} \sin(\sqrt{3}t) + 1/2, t > \phi \\ i(\phi^+) = 1/2 \\ \frac{d}{dt} i(\phi^+) = ? = 1 \end{cases}$$

$$t = \phi^+$$



$$\begin{aligned} V_L(\phi^+) &= L \cdot \frac{d}{dt} i(\phi^+) \\ &= \frac{d}{dt} i(\phi^+) = 1 \end{aligned}$$

$$\frac{1}{2} = K_1 + \frac{1}{2} \rightarrow K_1 = \cancel{0}$$

$$-K_1 + \sqrt{3} \cdot K_2 = 1 \rightarrow K_2 = \frac{1}{\sqrt{3}}$$

$$i(t) = \frac{1}{\sqrt{3}} e^{-t} \sin(\sqrt{3}t) + \frac{1}{2}, t > \phi$$

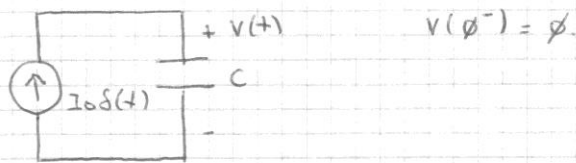
Con Laplace : Ricominciare !

$$I(s) = \frac{1}{2} \cdot \frac{1}{s} \cdot \frac{s^2 + 4s + 4}{s^2 + 2s + 4}$$

$$i(\infty) = \lim_{s \rightarrow 0} sI(s) = \frac{4}{8} = \frac{1}{2}$$

22/05/2015

C con eccitazione impulsiva



$[I_0] = A \cdot sec = Coulomb$

$i(t) = C \cdot \frac{d}{dt} v(t) = I_0 \delta(t)$

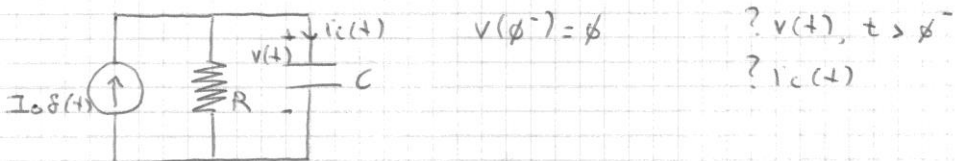
$C \int_{\phi^-}^{\phi^+} \frac{d}{dt} v(t) = I_0 \int_{\phi^-}^{\phi^+} \delta(t) dt$

$C [v(\phi^+) - \cancel{v(\phi^-)}] = I_0 \cdot 1 \rightarrow v(\phi^+) = \frac{I_0}{C} \text{ Volt}$

è quindi una discontinuità.

Impulso di corrente in C \Rightarrow discontinuità var. di stato

RC con eccitazione impulsiva



(c.c.)

il condensatore è scarico quindi la corrente tenderà a pararsi di lei

$I_0 \delta(t), t > \phi^-$

$I_0 \delta(t) = C \cdot \frac{d}{dt} v(t) + \frac{v(t)}{R}, t > \phi^-$

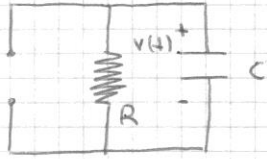
$C [v(\phi^+) - \cancel{v(\phi^-)}] + \frac{1}{R} \int_{\phi^-}^{\phi^+} v(t) dt = I_0 \cdot 1$

$v(\phi^+) = \frac{I_0}{C} \text{ Volt}$

funzione emmetata integrale fra $(-\epsilon, \epsilon)$.

$$(\phi^-, \phi^+) \rightarrow v(\phi^+) = \frac{I_0}{C}$$

$t > \phi$



$$v(t) = v(\phi^+) e^{-t/RC}, \quad t > \phi$$

C si scarica su R.

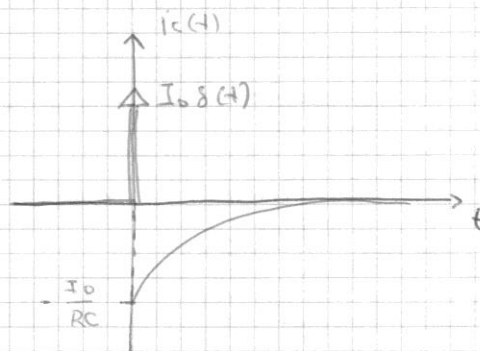
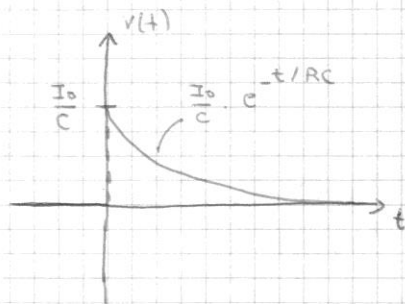
$$v(t) = \frac{I_0}{C} \cdot e^{-t/RC} \cdot u(t)$$

$$i_C(t) = C \cdot \frac{d}{dt} v(t) = \cancel{C} \cdot \frac{d}{dt} \left(\frac{I_0}{\cancel{C}} \cdot e^{-t/RC} \cdot u(t) \right)$$

derivata nel senso delle funzioni impulsive

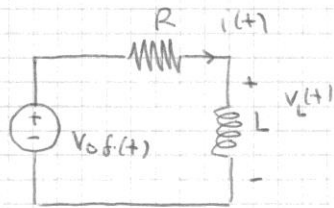
$$= -\frac{I_0}{RC} \cdot e^{-t/RC} \cdot u(t) + I_0 \delta(t)$$

↑
in quanto $v(t)$ discontinua in ϕ .



inizialmente tutta la corrente passa su C, poi C si scarica su R.

RL con eccitazione impulsiva



$i(\phi^-) = 0$? $i(t)$, $v_L(t)$

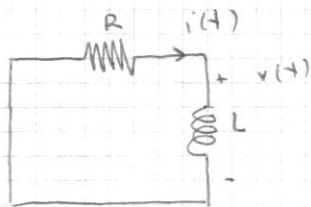
$(\phi^-, \phi^+) \rightarrow v_L(t) \approx V_0 \delta(t)$ in quanto L scarica
 è un c.a.

$$L \cdot \frac{d}{dt} i(t) \approx V_0 \delta(t)$$

$$L [i(\phi^+) - i(\phi^-)] \approx V_0 \cdot 1$$

$$i(\phi^+) \approx \frac{V_0}{L}$$

$t > \phi$



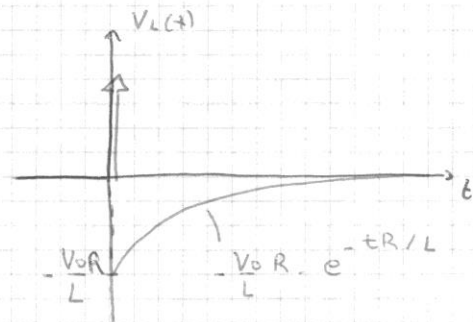
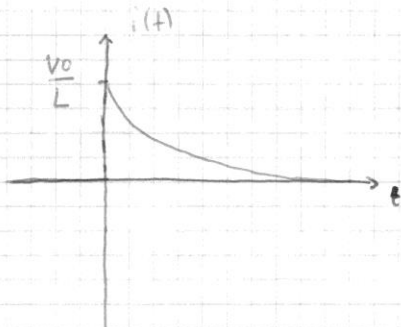
scarica di L su R

$$i(t) = i(\phi^+) \cdot e^{-t \cdot R/L}, \quad t > \phi$$

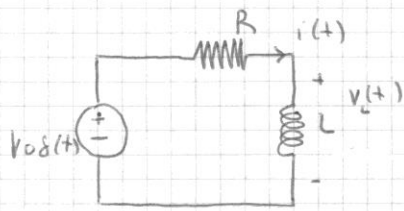
$$= \frac{V_0}{L} \cdot e^{-t \cdot R/L}, \quad t > \phi$$

$$i(t) = \frac{V_0}{L} \cdot e^{-t \cdot R/L} \cdot u(t)$$

$$v_L(t) = L \cdot \frac{d}{dt} i(t) = V_0 \delta(t) - \frac{V_0 \cdot R}{L} \cdot e^{-t \cdot R/L} \cdot u(t)$$



Verifica con T.L.



$$i(\phi^-) = \phi$$

$$L \frac{d}{dt} i + Ri = V_0 \delta(t), \quad t > \phi$$

$$\int_{\phi^-}^{+\infty} (L \frac{d}{dt} i + Ri) e^{-st} dt = \int_{\phi^-}^{+\infty} V_0 \delta(t) e^{-st} dt$$

$$sL I(s) - L i(\phi^-) + RI(s) = V_0$$

$$(sL + R) I(s) = V_0$$

$$I(s) = \frac{V_0}{sL + R} = \frac{V_0}{L} \cdot \frac{1}{s + \frac{R}{L}}$$

$$i(t) = \frac{V_0}{L} e^{-tR/L} \cdot u(t), \quad \text{verificato!}$$

$$i(\phi^+) = \lim_{s \rightarrow \infty} s I(s) = \frac{V_0}{L}$$

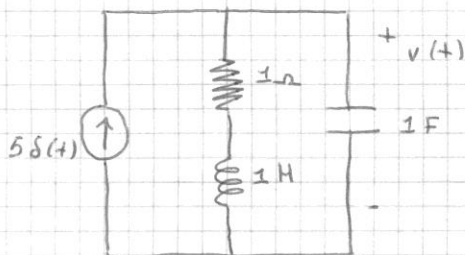
$$v(t) = L \frac{d}{dt} i(t)$$

$$V(s) = s \cdot L I(s) - L i(\phi^-)$$

$$V(s) = V_0 \cdot \frac{s}{s + \frac{R}{L}} = V_0 \left(1 - \frac{\frac{R}{L}}{s + \frac{R}{L}} \right)$$

$$v(t) = V_0 \delta(t) - V_0 \frac{R}{L} e^{-tR/L} \cdot u(t), \quad \text{verificato!}$$

16/12/1996 Per Casa.



? $v(t), t > \phi$ sup. forzato

$$v(\phi^-) = \phi$$

$$i_L(\phi^-) = \phi$$

1) p.T.

2) T.L.

$$v(t) = \frac{10}{\sqrt{3}} e^{-\frac{1}{2}t} \cos\left(\frac{\sqrt{3}}{2}t - \frac{\pi}{6}\right)$$

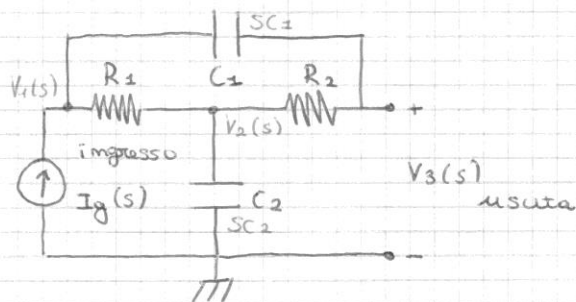
Funzioni di Rete di un circuito LTI

1 ingresso, tensione impressa da gen. indip. di tensione o corrente impressa da gen. indip. di corrente.

1 uscita: tensione o corrente che interessa

$$H(s) = \frac{\text{T.L. uscita (sup. forzata)}}{\text{T.L. ingresso}}$$

L_i, C_i , accolti a $t=0^-$



$$? H(s) = \frac{V_3(s)}{I_g(s)}$$

$$\vec{Y}(s) \cdot \vec{V}(s) = \vec{I}(s)$$

↑
matrici
ammittenze

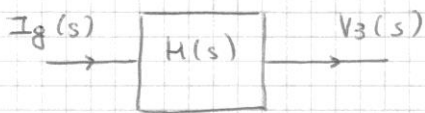
$$\begin{pmatrix} G_1 + sC_1 & -G_2 & -sC_1 \\ -G_2 & G_1 + G_2 + sC_2 & -G_2 \\ -sC_1 & -G_2 & G_1 + sC_1 \end{pmatrix} \begin{pmatrix} V_1(s) \\ V_2(s) \\ V_3(s) \end{pmatrix} = \begin{pmatrix} I_g(s) \\ \emptyset \\ \emptyset \end{pmatrix}$$

$$V_3(s) = \frac{\det \begin{pmatrix} G_1 + sC_1 & -G_2 & I_g(s) \\ -G_2 & G_1 + G_2 + sC_2 & \emptyset \\ -sC_1 & -G_2 & \emptyset \end{pmatrix}}{\det \vec{Y}(s)}$$

$$= I_g(s) \frac{\det \begin{pmatrix} -G_2 & G_1 + G_2 + sC_2 \\ -sC_1 & -G_2 \end{pmatrix}}{\det \vec{Y}(s)}$$

$H(s)$

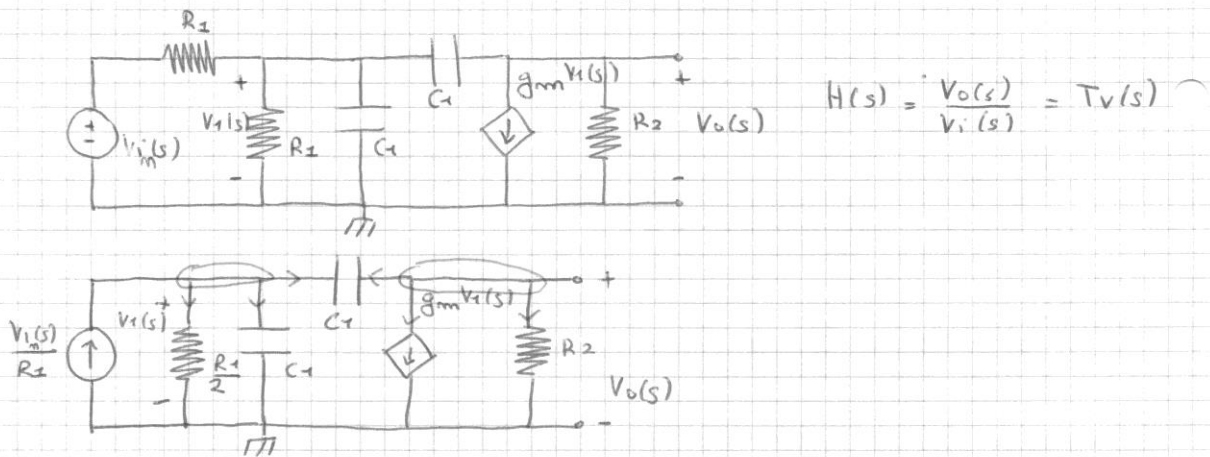
$$H(s) = \frac{\det(\dots)}{\det \vec{Y}(s)} = \frac{s^2 + \left(\frac{G_1}{C_2} + \frac{G_2}{C_2}\right)s + \frac{G_1 G_2}{C_1 C_2}}{(G_1 + G_2)s^2 + \frac{G_1 G_2}{C_1} s}$$



$H(s) = Z_T(s)$ impedanza di Trasferimento

Funzione di Rete: razionale, a coefficienti reali e non dipendente da grandezza imposta dall' eccitazione

Es. Transistor ad alta frequenza.



$$H(s) = \frac{V_o(s)}{V_i(s)} = T_V(s)$$

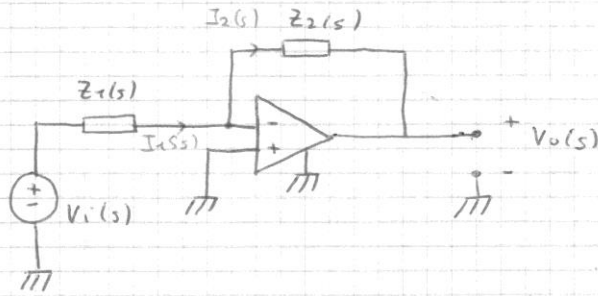
$$\begin{cases} V_1(s) \frac{R_1}{2} + V_1(s) s C_1 + (V_1(s) - V_o(s)) s C_2 = \frac{V_{in}(s)}{R_1} \\ (V_o(s) - V_1(s)) s C_2 + g_m V_1(s) + \frac{V_o(s)}{R_2} = 0 \end{cases}$$

$$\begin{pmatrix} \frac{2}{R_1} + 2sC_1 & -sC_2 \\ -sC_2 + g_m & sC_2 + \frac{1}{R_2} \end{pmatrix} \begin{pmatrix} V_1(s) \\ V_o(s) \end{pmatrix} = \begin{pmatrix} \frac{V_{in}(s)}{R_1} \\ 0 \end{pmatrix}$$

$$H(s) = \frac{V_o(s)}{V_{in}(s)} = \frac{\frac{C_2}{R_1} s - \frac{g_m}{R_1}}{3C_2^2 s^2 + \left(2\frac{C_2}{R_1} + C_2 g_m\right) s + \frac{2}{R_1 R_2}}$$

Per ogni valore dei parametri il sistema è asintoticamente stabile.

Funzioni di Rete Circuiti con A.O.



$$? T_V(s) = \frac{V_o(s)}{V_i(s)} = - \frac{Z_2(s)}{Z_1(s)}$$

$$I_1(s) = I_2(s)$$

$$\frac{V_i(s) - \phi}{Z_1(s)} = \frac{\phi - V_o(s)}{Z_2(s)}$$

$$Z_1(s) = R, \quad Z_2(s) = C$$

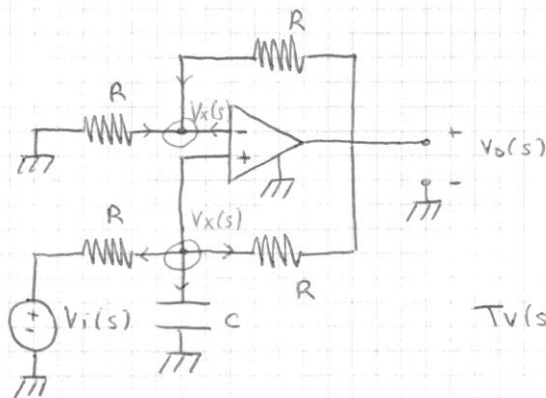
$$T_V(s) = - \frac{Z_2(s)}{Z_1(s)} = - \frac{1}{sRC} = \frac{V_o(s)}{V_i(s)}$$

$$V_o(s) = - \frac{1}{sRC} \cdot V_i(s)$$

$$V_o(t) = - \frac{1}{RC} \int V_i(t) dt \quad : \text{Integratore invertente.}$$

Se scambio R con C ottengo un derivatore.

Integratore non Invertente (di DEBOO).



$$T_V(s) = \frac{V_o(s)}{V_i(s)} = \frac{2}{RCs}$$

2 incognite: $V_o(s)$, $V_x(s)$

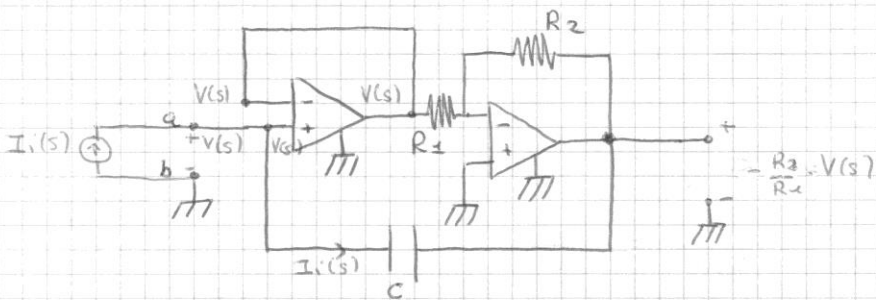
2 K.I.

$$V_x(s) = \frac{V_o(s)}{2}$$

$$\frac{\frac{V_o(s)}{2} - V_i(s)}{R} + \frac{\frac{V_o(s)}{2} - V_o}{R} + \frac{V_o}{2} \cdot sC = 0$$

$$V_o(s) = \frac{2}{R \cdot sC} \cdot V_i(s)$$

moltiplicatore di capacità



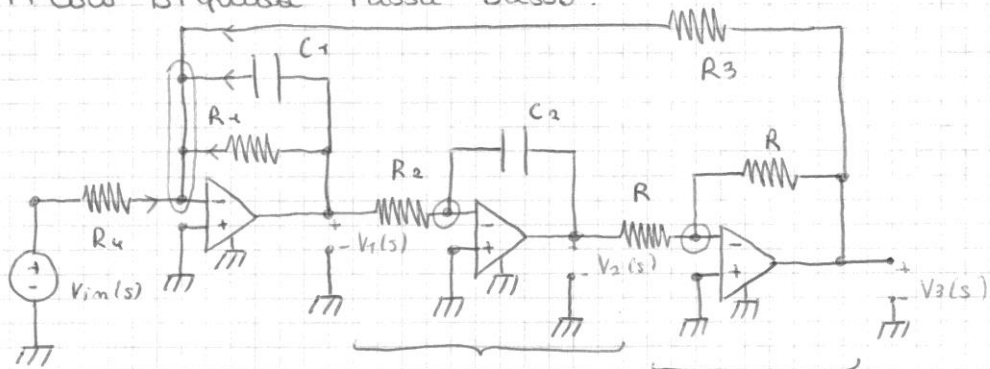
$$? Z(s) = \frac{V(s)}{I(s)}$$

$$I_i(s) = \left[V(s) - \left(-\frac{R_2}{R_1} V(s) \right) \right] sC = V(s) \left[1 + \frac{R_2}{R_1} \right] sC$$

$$Z(s) = \frac{V(s)}{I(s)} = \frac{1}{\left(1 + \frac{R_2}{R_1} \right) sC} = \frac{1}{s \cdot C_{eq}}, \quad C_{eq} = \left(1 + \frac{R_2}{R_1} \right) C$$

mantengo la costante su C costante ma aumento la d.d.p. ai capi di C.

Filtro Biquad Passa Basso.



Integratore
Invertente Amp. Inv.

$$? T_V(s) = \frac{V_3(s)}{V_{in}(s)}$$

3 incognite : $V_1(s), V_2(s), V_3(s)$

3 KI

$$\begin{cases} V_2(s) = -\frac{1}{sR_2C_2} V_1(s) \rightarrow V_1 = -sR_2C_2 V_2 = sR_2C_2 V_3 \\ V_3(s) = -V_2(s) \\ \frac{V_{in}(s)}{R_4} + \frac{V_1(s)}{R_1} + V_1(s) \cdot sC_1 + \frac{V_3(s)}{R_3} = 0 \end{cases}$$

$$H(s) = T_V(s) = -\frac{1}{R_2R_4C_1C_2} \frac{1}{s^2 + s \cdot \frac{1}{R_1C_1} + \frac{1}{R_2R_3C_1C_2}}$$

Filtro stabile!

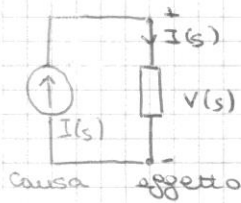
$$T_V(s) = -\frac{K}{s^2 + as + b} \quad \text{filtro passa basso del secondo ordine}$$

$\frac{V_2(s)}{V_{in}(s)}$: Filtro Passa Banda!

Cenni su Bipoli:

27/05/2015

L, C scaturiti a $t = 0^-$.



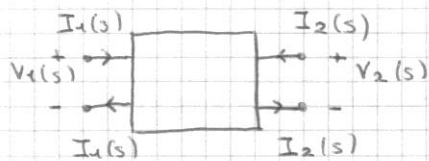
$$Z(s) = \frac{V(s)}{I(s)}, \quad V(s) = Z(s) \cdot I(s)$$

↑
contx. im
corrente

relazione costitutiva

Se contx. im tensione: $Y(s) = \frac{I(s)}{V(s)}$
 $I(s) = Y(s) \cdot V(s)$

Quadrupolo (Rete 2 Porte)



Grandezze di Porta:
 $V_1(s), V_2(s), I_1(s), I_2(s)$

Relazioni costitutive reti due porte:

2 legami indip. ti che la rete sta a dispo. fra le
quelle tre grandezze di porta V_1, V_2, I_1, I_2 .

Grandezze ind. ti : I_1, I_2
(Cause)

Grandezze dep. ti : V_1, V_2
(Effetti)

$$\begin{cases} V_1(s) = Z_{11}(s) I_1(s) + Z_{12}(s) I_2(s) \\ V_2(s) = Z_{21}(s) I_1(s) + Z_{22}(s) I_2(s) \end{cases}$$

↑
sottoposizione dagli effetti

Rappresentazione
a parametri Z .

Cause : V_1, V_2

Effetti : I_1, I_2

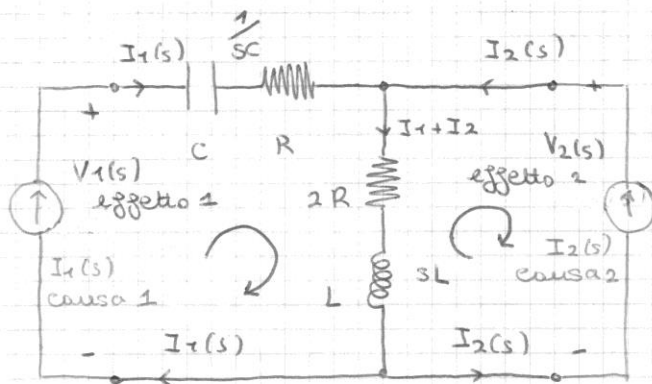
$$\begin{cases} I_1(s) = Y_{11}(s) \cdot V_1(s) + Y_{12}(s) \cdot V_2(s) \\ I_2(s) = Y_{21}(s) \cdot V_1(s) + Y_{22}(s) \cdot V_2(s) \end{cases} \quad \begin{array}{l} \text{Rappresentazione} \\ \text{a parametri } Y. \end{array}$$

Cause : I_1, V_2

Effetti : V_1, I_2

$$\begin{cases} V_1 = R_{11} \cdot I_1 + R_{12} \cdot V_2 \\ I_2 = R_{21} \cdot I_1 + R_{22} \cdot V_2 \end{cases} \quad \begin{array}{l} \text{Rappresentazione a} \\ \text{parametri } R. \end{array}$$

Esercizio :



È una rete
due porte
per definizione

? Rapp. Param. Z.

$$\begin{cases} V_1(s) = \left(\frac{1}{sC} + R \right) I_1 + (2R + sL) (I_1 + I_2) \\ V_2(s) = (2R + sL) (I_1 + I_2) \end{cases}$$

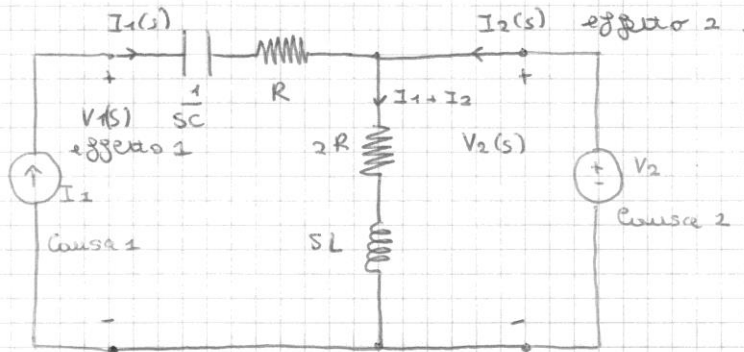
$$V_1(s) = \underbrace{\left(3R + sL + \frac{1}{sC} \right) I_1}_{Z_{11}(s)} + \underbrace{(2R + sL) I_2}_{Z_{12}(s)}$$

$$V_2(s) = \underbrace{(2R + sL) I_1}_{Z_{21}(s)} + \underbrace{(2R + sL) I_2}_{Z_{22}(s)}$$

mat. Z simmetrica

? Rapp. Param. R

Cause: I_1, V_2



$$\begin{cases} V_1(s) = \underbrace{\left(\frac{1}{SC} + R\right)}_{R_{11}} I_1 + \underbrace{1}_{R_{12}} \cdot V_2 \\ I_2(s) = \underbrace{-1}_{R_{21}} \cdot I_1 + \underbrace{\frac{1}{SL+2R}}_{R_{22}} \cdot V_2 \end{cases} \quad \begin{array}{l} \text{mat. R} \\ \text{antisimmetrica} \end{array}$$

Parametri Z (di circuito aperto)

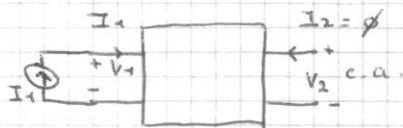
Cause: I_1, I_2 $\begin{cases} V_1 = Z_{11}(s) \cdot I_1 + Z_{12}(s) \cdot I_2 \\ V_2 = Z_{21}(s) \cdot I_1 + Z_{22}(s) \cdot I_2 \end{cases}$

Effetti: V_1, V_2

$$\begin{pmatrix} V_1 \\ V_2 \end{pmatrix} = \begin{pmatrix} Z_{11}(s) & Z_{12}(s) \\ Z_{21}(s) & Z_{22}(s) \end{pmatrix} \begin{pmatrix} I_1 \\ I_2 \end{pmatrix}$$

$$\vec{V} = \vec{Z}(s) \cdot \vec{I}$$

Definizione Operativa:



$$Z_{11} = \left. \frac{V_1}{I_1} \right|_{I_2 = \emptyset}$$

impedenza alla porta 1 con porta 2 a c.a.

$$Z_{22} = \left. \frac{V_2}{I_2} \right|_{I_1 = \emptyset}$$

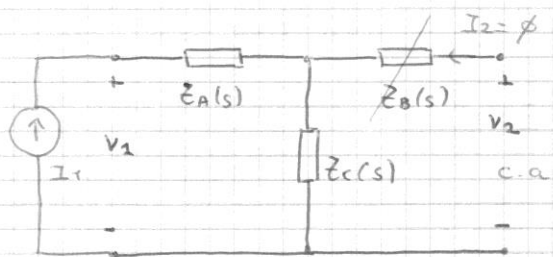
impedenza di trasferimento da porta 1 a porta 2 con porta 2 a c.a.



$$Z_{22} = \frac{V_2}{I_2} \Big|_{I_1 = \emptyset}$$

$$Z_{12} = \frac{V_1}{I_2} \Big|_{I_1 = \emptyset}$$

Impedanza a T



$$Z_{11}(s) = \frac{V_1}{I_1} \Big|_{I_2 = \emptyset}$$

$$Z_{21}(s) = \frac{V_2}{I_1} \Big|_{I_2 = \emptyset}$$

$$Z_{11}(s) = Z_A(s) + Z_C(s)$$

$$Z_{21}(s) = Z_C(s)$$

$$Z_{22}(s) = \frac{V_2}{I_2} \Big|_{I_1 = \emptyset} = Z_B(s) + Z_C(s)$$

$$Z_{12}(s) = \frac{V_1}{I_2} \Big|_{I_1 = \emptyset} = Z_C(s)$$

$$\Rightarrow \underline{\underline{Z}}_{TT} = \begin{pmatrix} Z_A + Z_C & Z_C \\ Z_C & Z_B + Z_C \end{pmatrix}$$

$$\underline{\underline{Z}}^t = \underline{\underline{Z}} : \text{simmetrica}$$

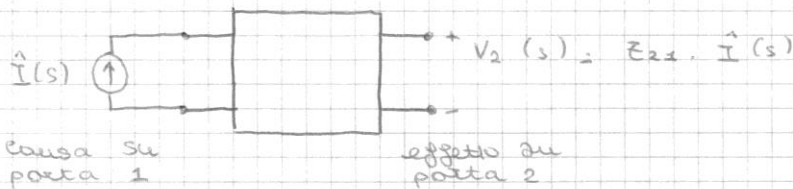
Da rete c.a. $\underline{\underline{Z}}$ simmetrica è una rete di tipo reciproco (ripetibile in parametri τ).

Proprietà:

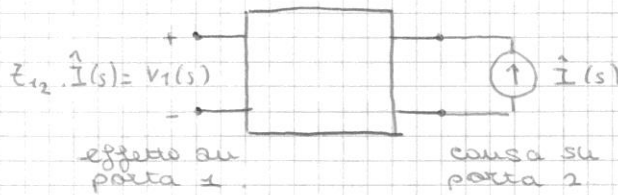
Una rete due porte che è costituita da soli elementi
è necessariamente RECIPROCA.

Rete Reciproca:

$$Z_{21} = \left. \frac{V_2}{I_1} \right|_{I_2 = \phi} = Z_{12} = \left. \frac{V_1}{I_2} \right|_{I_1 = \phi}$$



$$Z_{12} = Z_{21}$$

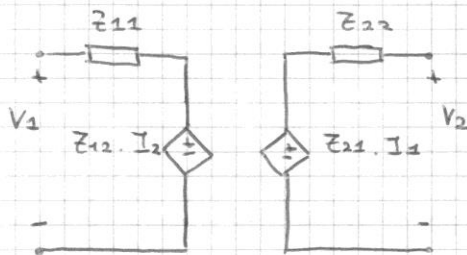


"In una rete reciproca l'effetto non cambia, scambiando fra di loro, posizione di causa ed effetto".

Circuiti Equivalenti a Parametri Z.

$$\begin{cases} V_1 = Z_{11} \cdot I_1 + Z_{12} \cdot I_2 \\ V_2 = Z_{21} \cdot I_1 + Z_{22} \cdot I_2 \end{cases}$$

↑
Relazioni costitutive.

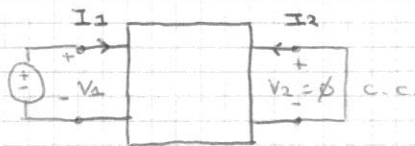


Parametri y (di corto circuito)

Cause: V_1, V_2

Effetti: I_1, I_2

$$\begin{cases} I_1 = y_{11} V_1 + y_{12} V_2 \\ I_2 = y_{21} V_1 + y_{22} V_2 \end{cases}$$



$$y_{11} = \frac{I_1}{V_1} \Big|_{V_2=0}$$

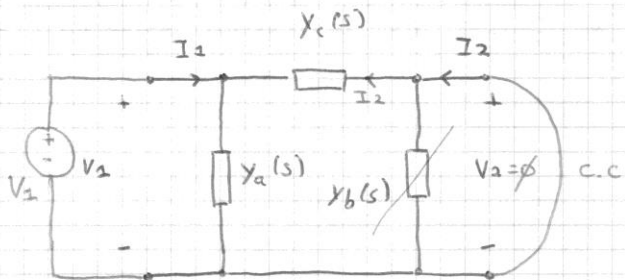
$$y_{21} = \frac{I_2}{V_1} \Big|_{V_2=0}$$

↑
ammittenza di trasferimento
da porta 1 a porta 2

$$y_{22} = \frac{I_2}{V_2} \Big|_{V_1=0}$$

$$y_{12} = \frac{I_1}{V_2} \Big|_{V_1=0}$$

Impedenze a "π" (Triangolo)



$$y_{11} = \frac{I_1}{V_1} \Big|_{V_2=0} = y_a + y_c$$

$$y_{21} = \frac{I_2}{V_1} \Big|_{V_2=0} = -y_c$$

$$\text{con } I_2 = -y_c \cdot V_1$$

Poi, invertendo:

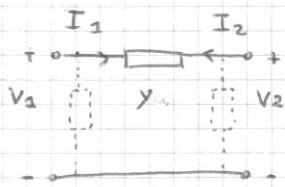
$$y_{22} = y_b + y_c$$

$$y_{12} = -y_c$$

$$\underline{\underline{Y}}_{\pi} = \begin{pmatrix} y_a + y_c & -y_c \\ -y_c & y_b + y_c \end{pmatrix}$$

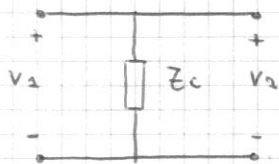
Reciproca $\Leftrightarrow \underline{\underline{Y}} = \underline{\underline{Y}}^t$

Dominate: $\underline{\underline{Z}} = \underline{\underline{Y}}^{-1}$



$I_1 = -I_2$, ~~$\underline{\underline{Z}}$~~ Parametri ~~$\underline{\underline{Z}}$~~
 I_1 e I_2 dip. ti

$$\exists \underline{\underline{Y}} = \begin{pmatrix} y_c & -y_c \\ -y_c & y_c \end{pmatrix}$$

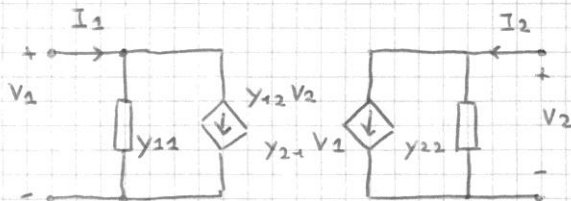


$\exists \underline{\underline{Z}}$, ~~$\underline{\underline{Y}}$~~ in quanto V_1 e V_2
dip. ti

Trasformatore Ideale

$$\begin{cases} V_1 = nV_2 \\ I_1 = -\frac{1}{n}I_2 \end{cases} \quad \text{ ~~$\underline{\underline{Z}}$~~ , ~~$\underline{\underline{Y}}$~~ in quanto V_1 e V_2
e I_1 e I_2 dip. ti.$$

Circuito Equivalente a Parametri y .



$$\begin{cases} I_1 = y_{11}V_1 + y_{12}V_2 \\ I_2 = y_{21}V_1 + y_{22}V_2 \end{cases}$$

Stabilità rispetto alla funzione di trasferimento $H(s)$

$$H(s) = \frac{N(s)}{D(s)}$$

Asintoticamente Stabile

\Leftrightarrow tutti i poli di $H(s)$ hanno $\text{Re} < 0$.

Stabilità Marginale

\Leftrightarrow tutti i poli di $H(s)$ hanno $\text{Re} \leq 0$ e quelli con $\text{Re} = 0$ sono semplici.

Instabile in tutti gli altri casi.

La stabilità è una proprietà intrinseca di tutti i circuiti passivi RLC.

Proprietà: Sia $H(s)$ una funzione di trasferimento di un circuito passivo RLC.

I poli di $H(s)$ possono essere dei seguenti tipi:

- 1) Poli a $\text{Re} < 0$ (anche multipli);
- 2) Poli a $\text{Re} = 0$ (necessariamente semplici)
- 3) Poli per $s \rightarrow \infty$ (necessariamente semplice)

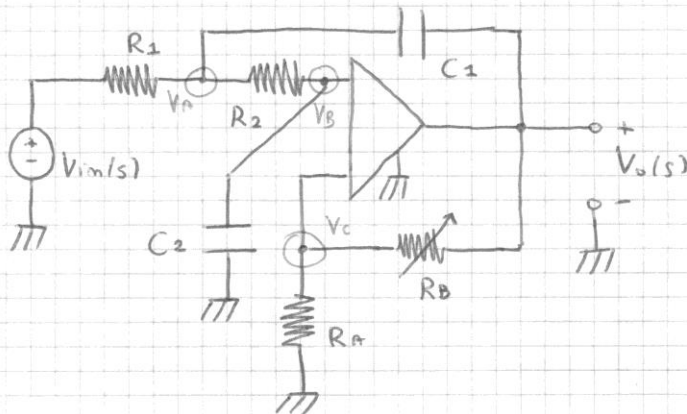
↑ esempio: $\frac{s^2}{s+1} \sim s$

Perché non si può essere un polo doppio in ∞ ?

Perché se mettiamo $z = \frac{1}{s}$, rispetto tutto su z (con L con C) ma non si può essere un polo doppio in 0 .

Per un circuito attivo la stabilità non è garantita a priori.

Fiebras de II° Ordeme com A.O.



$$? T_V(s) = \frac{V_o(s)}{V_{in}(s)}$$

$$K = 1 + \frac{R_B}{R_A}$$

$$H(s) = \frac{K \frac{1}{R_1 R_2 C_1 C_2}}{s^2 + s \left(\frac{1}{R_1 C_1} + \frac{1}{R_2 C_1} + \frac{1}{R_2 C_2} - K \frac{1}{R_2 C_2} \right) + \frac{1}{R_1 R_2 C_1 C_2}}$$

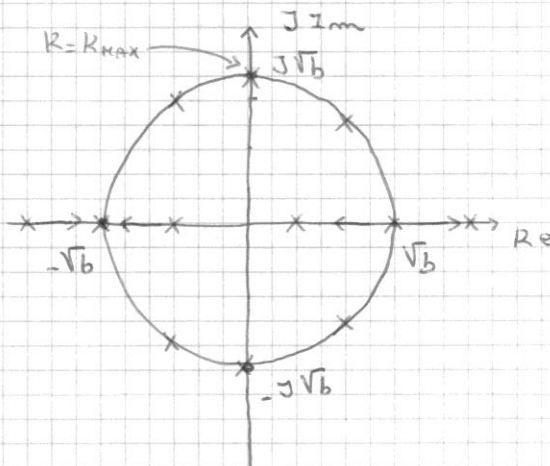
$$K_{MAX} = \frac{\frac{1}{R_1 C_1} + \frac{1}{R_2 C_1} + \frac{1}{R_2 C_2}}{\frac{1}{R_2 C_2}}$$

$R < K_{MAX}$: 2 Poles a $Re < 0$ Asint. Stab.

$R = K_{MAX}$: 2 Poles a $Re = 0$ sempleis Marg. Stab.

$R > K_{MAX}$: 2 Poles a $Re > 0$ Instab.

$$b = \frac{1}{R_1 R_2 C_1 C_2}$$



$$V_B = V_0 \cdot \frac{R_A}{R_A + R_B} = \frac{V_0}{K}$$

$$V_B = V_A \cdot \frac{1}{sC_2} = \frac{V_A}{1 + sR_2C_2}$$

$$V_A = V_B (1 + sR_2C_2) = (1 + sR_2C_2) \frac{V_0}{K}$$

$$\frac{V_A - V_{im}}{R_1} + \frac{V_A - V_B}{R_2} + (V_A - V_0) sC_1 = 0$$

$$V_A \left(\frac{1}{R_1} + \frac{1}{R_2} + sC_1 \right) - \frac{V_B}{R_2} - V_0 sC_1 = \frac{V_{im}}{R_1}$$

$$(1 + sR_2C_2) \left(\frac{1}{R_1} + \frac{1}{R_2} + sC_1 \right) \frac{V_0}{K} - \frac{V_0}{KR_2} - V_0 sC_1 = \frac{V_{im}}{R_1}$$

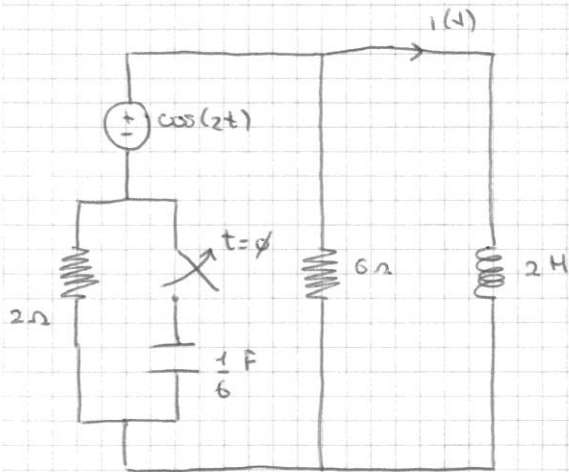
$$V_0 \left[s^2 R_2 C_1 C_2 + s R_2 C_2 \left(\frac{1}{R_1} + \frac{1}{R_2} \right) + \frac{1}{R_1} + \frac{1}{R_2} + sC_1 - \frac{1}{R_2} - K s C_1 \right] = K \frac{V_{im}}{R_1}$$

$$\frac{V_0}{V_{im}} = \frac{\frac{K}{R_1}}{s^2 R_2 C_1 C_2 + s \left(R_2 C_2 \left(\frac{1}{R_1} + \frac{1}{R_2} \right) + C_1 - K C_1 \right) + \frac{1}{R_1}}$$

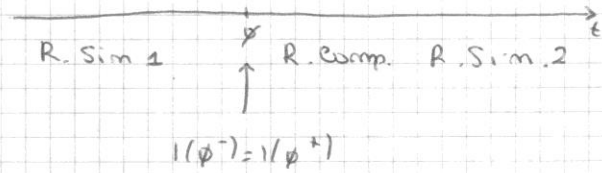
$$\frac{V_0}{V_{im}} = \frac{K}{R_1 R_2 C_1 C_2} \cdot \frac{1}{s^2 + s \left(\frac{1}{R_1 C_1} + \frac{1}{R_2 C_1} + \frac{1}{R_2 C_2} - \frac{K}{R_2 C_2} \right) + \frac{1}{R_1 R_2 C_1 C_2}}$$

$$\frac{V_0}{V_{im}} = \frac{R}{s^2 + as + b}$$

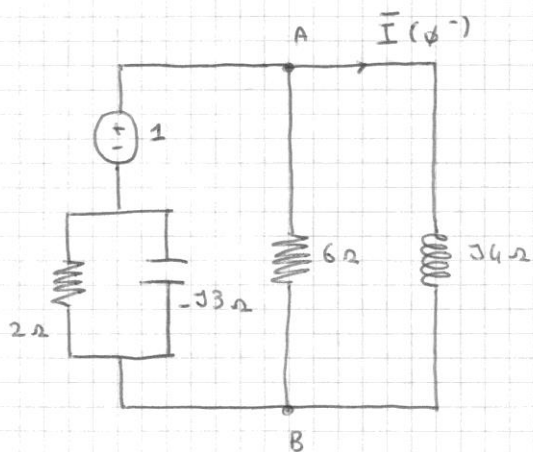
ES. 15/01/2009



Determine $i(t)$, $t \geq \phi$.



$t = \phi^-$



MILLMANN:

$$V_{AB} = \frac{1 \cdot \frac{1}{2 \parallel -j3}}{\frac{1}{2 \parallel -j3} + \frac{1}{6} + \frac{1}{j4}}$$

$$2 \parallel -j3 = \frac{-2 \cdot j3}{2 - j3}$$

$$= \frac{-j6}{2 - j3} \cdot \frac{2 + j3}{2 + j3} = \frac{18 - j12}{13}$$

$$V_{AB} = \frac{\frac{13}{18 - j12}}{\frac{13}{18 - j12} + \frac{1}{6} + \frac{1}{j4}}$$

29/05/2015

Parametri Ibridi R

Cause : I_1, V_2

Effetti : V_1, I_2

$$\begin{cases} V_1 = R_{11} I_1 + R_{12} V_2 \\ I_2 = R_{21} I_1 + R_{22} V_2 \end{cases}$$

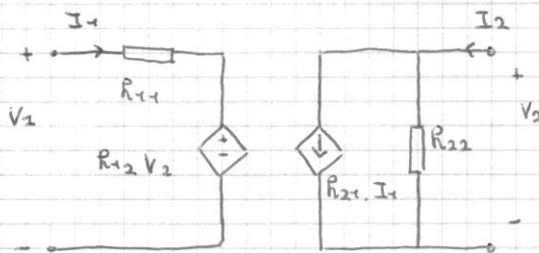
$$R_{11} = \left. \frac{V_1}{I_1} \right|_{V_2=0} = \left. \frac{1}{\frac{I_1}{V_1}} \right|_{V_2=0} = \frac{1}{y_{11}}$$

$$R_{21} = \left. \frac{I_2}{I_1} \right|_{V_2=0} = \left. \frac{I_2}{V_1} \cdot \frac{V_1}{I_1} \right|_{V_2=0} = \frac{y_{21}}{y_{11}} \quad : \text{funzione di trasferimento in corrente}$$

$$R_{22} = \left. \frac{I_2}{V_2} \right|_{I_1=0} = \left. \frac{1}{\frac{V_2}{I_2}} \right|_{I_1=0} = \frac{1}{z_{22}}$$

$$R_{12} = \left. \frac{V_1}{V_2} \right|_{I_1=0} = \left. \frac{V_1}{I_2} \cdot \frac{I_2}{V_2} \right|_{I_1=0} = \frac{z_{12}}{z_{22}} \quad : \text{funzione di trasferimento in tensione}$$

Circuito Equivalente a Parametri R.



Reciprocità $\Leftrightarrow R_{12} = -R_{21}$

Determinare \vec{R} in funzione di \vec{z} e verificare che, in termini di R, la reciprocità equivale a

$$R_{12} = -R_{21}$$

$$\vec{z} = \begin{cases} V_1 = z_{11} I_1 + z_{12} I_2 \\ V_2 = z_{21} I_1 + z_{22} I_2 \end{cases} \rightarrow I_2 = \underbrace{-\frac{z_{21}}{z_{22}} I_1}_{R_{21}} + \underbrace{\frac{1}{z_{22}} V_2}_{R_{22}}$$

$$\vec{R} = \begin{cases} V_1 = R_{11} I_1 + R_{12} V_2 \\ I_2 = R_{21} I_1 + R_{22} V_2 \end{cases}$$

$$V_1 = Z_{11} I_1 - \frac{Z_{12} Z_{21}}{Z_{22}} I_1 + \frac{Z_{12}}{Z_{22}} V_2$$

$$\Rightarrow R = \frac{1}{Z_{22}} \begin{pmatrix} \det \vec{Z} & Z_{12} \\ -Z_{21} & 1 \end{pmatrix}$$

rete reciproca: $Z_{12} = Z_{21} \Rightarrow R_{12} = -R_{21}$

Parametri di Trasmissione (Diretta)

Cause: $V_2, -I_2$

Effetti: V_1, I_1

$$\begin{cases} V_1 = A V_2 + B (-I_2) \\ I_1 = C V_2 + D (-I_2) \end{cases}$$

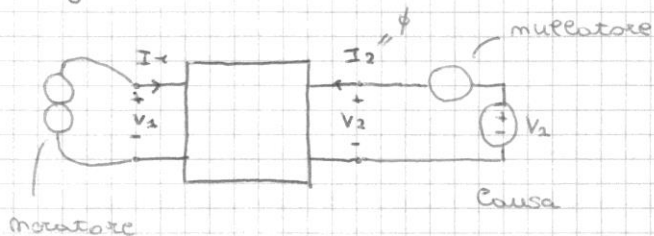
Matrice di Trasmissione: $\vec{T} = \begin{pmatrix} A & B \\ C & D \end{pmatrix}$

Diretta

$A = \frac{V_1}{V_2} \Big|_{I_2 = \emptyset}$: funzione di trasferimento in tensione da P_2 a P_1 .

$C = \frac{I_1}{V_2} \Big|_{I_2 = \emptyset}$: ammettenza " " da P_2 a P_1

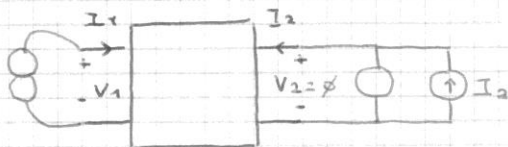
Def. Operativa:



$$B = \left. \frac{V_1}{-I_2} \right|_{V_2 = \phi} : \text{Impedenza di trasferimento}$$

$$D = \left. \frac{I_1}{-I_2} \right|_{V_2 = \phi} : \text{funz. di trasferimento in corrente}$$

Def. Operativa



Reciprocità : $\det \vec{T} = AD - BC = 1.$

? \vec{Z} in funzione di \vec{T}

$$\begin{cases} V_1 = AV_2 + B(-I_2) \\ I_1 = CV_2 + D(-I_2) \end{cases} \rightarrow V_2 = \frac{1}{C} I_1 + \frac{D}{C} I_2$$

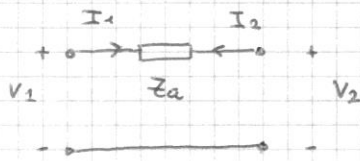
$$\begin{cases} V_1 = z_{11} I_1 + z_{12} I_2 \\ V_2 = z_{21} I_1 + z_{22} I_2 \end{cases}$$

$$V_1 = \frac{A}{C} I_1 + \frac{AD}{C} I_2 - B I_2$$

$$\vec{Z} = \frac{1}{C} \begin{pmatrix} \frac{A}{C} & \det \vec{T} \\ 1 & D \end{pmatrix}$$

Reciprocità : $z_{12} = z_{21} \Rightarrow \det \vec{T} = 1.$

Esercizio Teorico

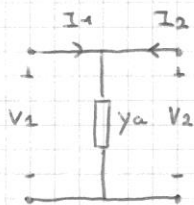


$$\vec{T} = \begin{pmatrix} 1 & Z_a \\ \emptyset & 1 \end{pmatrix}$$

$$V_2 = Z_a \cdot I_1 + V_2$$

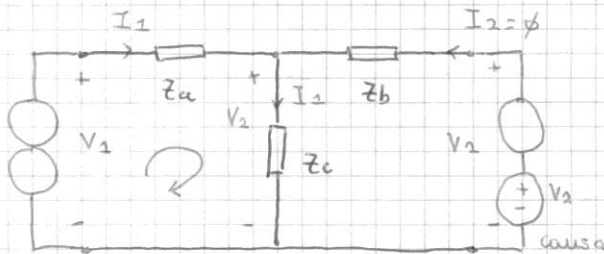
$$\begin{cases} V_1 = 1 \cdot V_2 + Z_a(-I_2) \\ I_1 = \emptyset \cdot V_2 + 1(-I_2) \end{cases} \quad \text{OK!}$$

Per l'uso:



verificare che $\vec{T} = \begin{pmatrix} 1 & \emptyset \\ y_a & 1 \end{pmatrix}$

Esercizio Teorico:



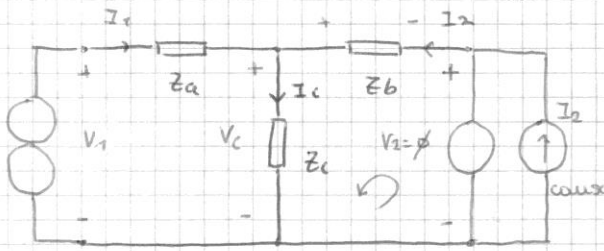
? ABCD con la def.

$$A = \frac{V_1}{V_2} \Big|_{I_2 = \emptyset} = 1 + \frac{Z_a}{Z_c}$$

$$C = \frac{I_1}{V_2} \Big|_{I_2 = \emptyset} = \frac{1}{Z_c}$$

$$I_1 = \frac{V_2}{Z_c}$$

$$V_1 = Z_a \cdot I_1 + V_2 = Z_a \cdot \frac{V_2}{Z_c} + V_2$$



$$B = \frac{V_1}{-I_2} \Big|_{V_2 = \emptyset} = Z_a + Z_b + \frac{Z_a Z_b}{Z_c}$$

$$D = \frac{I_1}{-I_2} \Big|_{V_2 = \emptyset} = 1 + \frac{Z_b}{Z_c}$$

$$V_c = -Z_b \cdot I_2$$

$$I_c = \frac{V_c}{Z_c} = -\frac{Z_b}{Z_c} \cdot I_2$$

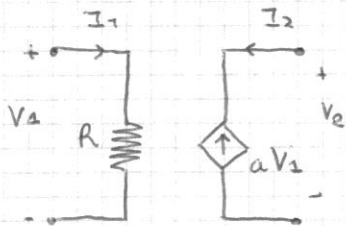
$$I_1 = I_c \cdot I_2 = \left(1 + \frac{Z_b}{Z_c} \right) (-I_2)$$

$$V_2 = Z_a \cdot I_1 - Z_b \cdot I_2 = Z_a \left(1 + \frac{Z_b}{Z_c} \right) (-I_2) - Z_b I_2$$

$$\vec{T} = \begin{pmatrix} 1 + \frac{Z_a}{Z_c} & Z_a + Z_b + \frac{Z_a Z_b}{Z_c} \\ \frac{1}{Z_c} & 1 + \frac{Z_b}{Z_c} \end{pmatrix}$$

$$\det \vec{T} = 1, \text{ OK!}$$

14/09/1998



$a \neq \phi$

? z, y, R, g, ABCD

N.B. gen. re controllato è una rete due porte.

$$\begin{cases} V_1 = R \cdot i_1 \\ i_2 = -a V_1 = -a R i_1 \end{cases}$$

i_1, i_2 sono dip. $i_1 \Rightarrow \cancel{z}$

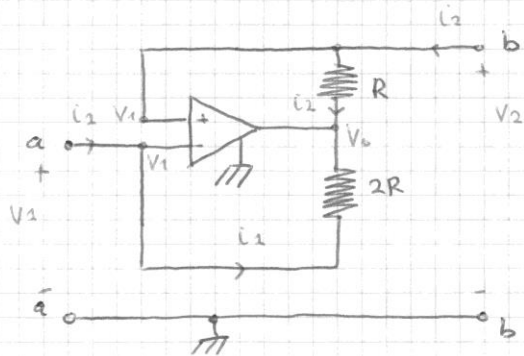
V_1, i_2 sono dip. $i_1 \Rightarrow \cancel{g}$

$$\exists \vec{y} \begin{cases} i_2 = \frac{1}{R} V_1 + \phi \cdot V_2 \\ i_2 = -a V_1 - \phi \cdot V_2 \end{cases} \quad \vec{y} = \begin{pmatrix} 1/R & \phi \\ -a & \phi \end{pmatrix}$$

$$\exists \vec{R} \begin{cases} V_1 = R (i_1 + \phi V_2) \\ i_2 = -a R i_1 + \phi V_2 \end{cases} \quad \vec{R} = \begin{pmatrix} R & \phi \\ -a R & \phi \end{pmatrix}$$

$$\exists \text{ ABCD} \begin{cases} V_1 = \phi \cdot V_2 + \frac{1}{a} (-i_2) \\ i_1 = \phi \cdot V_2 + \frac{1}{a R} (-i_2) \end{cases} \quad \vec{T} = \begin{pmatrix} \phi & 1/a \\ \phi & 1/a R \end{pmatrix}$$

31/10/2001



? z, y, ABCD.

$$V_1 = V_2$$

$$V_1, V_2 \text{ dip. ti} \Rightarrow \vec{z} \vec{y}$$

$$V_1 = 2Ri_1 + V_0$$

$$V_2 = Ri_2 + V_0$$

$$V_1 = V_2 \rightarrow 2Ri_1 + V_0 = Ri_2 + V_0$$

$$i_2 = 2i_1$$

$$i_1, i_2 \text{ dip. ti} \Rightarrow \vec{z} \vec{z}$$

$$\begin{cases} V_1 = V_2 \\ i_1 = \frac{1}{2} i_2 \end{cases}$$

$$\vec{T} = \begin{pmatrix} 1 & \emptyset \\ \emptyset & -\frac{1}{2} \end{pmatrix}$$

$\det \vec{T} \neq 1$: Rete non reciproca.

INIC

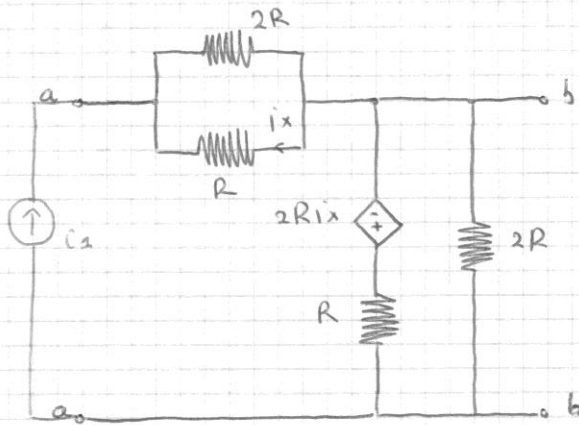
$$\begin{cases} V_1 = K_1 V_2 \\ i_1 = K_2 i_2 \end{cases} \quad K_1, K_2 > \emptyset$$

$$\begin{cases} V_1 = V_2 \\ i_1 = i_2 \end{cases}$$

Invertitore di
Corrente

Remde una resistenza $R < \emptyset$.

ES. 29/03/2006



? $Z_{11}, Z_{21}, R_{11}, R_{21}$
com as def.

$$i_x = -\frac{2}{3} i_1$$

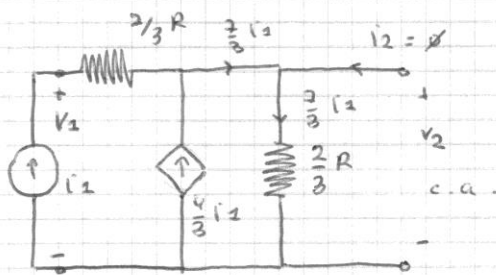
$$Z_{11} = \frac{V_1}{i_1} \Big|_{i_2 = \phi}$$

$$Z_{21} = \frac{V_2}{i_1} \Big|_{i_2 = \phi}$$

$$R_{11} = \frac{V_1}{i_1} \Big|_{v_2 = \phi}$$

$$R_{21} = \frac{i_2}{i_1} \Big|_{v_2 = \phi}$$

Causa sempre i_1 .

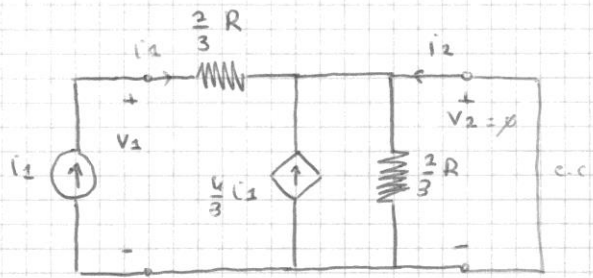


Parâmetros Z .

$$Z_{11} = \frac{V_1}{i_1} \Big|_{i_2 = \phi} = \frac{20}{9} R$$

$$Z_{21} = \frac{V_2}{i_1} \Big|_{i_2 = \phi} = \frac{16}{9} R$$

$$V_2 = \frac{2}{3} R \cdot i_2 + \frac{2}{3} R \cdot \frac{1}{3} i_2 = \frac{20}{9} R \cdot i_2$$



Parametri R

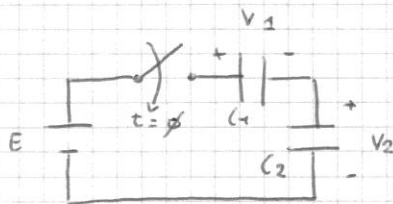
$$R_{11} = \left. \frac{V_1}{i_1} \right|_{V_2 = \phi} = \frac{2}{3} R$$

$$R_{21} = \left. \frac{i_2}{i_1} \right|_{V_2 = \phi} = -\frac{2}{3}$$

$$i_1 + \frac{4}{3} i_1 + i_2 = \phi$$

PARTE 2

Rete Degenera



$$V_1(\phi^-) = V_2(\phi^-) = \phi$$

$$? V_1(\phi^+), V_2(\phi^+)$$

Rete Degenera con presenza di C
 \Rightarrow discontinuita' var. di stato

$$V_1(\phi^+) + V_2(\phi^+) = E$$

$$i_1(t) = i_2(t) \quad t \in [\phi^-, \phi^+]$$

$$i_1 = C_1 \cdot \frac{d}{dt} V_1(t) = i_2 = C_2 \cdot \frac{d}{dt} V_2(t)$$

$$C_1 \int_{\phi^-}^{\phi^+} \frac{d}{dt} V_1(t) dt = C_2 \int_{\phi^-}^{\phi^+} \frac{d}{dt} V_2(t) dt$$

$$C_1 (V_1(\phi^+) - V_1(\phi^-)) = C_2 (V_2(\phi^+) - V_2(\phi^-))$$

$$V_1(\phi^-) = V_2(\phi^-) = \phi \quad \text{ipotesi iniziale}$$

$$C_1 V_1(\phi^+) = C_2 V_2(\phi^+)$$

$$\begin{cases} V_1(\phi^+) + V_2(\phi^+) = E \\ C_1 V_1(\phi^+) = C_2 V_2(\phi^+) \end{cases}$$

$$\frac{C_2}{C_1} V_2(\phi^+) + V_2(\phi^+) = E$$

$$V_2(\phi^+) = \frac{E}{1 + \frac{C_2}{C_1}} = \frac{E C_1}{C_1 + C_2}$$

$$V_1(\phi^+) = \frac{E C_2}{C_1 + C_2}$$

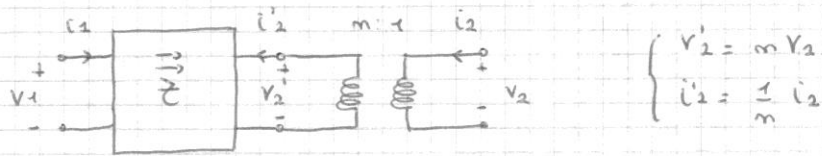
N.B.: In questo circuito Tellegen non torna.

Potenza erogata da gen. \neq doppia di energia accumulata dai C.

Causa fenomeni di samplizzazione

03/06/2015

Interconnessione di reti due Porte



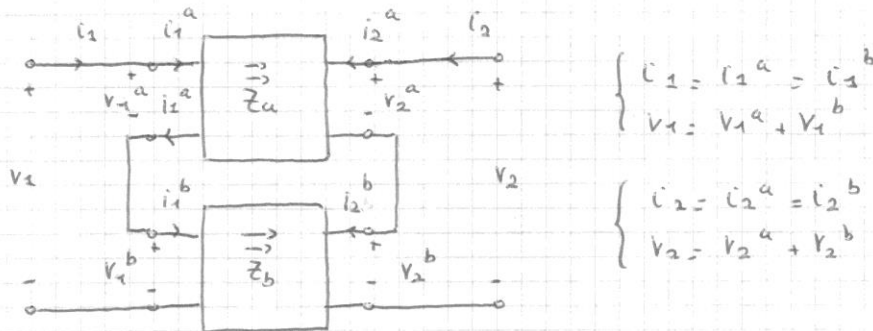
$$\vec{Z} = \begin{pmatrix} Z_{11} & \frac{Z_{12}}{m} \\ \frac{Z_{21}}{m} & \frac{Z_{22}}{m^2} \end{pmatrix}$$

$$Z_{11} = \frac{V_1}{i_1} \Big|_{i_2 = \emptyset} = \frac{V_1}{i_1} \Big|_{i_2 = \emptyset} \quad Z_{11} \text{ non cambia}$$

$$Z_{21} = \frac{V_2}{i_1} \Big|_{i_2 = \emptyset} = \frac{1}{m} \frac{V_2'}{i_1} = \frac{Z_{21}}{m}$$

Da verificare se valgono due relazioni.

Connessione in serie fra reti due Porte



$$\begin{cases} i_1 = i_1^a = i_1^b \\ V_1 = V_1^a + V_1^b \end{cases}$$

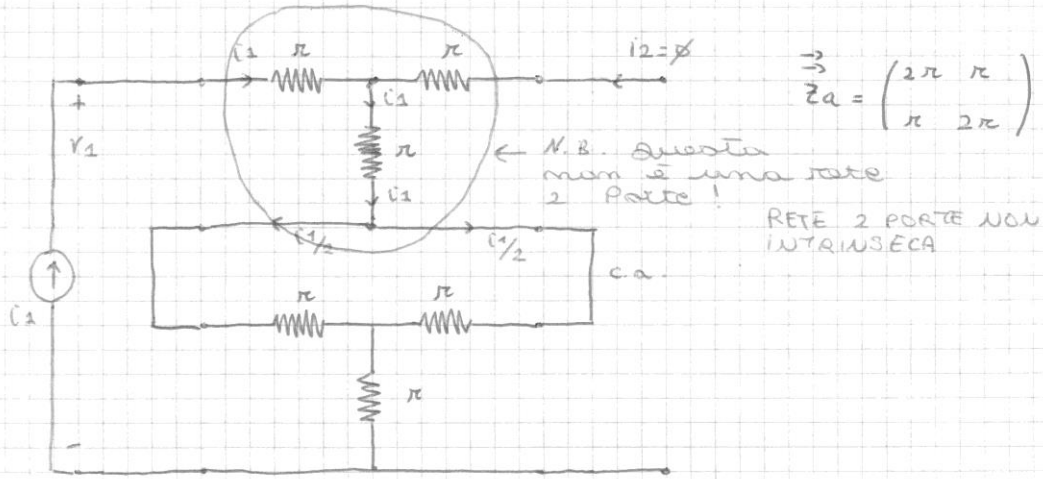
$$\begin{cases} i_2 = i_2^a = i_2^b \\ V_2 = V_2^a + V_2^b \end{cases}$$

$$\vec{Z} = \vec{Z}_a + \vec{Z}_b \quad \text{D.M.} \quad \downarrow$$

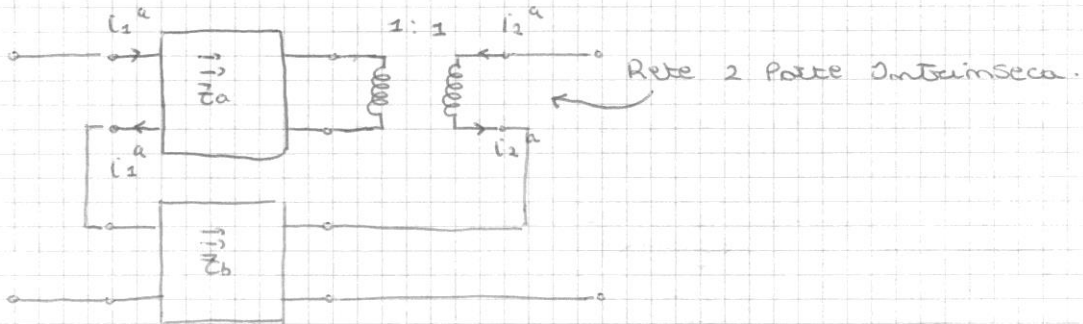
$$\begin{aligned} V_1 &= V_1^a + V_1^b = Z_{11}^a \cdot i_1^a + Z_{12}^a \cdot i_2^a + Z_{11}^b \cdot i_1^b + Z_{12}^b \cdot i_2^b \\ &= \underbrace{(Z_{11}^a + Z_{11}^b)}_{Z_{11}} i_1 + \underbrace{(Z_{12}^a + Z_{12}^b)}_{Z_{12}} i_2 \end{aligned}$$

Stessa cosa per V_2 .

ESERCIZIO TEORICO

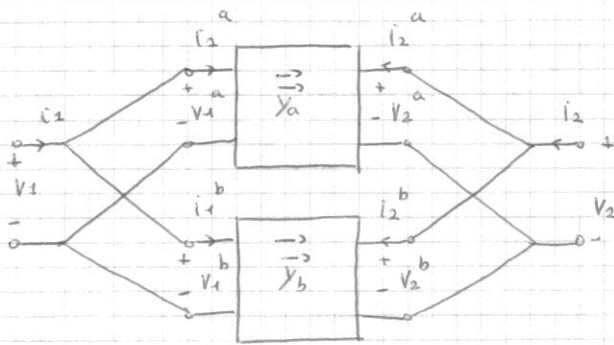


$Z_{11} = \frac{7}{2} r$ ed invece dovrebbe venire $2r$.



↑
 Collegamento Serie Valori: $\vec{Z} = \vec{Z}_a + \vec{Z}_b$

Collegamento in Parallelo fra reti 2 Porte



$$\begin{cases} V_1 = V_1^a = V_1^b \\ i_1 = i_1^a + i_1^b \\ V_2 = V_2^a = V_2^b \\ i_2 = i_2^a + i_2^b \end{cases}$$

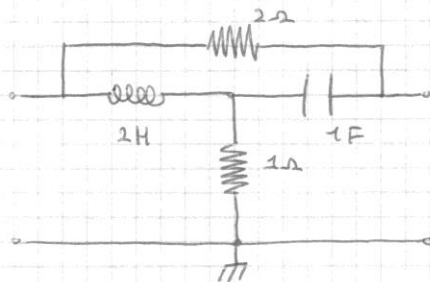
$$i_2 = i_2^a + i_2^b = Y_{21}^a \cdot V_1^a + Y_{22}^a \cdot V_2^a + Y_{21}^b \cdot V_1^b + Y_{22}^b \cdot V_2^b$$

$$= (Y_{21}^a + Y_{21}^b) V_1 + (Y_{22}^a + Y_{22}^b) V_2$$

$$\underbrace{\hspace{10em}}_{Y_{21}} \qquad \underbrace{\hspace{10em}}_{Y_{22}}$$

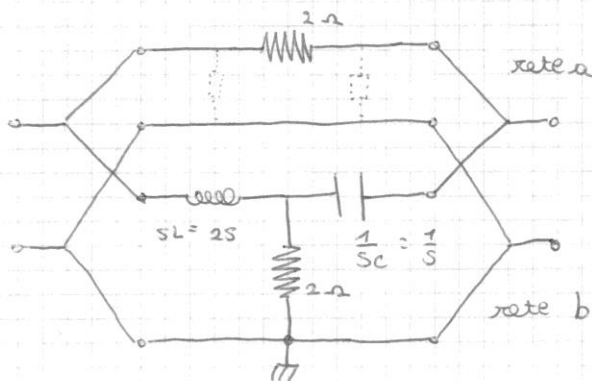
$$\vec{Y} = \vec{Y}_a + \vec{Y}_b$$

ESERCIZIO TEORICO



? \vec{Y} Rete due porte

Risolvere con Laplace sommandole in due reti in parallelo.

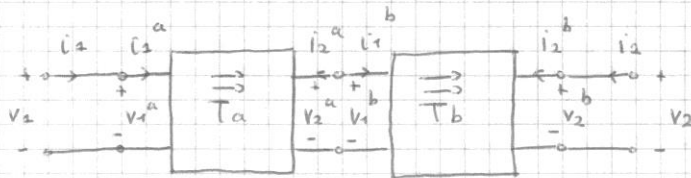


$$\vec{Y} = \vec{Y}_a + \vec{Y}_b$$

$$\vec{y}_a = \begin{pmatrix} -1/2 & -1/2 \\ -1/2 & 1/2 \end{pmatrix}$$

$$\vec{z}_b = \begin{pmatrix} 2s+1 & 1 \\ 1 & \frac{1}{s}+1 \end{pmatrix} \quad \vec{y}_b = \vec{z}_b^{-1} = \frac{\begin{pmatrix} \frac{1}{s}+1 & -1 \\ -1 & 2s+1 \end{pmatrix}}{\det \vec{z}_b}$$

Collegamento in cascata fra due porte

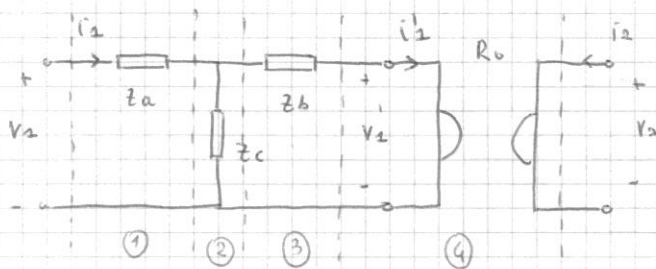


$$\vec{T} = \vec{T}_a \cdot \vec{T}_b$$

$$\begin{cases} V_1 = V_1^a \\ I_1 = I_1^a \end{cases} \quad \begin{cases} V_2^a = V_1^b \\ I_2^a = -I_1^b \end{cases} \quad \begin{cases} V_2 = V_2^b \\ I_2 = I_2^b \end{cases}$$

$$\begin{aligned} \begin{pmatrix} V_1 \\ I_1 \end{pmatrix} &= \begin{pmatrix} V_1^a \\ I_1^a \end{pmatrix} = \vec{T}_a \begin{pmatrix} V_2^a \\ -I_2^a \end{pmatrix} = \vec{T}_a \begin{pmatrix} V_1^b \\ I_2^b \end{pmatrix} = \vec{T}_a \cdot \vec{T}_b \begin{pmatrix} V_2^b \\ -I_2^b \end{pmatrix} \\ &= \underbrace{\vec{T}_a \cdot \vec{T}_b}_{\vec{T}} \begin{pmatrix} V_2 \\ -I_2 \end{pmatrix} \end{aligned}$$

ESERCIZIO TEORICO



$$\vec{T} = ((\vec{T}_1 \cdot \vec{T}_2) \cdot \vec{T}_3) \cdot \vec{T}_4$$

$$\vec{T}_1 = \begin{pmatrix} 1 & z_a \\ \emptyset & 1 \end{pmatrix}$$

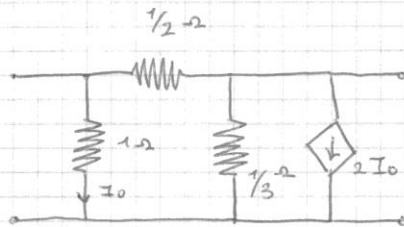
$$\vec{T}_3 = \begin{pmatrix} 1 & z_b \\ \emptyset & 1 \end{pmatrix}$$

$$\vec{T}_2 = \begin{pmatrix} 1 & \emptyset \\ \frac{1}{z_c} & 1 \end{pmatrix}$$

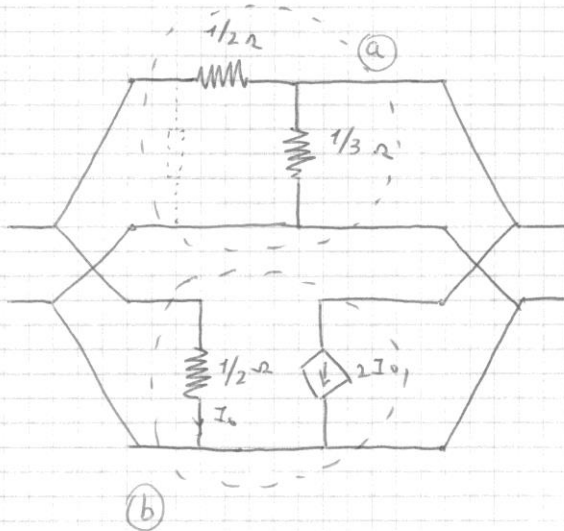
$$\begin{cases} V_1' = -R_0 i_2 \\ V_2 = R_0 i_1' \end{cases} \quad \begin{cases} V_1' = R_0 (-i_2) \\ i_1' = \frac{1}{R_0} V_2 \end{cases}$$

$$\vec{T}_4 = \begin{pmatrix} \emptyset & R_0 \\ \frac{1}{R_0} & \emptyset \end{pmatrix} \leftarrow \text{Rete Antirreciproca}$$

ES.



? \vec{Y} della rete due porte
pensando la rete
come parallelo fra
due sottoreti.



$$\vec{Y} = \vec{Y}_a + \vec{Y}_b$$

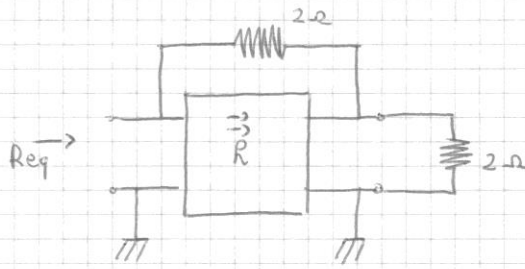
$$\vec{Y}_a = \begin{pmatrix} 2 & -2 \\ -2 & 5 \end{pmatrix}$$

$$\vec{Y}_b = \begin{pmatrix} 1 & \emptyset \\ 2 & \emptyset \end{pmatrix}$$

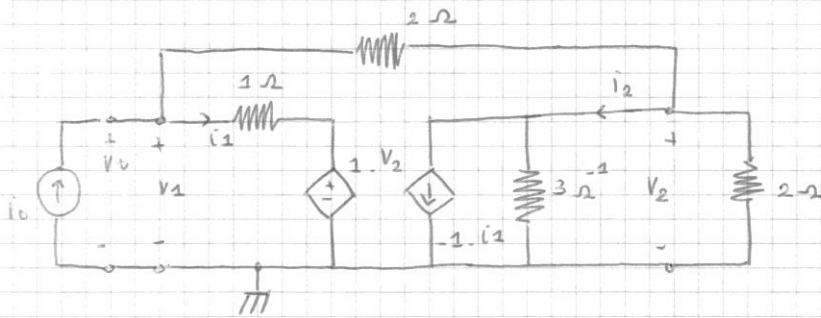
$$\vec{Y} = \begin{pmatrix} 3 & -2 \\ \emptyset & 5 \end{pmatrix}$$

ES.

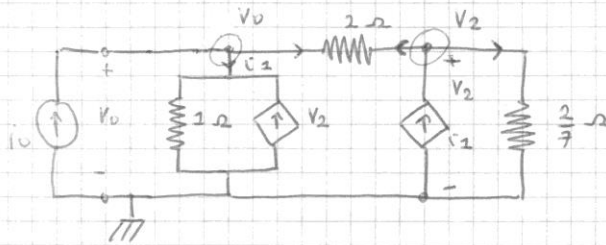
2. Req



$$\vec{h} = \begin{pmatrix} 1 & 1 \\ -1 & 3 \end{pmatrix}$$



$$R_{eq} = \frac{V_0}{i_0}$$



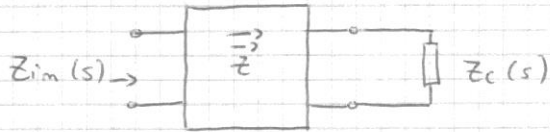
$$\begin{cases} i_0 = i_1 + \frac{V_0 - V_2}{2} \\ i_1 = V_2 \cdot \frac{7}{2} + \frac{V_2 - V_0}{2} \end{cases}$$

$$i_1 = V_0 - 1 \cdot V_2$$

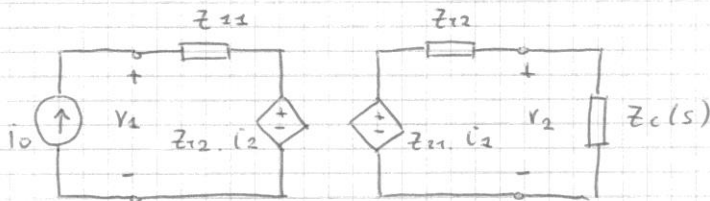
$$\dots \frac{V_0}{i_0} = \frac{10}{21} \Omega$$

ES.

? $Z_{im}(s)$



$$\vec{Z} = \begin{pmatrix} z_{11} & z_{12} \\ z_{21} & z_{22} \end{pmatrix} \quad \begin{cases} V_1 = z_{11} \cdot i_1 + z_{12} \cdot i_2 \\ V_2 = z_{21} \cdot i_1 + z_{22} \cdot i_2 \end{cases}$$



$$Z_{im}(s) = \frac{V_1}{i_0}$$

$$i_1 = i_0$$

$$i_2 = - \frac{z_{21} \cdot i_0}{z_{22} + Z_c}$$

$$V_1 = z_{12} \cdot i_2 + z_{11} \cdot i_1 = - \frac{z_{12} z_{21} i_0}{z_{22} + Z_c} + z_{11} \cdot i_0$$

$$Z_{im} = \frac{V_1}{i_0} = z_{11} - \frac{z_{12} \cdot z_{21}}{z_{22} + Z_c}$$